HITACHI PROGRAMMABLE AUTOMATION CONTROLLER


## APPLICATION MANUAL (Hardware) (SERVICE MANUAL)

## O Warranty period and coverage

The warranty period is the shorter period either 18 months from the date of manufacture or 12 months from the date of installation.
However even within the warranty period, the warranty will be void if the fault is due to;
(1) Incorrect use as directed in this manual and / or in the application manual.
(2) Malfunction or failure caused by external device.
(3) Attempted repair by unauthorized personnel.
(4) Other force majeure, such as natural disasters, which beyond the responsibility of manufacturer.

The warranty is for the PAC only, any damage caused to third party equipment by malfunction of the PAC is not covered by the warranty.

## O Repair

Any investigation or repair after the warranty period cannot be covered as free of charge. Also any faults caused by above (1) to (4), will be charged for its repair (or for its investigation), even if the product is within the warranty period. In case of any contact, please ask your supplier or local Hitachi distributor. (Depending on failure part, investigation may not be possible to apply)

## O Ordering parts or asking questions

In case of repair, replacement parts ordering, or any other inquiries, please have the following details ready before contacting the place of purchase.
(1) Model
(2) Manufacturing number (MFG.NO.)
(3) Details of the malfunction

## O Reader of this manual

This manual is described for the following person.

- Person considering to install PAC
- PAC system engineer
- Person handling PAC
- Person who maintain the installed PAC


## Warning

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(2) The content of this document may be changed without notice.
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Company name or a product name is trademark or a registered trademark.

## Safety Precautions

Read this manual and related documents thoroughly before installing, operating, performing preventive maintenance or performing inspection, and be sure to use the unit correctly. Use this product after acquiring adequate knowledge of the unit, all safety information, and all cautionary information. Also, make sure this manual enters the possession of the chief person in charge of safety maintenance.

Safety caution items are classifies as "Danger" and "Caution" in this document.

Cases where if handled incorrectly a dangerous circumstance may be created, resulting in possible death or severe injury.

Cases where if handled incorrectly a dangerous circumstance may be created, resulting in possible minor to medium injury to the body, or only mechanical damage

However, depending on the circumstances, items marked with

may result in major accidents. In any case, they both contain important information, so please follow them closely.

Icons for prohibited items and required items are shown below:
: Indicates prohibited items (items that may not be performed). For example, when open flames are prohibited, is shown.
( Indicates required items (items that must be performed). For example, when grounding must be performed,
$\xrightarrow{-}$ is shown.

## 1. About installation

## $\triangle$ CAUTION

- Use this product in an environment as described in the catalog and this document. If this product is used in an environment subject to high temperature, high humidity, excessive dust, corrosive gases, vibration or shock, it may result in electric shock, fire or malfunction.
- Perform installation according to this manual.

If installation is not performed adequately, it may result in dropping, malfunction or an operational error in the unit.

- Do not allow foreign objects such as wire chips to enter the unit.

They may become the cause of fire, malfunction or failure.

## 2. About wiring

## ( $\boldsymbol{\sigma}$ REQUIRED

- Always perform grounding (FE terminal).

If grounding is not performed, there is a risk of electric shocks and malfunctions.

## © CAUTION

- Connect power supply that meets rating.

If a power supply that does not meet rating is connected, fire may be caused.

- The wiring operation should be performed by a qualified personnel.

If wiring is performed incorrectly, it may result in fire, damage, or electric shock.

## 3. Precautions when using the unit

## DANGER

Do not touch the terminals while the power is on.
There is a risk of electric shock.

- Structure the emergency stop circuit, interlock circuit, etc. outside the programmable automation controller (hereinafter referred to as PAC).
Damage to the equipment or accidents may occur due to failure of the PAC.
However, do not interlock the unit to external load via relay drive power supply of the relay output module.


## $\triangle$ CAUTION

- When performing program change, forced output, RUN, STOP, etc., while the unit is running, be sure to verify safety.
Damage to the equipment or accidents may occur due to operation error.
- Supply power according to the power-up order.

Damage to the equipment or accidents may occur due to malfunctions.

## $\triangle$ CAUTION

- Use power supply unit of EH series or HX series for supplying electric power.


## . CAUTION

- Do not connect DC power supply module EH-PSD to a master power circuit. Supply a power to EH-PSD through an appropriate isolation transformer less than up to 150 VA by all means.


## 4. About preventive maintenance

## (1) DANGER

- Do not connect the + , of the battery in reverse. Also, do not charge, disassemble, heat, place in fire, or short circuit the battery.
There is a risk of explosion or fire.


## PROHIBITED

- Do not disassemble or modify the unit.

Electric shock, malfunction or failure may result.

## CAUTION

- Turn off the power supply before removing or attaching module/unit.

Electric shock, malfunction or failure may result.

## Revision History

| No. | Description of revision | Date of <br> revision | Manual number |
| :---: | :---: | :---: | :---: |
| 1 | The first edition | 2016.11 | NJI-637(X) |

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## Chapter 1 Introduction

Thank you very much for choosing Hitachi Programmable Automation Controller (hereinafter referred to as PAC) HX series.

This application manual informs hardware of HX series which is a high-performance PAC system suitable for IoT. The contents relevant to programming has been separated as an application manual (software) and a command reference manual.

Please read this manual and the following manuals carefully when constructing a system using HX series.
Table 1.1 List of Description materials

| Items | Title of material | Manual number |
| :---: | :--- | :--- |
| HX series | Application manual (Hardware) | NJI-637*1(X) |
|  | Application manual (Software) | NJI-638*1(X) |
|  | Command reference manual | NJI-639*1(X) |

*1 The last alphabet of the manual No. stands for version starting from blank, A, B, C...

### 1.1 Doing after Unpacking

(1) Preparation of programming software HX-CODESYS

The programming software HX-CODESYS more than Ver3.5 SP8 Patch4 is necessary to use HX series CPU module (hereinafter referred to as HX-CPU).

Because programming software EHV-CODESYS for the Hitachi programmable controller EHV+ series does not support HX-CPU module, please do not use it.

## (2) Initializing of user program

Since a memory in the HX-CPU is not set at first, error code to mean memory error may be displayed on the 7-segment LED. Please initialize the memory in the HX-CPU first by using HX-CODESYS.

## (3) Battery error indication

HX-CPU is shipped without a lithium battery. The battery is sold separately from CPU.
Therefore when Battery error detection*2 (OK LED blinking in the battery error) of HX-CODESYS is set Enable, HX-CPU detects a battery error, and " 71 " is displayed in 7 -segment LED. When you want to invalidate battery error detection, please set this parameter in Disable (invalidity).
*2 The tab of Configuration in Device of the project tree has the setting of Battery error detection.
Battery error detection is set in Enable in initial setup.

### 1.2 About Manuals

Various modules for EH-150 / EHV series shown in Table 1.2 are able to be used with HX-CPU. There is some module that HX-CPU does not support yet. Un-supported modules are going to be supported.

Please refer to manuals shown in Table 1.2 for the detail specification of various modules. Please refer to chapter 5 or after of this manual for modules which manual number are blank in Table 1.2.

Table 1.2 Related manuals to HX-CPU (1/2)

| Product name | Model name | Specifications | Manual number |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Japanese | English |
| Power supply module | EH-PSA | Input 100 to 240 V AC Output | - | - |
|  | EH-PSD | Input 21.6 to 26.4 V DC Output | - | - |
|  | EH-PSR | Input 100 to 240 V AC Output for redundancy | - | - |
| I/O controller | EH-IOCH2 | I/O controller for expansion unit | - | - |
| Digital input module | EH-XD8 | 8 points, 24 V DC input | - | - |
|  | EH-XD16 | 16 points, 24 V DC input | - | - |
|  | EH-XDL16 | 16 points, 24 V DC input, Intensified filter | - | - |
|  | EH-XDS16 | 16 points, 24 V DC Fast input | - | - |
|  | EH-XD32 | 32 points, 24 V DC input | - | - |
|  | EH-XDL32 | 32 points, 24 V DC input, Intensified filter | - | - |
|  | EH-XDS32 | 32 points, 24 V DC Fast input | - | - |
|  | EH-XD32E | 32 points, 24 V DC input, Spring type terminal block | - | - |
|  | EH-XDL32E | 32 points, 24 V DC input, Spring type terminal block, Intensified filter | - | - |
|  | EH-XD32H | 32 points, 24 V DC input, Compatible connecter with EM and H-200 | - | - |
|  | EH-XD64 | 64 points, 24 V DC input | - | - |
|  | EH-XA16 | 16 points, 100 to 120 V AC input | - | - |
|  | EH-XAH16 | 16 points, 200 to 240 V AC input | - | - |
| Digital output module | EH-YR8B | 8 points, relay output (isolated contact point), $100 / 240 \mathrm{VAC}, 24 \mathrm{~V}$ DC | - | - |
|  | EH-YR12 | 12 points, relay output, $100 / 240 \mathrm{~V} \mathrm{AC}, 24 \mathrm{~V} \mathrm{DC}$ | - | - |
|  | EH-YR16 | 16 points, relay output, $100 / 240 \mathrm{~V} \mathrm{AC}, 24 \mathrm{~V} \mathrm{DC}$,16 points / 1 common | - | - |
|  | EH-YR16D | 16 points, relay output, $100 / 240 \mathrm{~V} \mathrm{AC}, 24 \mathrm{~V} \mathrm{DC}$,8 points / 1 common | - | - |
|  | EH-YT8 | 8 points, transistor output, $12 / 24 \mathrm{~V}$ DC (sink type) | - | - |
|  | EH-YTP8 | 8 points, transistor output, $12 / 24 \mathrm{~V}$ DC (source type) | - | - |
|  | EH-YT16 | 16 points, transistor output, 12 / 24 V DC (sink type) | - | - |
|  | EH-YTP16 | 16 points, transistor output, $12 / 24 \mathrm{~V}$ DC (source type) | - | - |
|  | EH-YTP16S | 16 points, transistor output, $12 / 24 \mathrm{~V}$ DC (source type), short-circuit protection | - | - |
|  | EH-YT32 | 32 points, transistor output, 12 / 24 V DC (sink type) | - | - |
|  | EH-YTP32 | 32 points, transistor output, $12 / 24 \mathrm{~V}$ DC (source type) | - | - |
|  | EH-YT32E | 32 points, transistor output, $12 / 24 \mathrm{~V}$ DC (sink type) Spring terminal block | - | - |
|  | EH-YTP32E | 32 points, transistor output, $12 / 24$ V DC (source type) Spring terminal block | - | - |
|  | EH-YT32H | 32 points, transistor output, $5 / 12 / 24 \mathrm{~V}$ DC (sink type) Compatible connecter with EM and H-200 | - | - |
|  | EH-YT64 | 64 points, transistor output, 12 / 24 V DC (sink type) | - | - |
|  | EH-YTP64 | 64 points, transistor output, $12 / 24 \mathrm{~V}$ DC (source type) | - | - |
|  | EH-YS16 | 16 points, triac output, $100 / 240 \mathrm{~V}$ AC | - | - |

[^0]Table 1.2 Related manuals to HX-CPU (2/2)

| Product name | Model name | Specifications | Manual number |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  |  | Japanese | English |
| Analog input module | EH-AX44 | 12 bits analog input ( 4 to $20 \mathrm{~mA}, 0$ to 10 V ) each 4 ch . | - | - |
|  | EH-AX8V | 12 bits analog input 8 ch ., Voltage ( 0 to +10 V ) | - | - |
|  | EH-AX8H | 12 bits analog input 8 ch., Voltage ( -10 to +10 V ) | - | - |
|  | EH-AX8I | 12 bits analog input 8 ch ., Current ( 4 to 20 mA ) | - | - |
|  | EH-AX8IO | 12 bits analog input 8 ch., Current ( 0 to 22 mA ) | - | - |
|  | EH-AXH8M | 14 bits analog input 8 ch . ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA},-10$ to $+10 \mathrm{~V}, 0$ to 10 V ) | - | - |
|  | EH-AXG5M | Isolation between channels, 16 bits analog input 5 ch . ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA},-10$ to $+10 \mathrm{~V}, 0$ to 10 V ) | - | - |
| Analog output module | EH-AY22 | 12 bits analog output ( 4 to $20 \mathrm{~mA}, 0$ to 10 V ) each 2 ch . | - | - |
|  | EH-AY2H | 12 bits analog output 2 ch., Voltage ( -10 to +10 V ) | - | - |
|  | EH-AY4V | 12 bits analog output 4 ch., Voltage ( 0 to +10 V ) | - | - |
|  | EH-AY4H | 12 bits analog output 4 ch ., Voltage ( -10 to +10 V ) | - | - |
|  | EH-AY4I | 12 bits analog output 4 ch., Current ( 4 to 20 mA ) | - | - |
|  | EH-AYH8M | 14 bits analog output 8 ch., ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA}, 0$ to 10 V ) | - | - |
|  | EH-AYG4M | Isolation between channels, 16 bits analog output 4 ch . ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA},-10$ to $+10 \mathrm{~V}, 0$ to 10 V ) | - | - |
| RTD input module | EH-PT4 | 4 channels resistance temperature detector, Signed 15 bits Platinum (Pt $100 \Omega / \operatorname{Pt} 1000 \Omega$ ) | NJI-323* | NJI-324* ${ }^{\text {(X) }}$ |
|  | EH-RTD8 | $6 / 8$ channels resistance temperature detector, Signed 15 bits Platinum ( $\operatorname{Pt} 100 \Omega$ / Pt $1000 \Omega$ ) | - | - |
| Thermocouple input module | EH-TC8 | Signed 15 bits, Thermocouple input (K, E, J, T, B, R, S, N) 8 channels | - | - |
| Positioning and counter module | EH-CU | 2 channels high-speed counter input, Maximum frequency of $100 \mathrm{kHz}, 1 / 2$-phases switchover, 4-point opened collector output | NJI-321* | NJI-321*(X) |
|  | EH-CUE | 1 channel high-speed counter input, Maximum frequency of $100 \mathrm{kHz}, 1 / 2$-phases switchover, 2-point opened collector output | - | - |
|  | EH-POS | 1 -axis pulse positioning module | NJI-314* | NJI-315*(X) |
| Communication module | EH-RMP2 | PROFIBUS-DP master module, 512 / 512 words I/O, 8 units per CPU can be installed | NJI-621* | NJI-621*(X) |
|  | EH-IOCP2 | PROFIBUS-DP slave controller, 122 / 122 words I/O | NJI-612* | NJI-612*(X) |
|  | EH-IOCA | EtherCAT slave controller, 176 words I/O | NJI-599* | NJI-599*(X) |
|  | EH-FLN3 | FL-net interface module | NJI-410* | - |
|  | EH-LNK | CPU link module (coaxial), 8 units per CPU can be mounted | NJI-381* | NJI-381*(X) |
|  | EH-OLNK | CPU link module (optical fiber), 8 units per CPU can be mounted | NJI-395* | NJI-395*(X) |
|  | EH-OLNKG | CPU link module (support optical fiber GI50 / $125 \mu \mathrm{~m}$ cable), 8 units per CPU can be mounted | NJI-395* | NJI-395* (X) |
|  | EH-OLNKE | CPU link module (support optical fiver GI62.5 / $125 \mu \mathrm{~m}$ cable), 8 units per CPU can be mounted | NJI-395* | NJI-395*(X) |

* The last alphabet of the manual No. stands for version starting from blank, A, B, C...


## MEMO

## Chapter 2 Features

### 2.1 Features of HX Series

## Open standards, High-performance, TCO reduction*1

(1) Open standards

The Hitachi HX Series supports global manufacturing by standardized programming with
5 programming languages compatible with the IEC61131-3 international standard. The integrated EtherCAT master function (industrial open network) enables interconnection of a wide range of devices. Seamless data transfer from field level to cloud is achieved via OPC-Unified Architecture.

## (2) High-performance

Through the effective combination of up-to-date developed high-performance CPU with CODESYS software, Hitachi provides sequential control (logic) and motion control*3 on one CPU platform with very fast execution speed.

## (3) TCO reduction*1

HX Series are designed to provide the functionality of PAC Controller (Programmable Automation Controller) which has both features of PLC and IPC.

HX series contribute to TCO (Total cost of ownership) reduction by drive down cost of installation, development and maintenance.


3 Ethernet port as standard (Full function model)
Various communication modes between master, controller and slave units by one CPU.


ERP : Enterprise Resource Planning, MES : Manufacturing Execution System
WMS : Warehouse Management System, IPC : Industrial PC
PLC : Programmable Logic Controller
*1 Total Cost of Ownership
*2 HF-W / IoT is a product of Hitachi Industry and Control Solutions, Ltd.
*3 Motion model is available with PLCopen based motion control function block. This model is planned to be released in near future.

## All modules of EH-150 series can be used.*1

HX-CPU can assemble all modules of EH- 150 series including input and output module and communication module.
When using a basic base units and 5 expansion bases, HX-CPU can controls 66 modules and 4,224 I/O points at the maximum.
*1 Some high-function modules will be supported in near future.


## EtherCAT master

In both the Standard Model and the Full Function Model, EtherCAT master function is available in Ethernet ports of the CPU.

Different type of slave devices such as inverters and remote I/O are controlled via EtherCAT.


## Large size data logging (SD Card)

The Full Function Model has a SD card interface, which makes data logging easy. (Function blocks to access files are available in CODESYS library.)


## OPC UA Server

The OPC UA (Unified Architecture) is a software interface between different manufacturers' apparatuses and host system based on the concept to unify industrial field and IT field.
HX-CPU has OPC-UA server function as standard. OPC-UA server allows easy connectivity with ERP, MES, SCADA, SAP, and various management and analysis software in host system.

## Programmable HMI connectivity

Programmable Touch-panel GP4000 series and EH-TP500 series are connectable with HX-CPU.


■ GP4000 series
All models are available with CODESYS V3 Ethernet Driver
Selectable from 4 models with $12.1 ", 10.4^{\prime \prime}, 7.5 ", 5.7 "$ display size

- EH-TP500 series


All models are available with CODESYS V3 Ethernet Driver
Selectable from 4 models with $13.3^{\prime \prime}, 10.4^{\prime \prime}, 7.0^{\prime \prime}, 4.3 "$ display size

## Easy maintenance

## ■ Fan-less design

The CPU has no mechanical parts which need to be replaced.

## - Battery-less design

Non-volatile memory is used for programming memory and data memory. The CPU can retain manufacturing data without optional batteries to protect the data from sudden power failures.

## Data and Program Protection

## ■ Block unauthorized access

- Detect / Protect unauthorized external access
- Block unauthorized remote login connection
- Prevent malicious data hacking
- Control user access
- Login authentification
- User and group control
- Setting access authority

Online user registration


Access permission


User management


## Web visualization (Monitoring via Web Browser)

Easy remote access to the controller's web server to monitor the application status without preparing a customized HMI. Potential cost reduction for hardware and on site resources through off site monitoring.

- Web server function prepared as standard (in Full Function Model)
- No requirement of customized HMI
- Availability of monitoring via standard web browser
- Remote maintenance, diagnosis and control can be also achieved



### 2.2 Integrated Development System HX-CODESYS

CODESYS is the widest-spread IEC61131-3 development system in the world. Over 350 controller manufacturers rely on CODESYS, in addition to tens of thousands of end users from a wide variety of industries.

## HX-CODESYS -integrating various support functions in every phase of development



- Project tree allow you collective management of device, task and program of application.
- Integrated configurator for EtherCAT and Modbus can connect I/O channels on slaves to IEC variables.
- HX-CODESYS is including editors for all 5 IEC 61131-3 compliant implementation languages.
- The tool display language supports Japanese, English German, French, Italian, Spanish, Russian, Chinese, eight languages in total.
- Optional object-oriented programming according to IEC 61131-3 (3rd Edition).
- Compiler for optimized powerful machine code of HX-CPU.
- Various function such as automatic input completion and assistance, syntax error check, debug and simulation allow you efficient development.


## IEC61131-3 compliant 5 languages available to skill and application

## LD (Ladder Diagram)

LD is a graphical language based on relay circuit. LD is suitable for the bit operation such as interlock processes.

## FBD (Function Block Diagram)

FBD is a graphic language which the flow of data and the signal is easy to watch.


## ST (Structured Text)

ST is a text language based on PASCAL. It is suitable for branch, repetition and the arithmetic operation that were weak points in LD.

```
count_M3 := count_M3 + 1;
L2_wait_time (IN:=FALSE, PT:=T#3.6S);
L2_wait_time (IN:=TRUE);
FOR i:=0 TO count_T
    K1_temp[i]:=B1_init; // Reset B1
END_FOR
IF count_Nmax <24 THEN
    WHILE vxent < 10 DO
        T1max:=125; // Max.=125 C
    END_WHILE
END_IF
B100}\mathrm{ status:=FALSE; // B100 complete
```


## SFC (Sequential Function Chart)

SFC is a graphic language which can express state transition. It is suitable for process control to step. Each step is able to be described with LD, FBD and IL.



## IL (Instruction List)

IL is a text language suitable for traditional PLC. It is suitable for high speed operation and convenient for read out and collate program.

| 1 | LD | t1_open |
| :---: | :---: | :---: |
|  | AND | t1_rdy |
|  | OR | t2_status0K |
|  | ST | fwd_cvy10 |
| 2 | CAL | TON_0 |
|  |  | cvyOK, |
|  |  | T\#3s, |
|  |  | ET_TONO) |
|  | LD | TON_0.Q |
|  | ST | start_cvy |

## CFC (Continuous Function Chart)

CFC is a graphical language with unrestricted layout of POUs and connections, including feedback paths. (CFC is not IEC61131-3 compliant language.)


## Reduction of development time and cost of IEC 61131-3 compliant applications

## - Local variable and Global variable

You can define Local variables that are effective only in each program and Global variables that are effective in all program. You can make application program having high reusability by using a local variable and global variable properly.

- Structured programming

You can make programs and function blocks with multi-layer structure. This structured programming improves readability of program, maintenance characteristics and reliability. As a result, application development efficiency increases.

- Library

Frequently used program or function can be registered as library, which can be called from other projects. Library contents can able to be non-indicated for the distribution use to end users.


## Substantial library

Various libraries such as PID or various conversion are incorporated as a standard library other than IEC61131-3 standard command.


## Convenient functions

HX-CODESYS improves programming efficiency, debug efficiency in various convenient functions.

- Automatic input completion and assistance avoiding compile error because of input error.
- Color-coded syntax highlighting, for example keywords and connected brackets.
- In LD editor and FBD editor, you can use ST language in function block.
- You can change any circuit or command to comment with right-click.



## Powerful debugging functions

Powerful debugging functions features save commissioning cost.

- Online-monitor
- Offline-simulation
- Breakpoint
- Force value
- Single step execution
- Single cycle execution
- Flow control
- Program change during run
- Trace
- Visualization
- Web visualization



## About HX-CODESYS

HX-CODESYS is IEC61131-3 compliant integrated development system for only HX series.
CODESYS® is a registered trademark of 3S-Smart Software Solutions GmbH. HX-CODESYS is the same tool with CODESYS, but is preinstalled device description files and libraries for HX series.

### 2.3 Communication Function

HX-CPU of Full function model has 3 Ethernet ports.(HX-CPU of standard model has 2 Ethernet ports) HX-CPU can communicate with host system, controller, and field devices individually. In addition, by a combination of how to use, HX-CPU can realize various communications.


Figure 2.1 Ethernet Communication port

You can build a flexible system with HX-CPU and Hitachi EtherCAT slave products such as coupler type slave (EH-IOCA) and Inverter and Servo. EH-IOCA is a coupler type slave and can be connected with 22 modules per slave node. Therefore, EH-IOCA can control 1,408 points in digital I/O. ( 176 channels in analog I/O) The configuration example is shown in Figure 2.2.

## [Configuration Example]



Figure 2.2 EtherCAT configuration

### 2.4 System Configuration

HX series is a module type programmable automation controller. The basic configuration is shown in Figure 2.3.


Figure 2.3 System configuration diagram (HX series)

Table 2.1 Modules in HX system configuration

| No. | Device name | Description of function |
| :---: | :--- | :--- |
| 1$]$ | Power supply module | Converts power supply to the power to be used within the HX-series. |
| 2$]$ | CPU module | Performs operations based on the content of the user program, receives input and controls <br> output. |
| 3$]$ | I/O module | Input module, output module, analog module, high-functional module, and communicate <br> module. |
| 4$]$ | Basic base | Base in which the power module, CPU module, I/O module, etc. are loaded. |
| 5$]$ | Expansion base | Base in which the power module, input and output controller, I/O module, etc. are loaded. |
| 6$]$ | Expansion cable | Cable to connect the input and output controller for the expansion base with the basic base. <br> Use 2m betweens stations at the maximum and within 8m at total. |
| 7$]$ | Input and output <br> controller | Interface between the expansion base and the CPU module. |

[^1]
## Chapter 3 General Specifications

### 3.1 General Specifications

Table 3.1 General specifications of HX series

| Item |  | Specification |
| :---: | :---: | :---: |
| Input Power voltage | AC | 100 / 110 / $120 \mathrm{~V} \mathrm{AC} \mathrm{(50} \mathrm{/} 60 \mathrm{~Hz}$ ), 200 / 220 / 240 V AC ( $50 / 60 \mathrm{~Hz}$ ) |
|  | DC | 24 V DC |
| Power voltage fluctuation range |  | 85 to 264 V AC |
|  |  | 21.6 to 26.4 V DC |
| Allowable instantaneous power failure |  | 85 to 100 V AC : when instantaneous power failure of less than 10 ms , operation continues 100 to 264 V AC: when instantaneous power failure of less than 20 ms , operation continues 21.6 to 26.4 V DC: when instantaneous power failure of less than 1 ms , operation continues |
| Operational temperature |  | 0 to $55^{\circ} \mathrm{C}\left(0\right.$ to $\left.45^{\circ} \mathrm{C} * 1\right)$ |
| Storage temperature |  | -10 to $75^{\circ} \mathrm{C}$ |
| Operational humidity |  | 5 to $95 \% \mathrm{RH}$ (no condensation) |
| Storage humidity |  | 5 to $95 \%$ RH (no condensation) |
| Vibration resistance |  | Conforms to IEC 60068-2-6 |
| Shock resistance |  | Conforms to IEC 60068-2-27 |
| Noise resistance |  | O Noise voltage $1,500 \mathrm{Vpp}$, Noise pulse width $100 \mathrm{~ns}, 1 \mu \mathrm{~s}$ (Noise input by a noise simulator across input terminals of a power module according to measuring method of Hitachi-IES) Conforms to IEC61131-2 (not applied for input modules) Static noise $3,000 \mathrm{~V}$ at electrode part |
| Insulation resistance |  | $20 \mathrm{M} \Omega$ minimum between AC terminal and frame ground (FE) terminal (Conforms to 500 V DC megger) |
| Dielectric withstand voltage |  | $1,500 \mathrm{~V} \mathrm{AC}$ for 1 minute between AC input terminal and frame ground (FE) terminal |
| Ground |  | Class D grounding (grounding with the power supply module) |
| Usage environment |  | No corrosive gases, no excessive dust |
| Structure |  | Open wall-mount type |
| Cooling |  | Natural air cooling |

*1 If EH-YR16 is used as UL listed product, max. surrounding temperature rating is $45^{\circ} \mathrm{C}$.

### 3.2 List of System Equipment

(1) Modules

Table 3.2 List of system equipment (1/2)

| Product | Model name | Specification | Standard compliant | Remarks |
| :---: | :---: | :---: | :---: | :---: |
| Power module | EH-PSA | Input 100 to 240 V AC, Output 5V DC $3.8 \mathrm{~A}, 24 \mathrm{~V}$ DC 0.4 A | CE, UL, RCM | *1 |
|  | EH-PSD | Input 24 V DC, Output 5 V DC 3.8 A | CE, UL, RCM | * 1 |
|  | EH-PSR | Input 100 to 240 V AC, Output 5V DC $5.6 \mathrm{~A} * 5$ | CE | *1 |
| I/O controller | EH-IOCH2 | I/O control module (1 unit / expansion base unit) | CE, UL, RCM | *1 |
| Base unit | EH-BS3A | 3 I/O modules installed | CE, UL, RCM | Commonly used for basic or expansion base |
|  | EH-BS5A | $5 \mathrm{I} / \mathrm{O}$ modules installed | CE, UL, RCM |  |
|  | EH-BS6A | 6 I/O modules installed | CE, UL, RCM |  |
|  | EH-BS8A | $8 \mathrm{I} / \mathrm{O}$ modules installed | CE, UL, RCM |  |
|  | EH-BS11A | $11 \mathrm{I} / \mathrm{O}$ modules installed | CE, UL, RCM |  |
|  | EH-BS8R | Redundant power supply, 8 I/O modules installed | - |  |
| Digital input module | EH-XD8 | $8 \mathrm{pts} ., 24 \mathrm{~V}$ DC input (response time 5 ms ) | CE, UL, RCM | *3 |
|  | EH-XD16 | $16 \mathrm{pts} ., 24 \mathrm{~V}$ DC input (response time 5 ms ) | CE, UL, RCM | *3 |
|  | EH-XDL16 | 16 pts., 24V DC input (response time 16 ms ) | CE, RCM | *3 |
|  | EH-XDS16 | $16 \mathrm{pts} ., 24 \mathrm{~V}$ DC input (response time 1 ms ) | CE, RCM | *3 |
|  | EH-XD32 | $32 \mathrm{pts} ., 24 \mathrm{~V}$ DC input (response time 5 ms ) | CE, UL, RCM | - |
|  | EH-XDL32 | 32 pts., 24V DC input (response time 16 ms ) | - | - |
|  | EH-XDS32 | $32 \mathrm{pts} ., 24 \mathrm{~V}$ DC input (response time 1 ms ) | CE, RCM | - |
|  | EH-XD32E | 32 pts ., 24V DC input (response time 1 ms ), Spring type terminal | CE, UL, RCM | - |
|  | EH-XDL32E | 32 pts., 24V DC input (response time 16 ms ), Spring type terminal | CE, UL, RCM | - |
|  | EH-XD32H | 32 pts., 24V DC input (response time 4 ms ), compatible connector with PIM / H-DM (EM / H-200) | CE, RCM | - |
|  | EH-XD64 | 64 pts., 24V DC input (response time 1 ms ) | CE, UL, RCM | - |
|  | EH-XA16 | 16 pts., 100 to 120 V AC input (response time 15 ms ) | CE, UL, RCM | *3 |
|  | EH-XAH16 | 16 pts., 200 to 240 V AC input (response time 15 ms ) | CE, UL, RCM | *3 |
| Digital output module | EH-YR8B | 8 pts., Independent relay output, $100 / 240 \mathrm{~V}$ AC, 24 V DC | CE, RCM | *3, *4 |
|  | EH-YR12 | 12 pts., Relay, $100 / 240 \mathrm{~V}$ AC, 24 V DC | CE, UL, RCM | *3, *4 |
|  | EH-YR16 | 16 pts., Relay, 100 / 240V AC, 24 V DC | CE, UL, RCM | *3, *4 |
|  | EH-YR16D | 16 pts., Relay, $100 / 240 \mathrm{~V}$ AC, 24 V DC, 2-common | CE, RCM | *3 |
|  | EH-YT8 | 8 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (sink type) | CE, UL, RCM | *3, *4 |
|  | EH-YTP8 | 8 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (source type) | CE, UL, RCM | *3, *4 |
|  | EH-YT16 | 16 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (sink type) | CE, UL, RCM | *3, *4 |
|  | EH-YTP16 | 16 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (source type) | CE, UL, RCM | *3, *4 |
|  | EH-YTP16S | 16 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (source type) *3 | CE, UL, RCM | Electric short circuit protection |
|  | EH-YT32 | 32 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (sink type) *2 | CE, UL, RCM |  |
|  | EH-YTP32 | 32 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (source type) *2 | CE, UL, RCM |  |
|  | EH-YT32E | 32 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (sink type), Spring type terminal | CE, UL, RCM |  |
|  | EH-YTP32E | 32 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (source type), Spring type terminal | CE, UL, RCM |  |
|  | EH-YT32H | 32 pts., Transistor, 5 / 12 / 24V DC (sink type), compatible connector with POM / H-DM (EM / H-200) | CE, RCM | ${ }^{-}$ |
|  | EH-YT64 | 64 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (sink type) | CE, UL, RCM | Electric short circuit protection |
|  | EH-YTP64 | 64 pts., Transistor, $12 / 24 \mathrm{~V}$ DC (source type) | CE, UL, RCM |  |
|  | EH-YS16 | 16 pts., Triac, $100 / 240 \mathrm{~V}$ AC | CE, RCM | *3, *4 |

[^2]| Cable for wiring |  |  | Torque to tighten <br> the terminal |
| :---: | :---: | :---: | :---: |
| Wire Size | Material | Type |  |
| $22-14$ AWG | Cu | $\mathrm{Sol} / \mathrm{Str}$. | 9 in.-lbs <br> $(1.02 \mathrm{Nm})$ |

Table 3.2 List of system equipment (2/2)

| Product | Model name | Specification | Standard compliant | Remarks |
| :---: | :---: | :---: | :---: | :---: |
| Analog input module | EH-AX44 | 12 bits, 8 ch . ( 4 ch . of 4 to $20 \mathrm{~mA}, 4 \mathrm{ch}$. of 0 to 10 V ) | CE, UL, RCM | *3 |
|  | EH-AX8V | 12 bits, 8 ch., Voltage ( 0 to 10 V ) | CE, UL, RCM | *3 |
|  | EH-AX8H | 12 bits, 8 ch., Voltage ( -10 to +10 V ) | CE, UL, RCM | *3 |
|  | EH-AX8I | 12 bits, 8 ch., Current ( 4 to 20 mA ) | CE, UL, RCM | *3 |
|  | EH-AX8IO | 12 bits, 8 ch., Current ( 0 to 22 mA ) | CE, UL, RCM | *3 |
|  | EH-AXH8M | 14 bits, 8 ch. ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA},-10$ to $+10 \mathrm{~V}, 0$ to 10 V ) | CE, UL, RCM | *3 |
|  | EH-AXG5M | $12 / 16$ bits, 5 ch. ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA},-10$ to $+10 \mathrm{~V}, 0$ to 10 V ), Galvanic isolation between channels | CE, RCM | *3 |
|  | EH-PT4 | Signed 15 bits, 4 ch . Resistance Temperature Detector input, PT100 / PT1000 | CE, UL, RCM | *3 |
|  | EH-RTD8 | Signed 15 bits, 6 ch. (3-wire) / 8 ch. (2-wire) Resistance Temperature Detector input, PT100 / PT1000 | CE, RCM | *3 |
|  | EH-TC8 | Signed 15 bits, 8 ch. Thermocouple input (K,E,J,T,B,R,S,N) | CE, UL, RCM | *3 |
| Analog output module | EH-AY22 | 12 bits, 4 ch . ( 2 ch . of 4 to $20 \mathrm{~mA}, 2 \mathrm{ch}$. of 0 to 10 V ) | CE, UL, RCM | *3 |
|  | EH-AY2H | 12 bits, 2 ch., Voltage ( -10 to +10 V ) | CE, UL, RCM | *3 |
|  | EH-AY4V | 12 bits, 4 ch., Voltage ( 0 to 10 V ) | CE, UL, RCM | *3 |
|  | EH-AY4H | 12 bits, 4 ch., Voltage ( -10 to +10 V ) | CE, UL, RCM | *3 |
|  | EH-AY4I | 12 bits, 4 ch., Current ( 4 to 20 mA ) | CE, UL, RCM | *3 |
|  | EH-AYH8M | 14 bits, 8 ch. ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA}, 0$ to 10 V ) | CE, UL, RCM | *3 |
|  | EH-AYG4M | $12 / 16$ bits, 4 ch. ( 0 to $22 \mathrm{~mA}, 4$ to $22 \mathrm{~mA}, 0$ to $10 \mathrm{~V},-10$ to +10 V ), Galvanic isolation between channels | CE, RCM | *3 |
| Positioning and counter module | EH-CU | 2 channels high-speed counter input, Maximum frequency of $100 \mathrm{kHz}, 1 / 2$-phases switchover, 4-point opened collector output | CE, UL, RCM | - |
|  | EH-CUE | 1 channel high-speed counter input, Maximum frequency of 100 kHz , 1/2-phases switchover, 2-point opened collector output | CE, UL, RCM | - |
|  | EH-POS | 1-axis pulse positioning module | CE, UL, RCM | - |
| Communicat ion and network module | EH-RMP2 | PROFIBUS-DP master module, 512 / 512 words I/O | CE, RCM | 8 units per CPU |
|  | EH-IOCP2 | PROFIBUS-DP slave controller, 1,408 points(176 words) I/O | CE, RCM | * 1 |
|  | EH-IOCA | EterCAT slave controller, 1408 points (176 words) I/O | CE, RCM | *1 |
|  | EH-LNK | CPU link module (coaxial) | CE, RCM | 8 units per CPU |
|  | EH-OLNK | CPU link module (optical fiber) | CE, UL, RCM | 8 units per CPU |
|  | EH-OLNKG | CPU link module (support optical fiber GI50 / $125 \mu \mathrm{~m}$ cable) | CE, UL, RCM | 8 units per CPU |
|  | EH-OLNKE | CPU link module (support optical fiber GI62.5 / $125 \mu \mathrm{~m}$ cable) | CE, UL, RCM | 8 units per CPU |
|  | EH-FLN3 | FL-net interface module | CE, UL, RCM | 2 units per CPU |
| Dummy module | EH-DUM | Module for an opened slot | CE, UL, RCM | - |

*1 CPUs, power modules and I/O controllers (EH-IOCH2, EH-IOCP2, EH-IOCA) are mounted on reserved positions only.
*2 Short circuit protection version is from May 2001 production. (MFG. No. 01Exx)
*3 The suggested torque for the terminal connections is 9 in -lbs as below.

| Cable for wiring |  |  | Torque to tighten <br> the terminal |
| :---: | :---: | :---: | :---: |
| Wire Size | Material | Type |  |
| $22-14$ AWG | Cu | $\mathrm{Sol} / \mathrm{Str}$. | 9in.-lbs <br> $(1.02 \mathrm{Nm})$ |

## [Installation rule]

- EH-(O)LNK / RMP2 can be mounted up to 8 units per CPU. Available position is from slot 0 to 7 of basic base only.
- EH-FLN3 can be mounted up to 2 units per CPU. Available position is from 0 to 7 of basic base only.


## Caution

The system of HX-CPU supports a maximum of 11 modules per base units. However, the number of modules which can be provided depends on the maximum output current of the power module. Make sure to use HX-CPU in a permissible level of the maximum output current of the power module. Please refer to section 3.3 for list of current consumption.
(2) Peripheral devices

Table 3.3 Peripheral device of HX series

| Product | Model name | Specification | Remarks |
| :---: | :--- | :--- | :---: | :---: |
| HX-CODESYS | HX-CDS | IEC 61131-3 compliant programming software with ST (Structured Text), SFC <br> (Sequential Function Chart), FBD (Function Block Diagram ), <br> LD (Ladder Logic Diagram) and IL (Instruction List). <br> Supported operating system: <br> Windows ® XP, Windows ® 7 (32 / 64 bit), Windows ® 8, Windows ® 8.1, <br> Windows ® 10 <br> Multilingual support (Japanese, English, German, Spanish, French, Italy, Russian, <br> Chinese) | - |

[^3]
## (3) Connection cable

Table 3.4 Connection cables of HX series

| Product | Model name | Specification |
| :---: | :---: | :---: |
| Cable for connecting basic base I/O controller *1 | EH-CB05A | 0.5 m (1.64 ft.) length (basic to expansion and expansion to expansion) |
|  | EH-CB10A | $1 \mathrm{~m}(3.28 \mathrm{ft}$.) length (basic to expansion and expansion to expansion) |
|  | EH-CB20A | 2 m (6.56 ft.) length (basic to expansion and expansion to expansion) |
| Cable for 32 / 64-points I/O module (Both edges connector type) | EH-CBM01W | 1 m (3.28 ft.) length ( $32 / 64$-points I/O module to terminal block adaptor) |
|  | EH-CBM03W | 3 m (9.84 ft.) length ( $32 / 64$-points I/O module to terminal block adaptor) |
|  | EH-CBM05W | 5 m (16.4 ft.) length ( $32 / 64$-points I/O module to terminal block adaptor) |
|  | EH-CBM10W | 10 m ( 32.8 ft .) length ( $32 / 64$-points I/O module to terminal block adaptor) |
| Cable for 32 / 64-points I/O module (One edges connector type) | EH-CBM01 | 1 m (3.28 ft.) length ( $32 / 64$-points I/O module to external equipments) |
|  | EH-CBM03 | 3 m (9.84 ft.) length ( $32 / 64$-points I/O module to external equipments) |
|  | EH-CBM05 | 5 m (16.4 ft.) length ( $32 / 64$-points I/O module to external equipments) |
|  | EH-CBM10 | 10 m ( 32.8 ft .) length ( $32 / 64$-points I/O module to external equipments) |
| Cable for counter input module | EH-CUC01 | $1 \mathrm{~m}(3.28 \mathrm{ft}$.) length (Counter input module to external equipments) |
|  | EH-CUC02 | 2 m ( 6.56 ft .) length (Counter input module to external equipments) |
|  | EH-CUC03 | 3 m (9.84 ft.) length (Counter input module to external equipments) |
|  | EH-CUC04 | 4 m (13.1 ft.) length (Counter input module to external equipments) |
|  | EH-CUC05 | 5 m (16.4 ft.) length (Counter input module to external equipments) |

*1 Use in a maximum of $2 \mathrm{~m}(6.56 \mathrm{ft}$.) between stations, 8 m (26.24ft.) in total
(4) Optional product

Table 3.5 Optional product of HX series

| Product | Use | Remarks |
| :---: | :--- | :--- |
| HX-BAT | The battery is to work real-time clock only. |  |

During the 8 days or more of a power cut, if the retention of realtime clock data is required, please use the Lithium battery. But even in the case of using real time clock, Battery is unnecessary when HX-CPU are always synchronized with NTP server. HX-CPU stores user program and data (retain and persistent) to a nonvolatile memory, so the battery is unnecessary for them. The durable life of the battery is 5 years. Even if the battery $t$ is not a life, replace it every 5 years.
[Reference]
Table 3.6 The life of battery

| The life of battery (Total power failure) [ Hr ] |  |
| :---: | :---: |
| Guaranteed value (MIN) @55 ${ }^{\circ} \mathrm{C}$ | Actual value (MAX) @ $25{ }^{\circ} \mathrm{C}$ |
| 25,000 | 67,000 |

### 3.3 List of Current Consumption

Table 3.7 List of current consumption of modules

| Product | Model name | Current consumption $[\mathrm{mA}]$ | Product | Model name | Current consumption $[\mathrm{mA}]$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| CPU module | HX-CP1S08 | 1,000 | Analog input module | EH-AX44 | 100 |
|  | HX-CP1H16 | 1,200 |  | EH-AX8V | 100 |
| I/O controller | EH-IOCH2 | 80 |  | EH-AX8H | 100 |
| Base unit | EH-BS3A | 200 |  | EH-AX8I | 100 |
|  | EH-BS5A | 200 |  | EH-AX8IO | 100 |
|  | EH-BS6A | 200 |  | EH-AXH8M | 70 |
|  | EH-BS8A | 200 |  | EH-AXG5M | 300 |
|  | EH-BS11A | 200 |  | EH-PT4 | 160 |
|  | EH-BS8R | 200 |  | EH-RTD8 | 300 |
| Input module | EH-XD8 | 30 |  | EH-TC8 | 70 |
|  | EH-XD16 | 50 | Analog output module | EH-AY22 | 100 |
|  | EH-XDL16 | 50 |  | EH-AY2H | 100 |
|  | EH-XDS16 | 50 |  | EH-AY4V | 100 |
|  | EH-XD32 | 60 |  | EH-AY4H | 100 |
|  | EH-XDL32 | 60 |  | EH-AY4I | 130 |
|  | EH-XD32E | 60 |  | EH-AYH8M | 70 |
|  | EH-XDL32E | 60 |  | EH-AYG4M | 730 |
|  | EH-XD32H | 60 | Positioning, and Counter module | EH-CU | 310 |
|  | EX-XD64 | 80 |  | EH-CUE | 310 |
|  | EH-XA16 | 50 |  | EH-POS | 300 (600)*1 |
|  | EH-XAH16 | 50 | Communication and network module | EH-RMP2 | 780 |
| Output module | EH-YR8B | 220 |  | EH-IOCP2 | 350 |
|  | EH-YR12 | 40 |  | EH-IOCA | 350 |
|  | EH-YR16 | 430 |  | EH-FLN3 | 350 |
|  | EH-YR16D | 430 |  | EH-LNK | 550 |
|  | EH-YT8 | 30 |  | EH-OLNK | 550 |
|  | EH-YTP8 | 30 |  | EH-OLNKG | 550 |
|  | EH-YT16 | 50 |  | EH-OLNKE | 550 |
|  | EH-YTP16 | 50 |  | EH-FLN3 | 350 |
|  | EH-YTP16S | 50 | Dummy module | EH-DUM | 0 |
|  | EH-YT32 | 90 |  |  |  |
|  | EH-YTP32 | 90 |  |  |  |
|  | EH-YT32E | 90 |  |  |  |
|  | EH-YTP32E | 90 |  |  |  |
|  | EH-YT32H | 90 |  |  |  |
|  | EH-YT64 | 120 |  |  |  |
|  | EH-YTP64 | 120 |  |  |  |
|  | EH-YS16 | 250 |  |  |  |

*1 In the case of Positioner connected.

## Caution

The system of HX-CPU supports a maximum of 11 modules per base units. However, the number of modules which can be provided depends on the maximum output current of the power module. Make sure to use HX-CPU in a permissible level of the maximum output current of the power module. Please refer to section 3.3 for list of current consumption.

## Chapter 4 CPU Module

### 4.1 Outline

Standard model


Full function model




ETH1 L/A LED (green)


Table 4.1 Each description of items in CPU module

| No. | Item | Description |
| :---: | :---: | :---: |
| 1 | RUN LED | Indicates operation status. (Green lighting: RUN / off: STOP) |
| 2 | ERR LED | Indicates error status. (Red blinking: battery error, I/O module mismatch or initialization of RTC (real time clock) etc. / red lighting: other errors / off: no error) |
| 3 | 7-segment LED | Indicates error code. <br> And indicates the status of the USB memory with dot LED "." on the right. <br> (Lighting: mounting, off: unmount) |
| 4 | USB host port (Type:A) | USB host function (Data logging) is supported. User program is needed to use data logging (File read / write / compare). Support device is USB memory only. |
| 5 | USB device port (Type:mini-B) | USB port supports gateway function (with HX-CODESYS) only. USB cable is not included with CPU package nor supplied by Hitachi-IES. Use type Mini-B USB cable. |
| 6 | Serial port (Full function model) | Serial communication port has a RS-485 interface with terminal. It is supporting Modbus-RTU (master / slave) and general purpose. User program is needed to use general purpose. |
| 7 | Ethernet port (ETH 1,2) | Ethernet port 1, 2 have both gateway function (with HX-CODESYS / HMI / OPC) and IEC programming function supporting global network variable, EtherCAT master, Modbus-TCP client / server and OPC-UA server. Do not use other function if EtherCAT master can be used. |
| 8 | Ethernet port (ETH 3) <br> (Full function model) | Ethernet port 3 has both gateway function (with HX-CODESYS / HMI / OPC) and IEC programming function supporting global network variable, Modbus-TCP client / server and OPC-UA server. EtherCAT master function is not supported. |
| 9 | SD card slot (Full function model) | SD / SDHC card are supported. Data logging function is supported. User program is needed to use data logging (File read / write / compare). |
| 10 | RUN / STOP switch | When this switch position is in RUN (left), CPU start executing program. At the same time, remote controlling is enabled, in which case, CPU is started or stopped by HX-CODESYS over communication. <br> When this switch position is in STOP (right), CPU stop executing program. In this status, remote controlling is disabled. |
| 11 | Error clear switch (E.CLR) | If any error occurs, error code is displayed in 7-segment LED and remains after the error cause is deactivated. When pressing this button, error code is cleared. If the error cause is still remaining, error code will be displayed again. |
| 12 | SD card switch(SW2) <br> (Full function model) | When pressing this switch, SD card is unmounted. Please check lights-out of READY LED before pull out SD card. |
| 13 | ACCESS LED <br> (Full function model) | Not supported. |
| 14 | READY LED <br> (Full function model) | Indicates the status of SD card. Do not pull out SD card during lighting. (Green lighting: mounting, off: unmount) |
| 15 | SPEED LED | Indicates communication speed of each Ethernet port. (Yellow lighting: 100Mbps, off: 10 Mbps or link-down) |
| 16 | L/A LED | Indicates the status of each Ethernet communication. (Green lighting: Ethernet link-up, blinking: Data is sent or received, off: link-down) |
| 17 | 2-bit switch (SW1) | User program can be downloaded, uploaded or verified according to switch position.* Resetting the factory default settings. Please refer to section 13.2. |
| 18 | 4-bit switch (SW3) (Full function model) | Not supported. Please keep off. |
| 19 | Lock button | Press this button to dismount from the base units. <br> Module can be fixed firmly by a screw of $\mathrm{M} 4 \times 10 \mathrm{~mm}$ ( 0.39 in.). |
| 20 | Front cover | Open this cover when operating the switch, button or replacing the battery. Keep the cover closed while cpu execute program. |
| 21 | Battery holder Battery connector | RTC (real time clock) data is retained by battery. Data specified as RETAIN and PERSISTENT and user program are retained without battery. <br> -The battery has polarity. When plugging in, check the polarity carefully. <br> -The battery is not included with CPU package. <br> -Replace the battery every five years even when doesn't reach the end of the battery. |
| 22 | FE terminal | Connect to Class D grounding. |

[^4]
## 1. Caution

Note the cautions for the communication ports.
Since EtherCAT supports 100 Mbps only, communication error might occur depending on installation environment, cable length or external noise. In this case, check your installation environments and take appropriate countermeasures to reduce noise.

### 4.2 Performance Specifications

Table 4.2 Performance specifications

| Item |  | Specification |  |
| :---: | :---: | :---: | :---: |
|  |  | HX-CP1S08 | HX-CP1H16 |
| Model |  | Standard Model | Full Function Model |
| User program memory *1 |  | 8 MB | 16 MB |
| Source file memory *1 |  | 8 MB | 16 MB *2 |
| Data memory (non-retain) *1 |  | 8 MB | 16 MB |
| Data memory (retain) *1 |  | 250 kB |  |
| Data memory (persistent) *1 |  | 250 kB |  |
| Field bus / Marker memory |  | 48 kB |  |
| Number of expansion base units |  | 5 units |  |
| Expansion cables |  | Between stations : $0.5 \mathrm{~m}, 1 \mathrm{~m}, 2 \mathrm{~m}$, Total length: 8 m or less |  |
| Number of I/O points (using 64 points module) |  | 4,224 points |  |
| I/O modules |  | Common with EH-150 / EHV series (Refer to section 3.2 for detail) |  |
| Programming language |  | IEC61131-3 compliant 5 languages + CFC  <br> LD : Ladder Logic Diagram <br> FBD : Function Block Diagram <br> SFC : Sequential Function Chart <br> IL : Instruction List <br> ST : Structured Text <br> CFC : Continuous Function Chart |  |
| I/O update cycle |  | Refresh processing |  |
| Execution speed | Boolean instruction | min. 1.0 ns |  |
|  | Double-precision floating point | $\min .6 .6 \mathrm{~ns}$ |  |
| Communication interfaces | Protocol | CODESYS V3 protocol |  |
|  | USB device | 1 port (Mini-B type connector, USB 2.0 High speed) |  |
|  | USB host | 1 port (A type connector, USB 2.0 High speed) for USB memory *3 |  |
|  | Ethernet | 2 ports (10BASE-T / 100BASE-TX) | 3 ports (10BASE-T / 100BASE-TX) |
|  | Serial | - | 1 port (RS-485) |
| $\begin{aligned} & \text { Available } \\ & \text { communication } \end{aligned}$ | OPC UA | $\checkmark$ | $\checkmark$ |
|  | Web Visualization | - | $\checkmark$ |
|  | NTP (network time protocol) | $\checkmark$ | $\checkmark$ |
|  | FTP (server) | $\checkmark$ | $\checkmark$ |
|  | EtherCAT Master*6 | $\checkmark$ | $\checkmark$ |
|  | (Communication cycle) | min. 1 ms |  |
|  | Modbus-TCP Client | $\checkmark$ | $\checkmark$ |
|  | Modbus-TCP Server | $\checkmark$ (Maximum number of clients : 16) |  |
|  | Modbus-RTU Client | - | $\checkmark$ |
|  | Modbus-RTU Server | - | $\checkmark$ |
| SD memory card slot |  | - | 1 slot (SD / SDHC) |
| Display and switch | Display | RUN LED, ERR LED, 7-segmented LED (2digits) |  |
|  | RUN / STOP switch | STOP / RUN (Remote control of RUN / STOP over communication from HX-CODESYS is enable when switch position is in RUN.) |  |
|  | Error clear switch | Clear of error code |  |
|  | 2-bit switch (SW1) | Reserved for future |  |
|  | 4-bit switch (SW3) | - | Reserved for future |
| Real-time clock |  | Built-in RTC (deviation $\pm 60 \mathrm{~s} /$ month at $25^{\circ} \mathrm{C}$ ) |  |
| Battery (Option for RTC) |  | HX-BAT (for RTC) *4 |  |
| Startup time |  | About 20 to $30 \mathrm{~s} * 5$ |  |
| Maintenance function | Self-diagram | microcomputer error, watchdog timer error, memory error, program error, system ROM / RAM error, scan time error, battery under-voltage detection, and others |  |
| Compliant |  | CE, RCM |  |
| Version of CODESYS runtime |  | 3.5.8.21 or later | 3.5.8.22 or later |
| Available version of CODESYS |  | 3.5 SP8 patch4 or later |  |

*1 Because the additional information of the program is stored, it becomes slightly smaller than a specification level.
*2 The source file memory is shared with files for Web visualization.
*3 For data storage.
*4 The battery is option for RTC.
*5 It depends on the size of the user program.
*6 EtherCAT master function must be configured it alone. Do not configure the other function with EtherCAT master function.

Table 4.3 EtherCAT functional specifications

| Item | Specification |
| :---: | :---: |
| Protocol | EtherCAT ${ }^{\circledR}$ protocol ( CoE ) |
| Supported communication profiles | CoE (PDO, SDO) |
| Synchronization (DC) | Supported |
| Physical layer | 100BASE-TX |
| Modulation system | Baseband communication |
| Transmission speed | 100 Mbps (100BASE-TX) |
| Duplex mode | Full duplex / Auto MDI |
| Topology | Daisy-chain, tree |
| Transmission medium | Twisted pair cable more over category 5 with shield |
| Transmission range | 100 m or less between nodes (IEEE802.3) |
| Maximum number of slaves | 255 |
| Maximum process data size | Input 5,736 bytes / Output 5,736 bytes |
| Maximum data size of slave | Input 1,434 bytes / Output 1,434 bytes |
| Maximum massage size | 2,048 bytes |
| Communication cycle time | 1 ms or more |
| Process data communication | - PDO Mapping with the CoE protocol <br> - Redundant communication even in a slave malfunction <br> - Stop operation in a slave malfunction |
| SDO communication | CoE <br> - Emergency message server (receive from slave) <br> - SDO request / Response |
| Configuration | - Setting node address by network scan from programming tool (HX-CODESYS) <br> - Display of network information |
| RAS function | - Slave configuration check in the network starting <br> - Read-out of the error information <br> - Trouble shoot information |
| Slave information | - Slave valid / invalid <br> - joining / out-network of a slave (Slave option) |
| Mail box | - CoE (CAN open / CAN application layer over EtherCAT) |

Table 4.4 Programming functional specifications

| Item |  |  | Specification |
| :---: | :---: | :---: | :---: |
| Task Specifications | Number of periodic task |  | 32 |
|  | periodic task priority |  | 0 to 31 |
|  | Number of event task |  | 8 |
|  | System event |  | 25 kinds such as Run / Stop |
|  | Number of status task |  | 8 |
|  | Number of freewheeling task |  | 1 |
| Kinds of POU |  |  | Program, Function block, Function |
| Data Types | Bool |  | BOOL, BYTE, WORD, DWORD, LWORD |
|  | Integer |  | SINT, INT, DINT, LINT |
|  | Unsigned integer |  | USINT, UINT, UDINT, ULINT |
|  | Real |  | REAL, LREAL |
|  | String |  | STRING, WSTRING |
|  | Time |  | TIME (T), LTIME (LT) |
|  | Date / time of day |  | TIME_OF_DAY (TOD), DATE_AND_TIME (DT), DATE (D) |
|  | Others |  | STRUCT, UNION, ARRAY, ENUMERATION, SUBRANGE, REFERENCE, POINTER, ANY, BIT |
|  | Array number of dimensions |  | 3 |
| Instructions | Arithmetic instructions |  | ADD, MUL, SUB, DIV, MOD, MOVE |
|  | Boolean instructions |  | AND, OR, XOR, NOT |
|  | Bit shift |  | SHL, SHR, ROL, ROR |
|  | Selection |  | SEL, MAX, MIN, LIMIT, MUX |
|  | Comparison |  | GT, LT, LE, GE, EQ, NE |
|  | Call |  | CAL |
|  | Type conversion |  | BOOL_TO_INT, WORD_TO_INT, and so on |
|  | Arithmetic Functions |  | ABS, SQRT, LN, LOG, EXP, SIN, COS, TAN, ASIN, ACOS, ATAN, EXPT |
|  | IEC extension |  | DELETE, ISVALIDREF, NEW, QUERYINTERFACE, QUERYPOINTER, AND_THEN, OR_ELSE, TRY, CATCH, FINALLY, ENDTRY, INDEXOF, ADR, BITADR, INDEXOF, SIZEOF, ANDN, ORN, XORN |
| Standard library | Flip-Flop |  | RS, SR |
|  | Counter |  | CTD, CTU, CTUD |
|  | STRING Functions |  | CONCAT, DELETE, FIND, INSERT, LEFT, LEN, MID, REPLACE, RIGHT |
|  | Timer |  | TOF, TON, TP |
|  | Edge Detection |  | F_TRIG, R_TRIG |
|  | Others |  | RTC |
|  | UTIL | BCD Conversions | BCD_TO_INT, INT_TO_BCD |
|  |  | Bit / Byte Functions | EXTRACT, PACK, PUTBIT, UNPACK |
|  |  | Mathematic Auxiliary Functions | DEREVATIVE, INTEGRAM LIN_TRAFO, STATISTICS_INT, STATISTICS_REAL,VARIANCE |
|  |  | PID | PD, PID, PID FIXCYCLE |
|  |  | Signal Generators | BLINK, FREQ_MEASURE, GEN |
|  |  | Function <br> Manipulators | CHARCURVE, RAMP_INT, RAMP_REAL |
|  |  | Analog Value Processing | HYSTERESIS, LIMITALARM |
|  | FILE | Directory | DirClose, DirCreate, DirList, DirOpen, DirRemove, DirRename |
|  |  | File | Close, Copy, Delet, EOF, Flush, GetAttribute, GetPos, GetSize, GetTime, Open, Read, Rename, SetPos, Write |
|  | DTU |  | GetDateAndTime, SetDateAndTime |

### 4.3 Ethernet Port Specifications

HX-CPU standard model has two Ethernet port (ETH1 / 2), and full function model has three
Ethernet port (ETH1 / $2 / 3$ ).


Figure 4.1 HX-CPU Ethernet port
(1) Supported communication function

Table 4.5 Supported function of Ethernet port

| No. | Function | ETH1 | ETH2 | ETH3 |  |
| :---: | :--- | :---: | :---: | :---: | :--- |
| 1 | Gateway | $\checkmark$ | $\checkmark$ | $\checkmark$ | HMI |
| 2 | Global network variable | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| 3 | OPC-UA | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| 4 | Web Visualization | $\checkmark$ | $\checkmark$ | $\checkmark$ | Only full function model |
| 5 | NTP client | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| 6 | FTP server | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |
| 7 | EtherCAT master*1 | $\checkmark$ | $\checkmark$ | - |  |
| 8 | Modbus-TCP | $\checkmark$ | $\checkmark$ | $\checkmark$ |  |

*1 Each ports are available using more than one function at a time except EtherCAT master function.
Do not configure the other function with EtherCAT master function.
(2) Ethernet port specification

Table 4.6 Ethernet port specification

| Item | Specifications |
| :--- | :---: |
| Ethernet Standard | 10BASE-T, 100BASE-TX |
| Transmission mode | AUTO (100 Mbps full, 100 Mbps half, 10 Mbps full, 10 Mbps half) |
| Modulation system | Baseband |
| Topology | Star |
| Transmission medium | Category 5 STP or UTP (STP recommended) |
| Maximum segment length | 100 m or less between nodes |
| Connector | 8-pin modular connector RJ45 |
| Function | EtherCAT master, Modbus-TCP client, Modbus-TCP server, |
|  | CODESYS gateway (TCP/IP, UDP/IP), network variable, TCP/IP, UDP/IP, |
| NTP, FTP server, http*1 |  |

[^5]

| Pin No. | Signal name |
| :---: | :---: |
| 1 | TX+ |
| 2 | TX- |
| 3 | RX+ |
| 4 | NC |
| 5 | NC |
| 6 | RX- |
| 7 | NC |
| 8 | NC |

Figure 4.2 HX-CPU Ethernet port connector pin assigned and signal name
(3) IP address default

Table 4.7 Default IP address of Ethernet port

|  | ETH1 | ETH2 | ETH3 |
| :--- | :---: | :---: | :---: |
| Default IP address | 192.168 .0 .1 | 192.168 .1 .1 | 192.168 .2 .1 |

(4) LED specification (ETH1 to 3)


Figure 4.3 Ethernet communication port LED
Table 4.8 Ethernet port LED specification

| LED | Color | Status | Remarks |
| :--- | :--- | :--- | :--- |
| L/A <br> (Link / Activity) | Green | ON | LINK established |
|  |  | Blinking | During communication |
|  | OFF | Not connected or LINK unestablished |  |
| SPEED |  | 100 Mbps |  |
|  | Yellow | OFF | 10 Mbps |

(5) Available receiving port No.

Table 4.9 Ethernet port No.

| Port No. |  |
| :--- | :--- |
| 1740 to 1743 | CODESYS gateway (UDP/IP) |
| 11740 | CODESYS gateway (TCP/IP) |
| 1217 | Gateway communication (TCP/IP) |
| 1202 | Network variable (UDP/IP) |
| 8080 | CODESYS Webserver (Web Visualization) |
| 4840 | CODESYS OPC-UA server |
| 502 | Modbus-TCP server |
| 20 | FTP server (Transmission data) |
| 21 | FTP server (control) |
| 123 | NTP server (UDP/IP) |
| 4000 to 4007 | CAA.NetBaseService receiving as both UDP/IP and TCP/IP |

*1 The port number is cannot be changed.

### 4.4 USB Port Specifications



Figure 4.4 USB port

## (1) USB-A(Host)

USB-A port is a USB host port that can connect a USB memory. (Connector : Type-A)
It supports the data storage function. To operate the file, creating a user program is required. Enabled devices is the only USB memory. When USB memory is used, please check an environmental condition of the USB memory and use in the rated range of use. The specifications of the USB memory may be changed by a maker and may not work normally. Please use under customer's responsibility.

## (2) USB-B(Device)

USB-B port supports a gateway (Connection with a HX-CODESYS) function. (Connector : Type-miniB) Use a commercial USB cable with ferrite core.

Table 4.10 USB port specification

| Items |  | Specification |
| :---: | :---: | :---: |
| USB-A(Host) | Standard | USB 2.0 High Speed (480 Mbps) |
|  | Connector | A type |
|  | File system | FAT16 / 32, ext2 |
|  | Maximum Volume | 32 GB |
|  | 1 file maximum volume | 2 GB |
|  | Bus power | 500 mA |
|  | Distance | 5 m |
|  | Function | Access USB memory (Data logging, file operation, etc.) |
| USB-B (Device) | Standard | USB 2.0 High Speed (480 Mbps) |
|  | Connector | mini-B type |
|  | Distance | 5 m |
|  | Function | CODESYS gateway |

### 4.5 SD Card Specifications



Figure 4.5 SD card
HX-CPU(Full function model) is supporting a SD card. To operate the file, creating a user program is required. When SD card is used, please check an environmental condition of the SD card and use in the rated range of use. The specifications of the SD card memory may be changed by a maker and may not work normally. Please use under customer's responsibility.

Table 4.11 SD card specification

| Items |  | Specification |
| :--- | :--- | :---: |
| SD card | Standard | SD (up to 2 GB), SDHC (2 to 32 GB) |
|  | Bus interface | Normal speed, High speed |
|  | Bus speed | Maximum 25 MB/s |
|  | Version | 2.00 |
|  | File system | FAT16 / 32, ext2 |
|  | Maximum volume | 32 GB |
|  | 1 file maximum size | 2 GB |
|  | Function | Access SD card (Data logging, File operation, etc.) |

### 4.6 Serial Port Specifications

Full function model has 2-wired RS-485 serial port. It supports Modbus-RTU master, Modbus-RTU slave, and general communication.


Figure 4.6 Serial communication port

Cable side connector


| Pin no. | Signal | Silk | Description |
| :---: | :---: | :---: | :--- |
| 5 | FG | FG | Frame ground |
| 4 | SN | - | Transmitting data- |
| 3 | SP | + | Transmitting data + |
| 2 | SN | - | Transmitting data- |
| 1 | SP | + | Transmitting data + |

Figure 4.7 Serial port Circuit and pin no.


Figure 4.8 RS-485 signal connection diagram
Applicable cable is $0.2 \mathrm{~mm}^{2}-1.25 \mathrm{~mm}^{2}$. (AWG 24 - 16)
Depending on the noise environment, connect the shielded wire to FG terminal. This terminal must not connect to ground.
If the HX-CPU is installed at both ends of the main line, install a termination resistor. (Metal film resistor $120 \Omega, 1 \%, 1 / 4 \mathrm{~W}$ )

### 4.7 Battery Specifications

The battery is not attached. (Option) In the case of the following, use the battery.

- During the 8 days or more of an interruption of the power supply, if the retention of realtime clock data is required
- When HX-CPU is used by more than $50{ }^{\circ} \mathrm{C}$ of environment.

In the case of the following, the battery is not required. User memory and retain memory are retained by nonvolatile memory.

- When the time is synchronous with a NTP server.


## Type : HX-BAT



Figure 4.9 HX-CPU battery (option)

How to install a battery to HX-CPU in the following steps. Be careful about the polarity of a battery.

## How to install the battery

1] Prepare a new battery.(HX-BAT)
2] Replace the battery while the power supply for the basic base is turned on.
3] Remove the consumed lithium battery from the battery case, and remove the connector on the battery side.
4] Insert the connector on the battery side to the CPU module connector.
Insert the red lead wire to + and the black lead wire to - .
5] Fold the excess lead wire and store it in the space for lead wire storage.
(Otherwise, the wire may be severed by the front cover.)
If replacing the battery without power supplied, power off time should be less than 30 minute.


Figure 4.10 Install battery

Refer to the following tables in the lifetime of the battery.
Table 4.12 Battery life

| Battery life (Total time interruption of power supply ) [ Hr ] |  |
| :---: | :---: |
| Guaranteed value (MIN) @ $55^{\circ} \mathrm{C}$ | Actual value (MAX) @25 ${ }^{\circ} \mathrm{C}$ |
| 25,000 | 67,000 |

- When using the battery, enable the battery error detection. Refer to the manual section 2.6 Configuration of HX series application manual (Software).
- The life time of the battery means the total time of interruption of power supply for PAC.
- When ERR LED is displayed flashing or the 7 -segment LED is displayed 71, replace the battery within 7 days.
- The durable life of the battery is 5 years. Even if the battery is not a life, replace it every 5 years.

| $\langle!$ DANGER |
| :--- |
| Precaution when handling the battery. |
| Use HX-BAT for the new battery. Be careful because a false replacement may cause the battery to |
| explode. Do not connect + and - of the battery reversely, do not charge disassemble, heat them, throw |
| them into the fire, short circuit them. |


| CAUTION |
| :--- | :--- |
| Disposal (collection) of the battery |
| Old battery should be individually put in plastic bag of similar (to prevent short circuit) and a disposal |
| company should be requested to dispose of them. |

## Chapter 5 Power Supply, Base, I/O Controller

### 5.1 Power Supply Module


(1) EH-PSA

| Item | Specification |  |
| :--- | :---: | :---: |
| Rated output voltage | 5 V DC | 24 V DC |
| Maximum DC output current | 3.8 A | 0.4 A |
| Efficiency | $65 \%$ or more (Load of $5 \mathrm{~V} \mathrm{3.8} \mathrm{~A} 24 \mathrm{~V} 0.4 \mathrm{~A}$ after conducting electricity for 5 minutes at room |  |
| temperature and humidity) |  |  |


*1 The POWER lamp does not light up if a fuse blows. And the module needs repairs.
User cannot replace the fuse.
(2) EH-PSD

| Item | Specification |
| :---: | :---: |
| Rated output voltage | 5 V DC |
| Maximum DC output current | 3.8 A |
| Efficiency | $70 \%$ or more (Load at 5 V DC $\quad 3.8 \mathrm{~A})$ |
| Input voltage range | 21.6 to 26.4 V DC |
| Input current | 1.25 A or less (with 24 V DC) |
| Input rush current | 50 A or less $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right), 100 \mathrm{~A}$ or less $\left(\mathrm{Ta}=55^{\circ} \mathrm{C}\right)$ |
| Output overcurrent protection | Output short-circuit protection |
| Instantaneous power failure guarantee | 1 ms or more (21.6 to 26.4 V DC) |
| Dielectric withstand voltage | 1 minute at $1,500 \mathrm{~V}$ AC between DC input and FE |
| Insulation resistance | $20 \mathrm{M} \Omega$ or more ( 500 V DC) (Between DC input and FE) |
| Insulation method | Non insulation |


*1 The POWER lamp does not light up if a fuse blows. And the module needs repairs.
User cannot replace the fuse.
(3) EH-PSR

| Item | Specifications |
| :---: | :---: |
| Rated output voltage | 5 V DC |
| Maximum output current | 5.6 A(up to 45 deg ambient temp), 5.0 A(from 45 to 55 deg ) |
| Efficiency | $65 \%$ or more (Load of 5 V 5.6 A after energizing for 5 minutes at room temperature and humidity) |
| Input rated voltage range | 85 to 264 V AC wide range |
| Input current | 1 A or less ( 85 to 264 V AC) |
| Input rush current | 50 A or less $\left(\mathrm{Ta}=25^{\circ} \mathrm{C}\right), 100 \mathrm{~A}$ or less $\left(\mathrm{Ta}=55^{\circ} \mathrm{C}\right)$ |
| Output over current protection | Output short circuit protection |
| Instantaneous power failure guarantee | less than 5 ms ( 85 to 100 V AC ), less than 20 ms ( 100 to 264 V AC ) |
| Input leak current | 3.5 mA or less ( $60 \mathrm{~Hz}, 264 \mathrm{~V} \mathrm{AC}$ ) |
| Dielectric withstand voltage | 1 minute at $1,500 \mathrm{~V} \mathrm{AC}$ between (AC input) and (DC output) <br> 1 minute at 750 V AC between (DC output) and (FE) |
| Insulation resistance | 20 M ohm or more ( 500 V DC)(1) Between AC input and FE <br> (2) Between AC input and DC output |
| Error output | Relay 24 V DC, 0.5 A |


| Terminal configuration |  |  |  |  | Diagram of internal circuit |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | [1] <br> [2] <br> [3] <br> [4] <br> [5] <br> [6] | [1] | Error output | Relay contact for error output |  |  |
|  |  | [2] | Error output |  |  |  |
|  |  | [3] | N.C. | Don't connect any wire. |  |  |
|  |  | [4] | $\begin{gathered} 100 \text { to } 240 \mathrm{~V} \\ \text { AC } \end{gathered}$ | Connect AC power |  |  |
|  |  | [5] | $\begin{gathered} 100 \text { to } 240 \mathrm{~V} \\ \text { AC } \\ \hline \end{gathered}$ |  |  |  |
|  |  | [6] | FE | Connect to ground |  |  |

*1 When fuse was blown, the POWER lamp don't light. Also the module must repair by manufacture. It is impossible to replace the blown flow by customer.
[ Available combination]

| Base • Power <br> supply <br> CPU type | EH-PSA / PSD |  |  | EH-PSR |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | EH-BS8R | EH-BS3A,5A,6A,8A | EH-BS11A | EH-BS8R | EH-BS3A,5A,6A,8A | EH-BS11A |
| HX-CP1S08 / HX-CP1H16 | Not available *1 | Available | Available | Available in redundant <br> power <br> supply <br> system | Restricted use *2 | Restricted use *2 |

*1 EH-PSA/PSD are not mounted in EH-BS8R. And it cannot monitor the operation status.
*2 Redundant power supply module (EH-PSR) is possible to use as large capacity power supply on the standard base. But it can not monitor the operation status.
[ Monitor of operation status ]
Combination of EH-PSR+HX-CP1S08 or EH-PSR + HX-CP1H16, operation status can monitor as input data of slot A.


In EH-BS8R, 8 IO modules are available.
The status of power supply can monitor as input data of slot A.
Input $\%$ IX*. 0 : power supply 0 operation is correct
Input \%IX*. 1 : power supply 1 operation is correct
"*" is variable depending on the mounting situations of the module.

### 5.2 Base Unit

(1) Standard base unit

*1 Not use in HX series.
(2) Redundant base unit

*1 Not use in HX series.

## [ Error output, Operation status ]

Error output and operation status will be change according to occurrence of error and power ON / OFF as follows.


## [ Replacement of fault power supply module ]

In case of fault the power supply module, it is possible to replace while operating another power supply module.

1. To easily replace the fault module, install the circuit breaker to each power line.
2. Please replace the fault module as the power off.

Please attention the electric shock, because another power supply module is operating.
Please design the system of 5 V capacity is used as one power supply module when the redundant power supply.

### 5.3 I/O Controller

| Name and function of each part | Type (Weight) |
| :--- | :--- |
| EH-IOCH2 (Approx $0.14 \mathrm{~kg}(0.31 \mathrm{lb}$.)) |  |

## Chapter 6 Digital I/O Module

### 6.1 Outline

(1) The appearance of 16 -point I/O module
Name and function of each part

| A front view of LED | Indicated contents |
| :---: | :---: |
|  | LED of the number that the I/O signal turns on lights up. |

(2) The appearance of 32 -point I/O module

| Name and function of each part |
| :---: |
|  |  |
|  |  |
|  |  |
|  |  |
|  |
|  |
|  |
|  |
|  |
| 毞 |
|  |
|  |
| Name |
| LED display switch |
| External wiring connector |


| A front view of LED |  |  | Indi |
| :---: | :---: | :---: | :---: |
| 0 | LED of the number that the I/O signal turns on lights up. LED display switch is switched as follows. |  |  |
| $\begin{array}{llll}4 & 5 & 6 & 7 \\ 8 & 9 & 10 & 11 \\ 12 & 13 & 14 & 15\end{array}$ | Switch | $\text { LED }+16$ | Display group |
| DC INPUT EH-XD32 | OFF | No lighting | 0 to 15 |
|  | ON | Lighting | 16 to 31 |

(3) The appearance of 64-point I/O module
Name and function of each part

| A front view of LED | Indicated contents |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | LED of the number that the I/O signal turns on lights up. LED display switch is switched as follows. |  |  |  |  |
| $\begin{array}{\|lllll\|} \hline 0 & 1 & 2 & 3 & 16 \\ 4 & 5 & 6 & 7 & 1 \end{array}$ | SW1 | SW2 | LED 16 | LED 32 | Display group |
| 8 9 10 11 32 <br> 12 13 14 15  <br> 15     | OFF | OFF | Non- lighting | Non-lighting | 0 to 15 |
| DC INPUT EH-XD64 | ON | OFF | Lighting | Non-lighting | 16 to 31 |
|  | OFF | ON | Non-lighting | Lighting | 32 to 47 |
|  | ON | ON | Lighting | Lighting | 48 to 63 |

### 6.2 Specifications

(1) EH-XD8

| Specification | EH-XD8 |
| :---: | :---: |
| Input type | DC input (common use to sink and source) |
| Number of input points | 8 points |
| Input voltage | 24 V DC (19.2 to 30 V DC) |
| Input current | Approx. 6.9 mA |
| Input impedance | Approx. $3.5 \mathrm{k} \Omega$ |
| Operating voltage | 15 V or more |
|  | 5 V or less |
| Input response time | 5 ms or less |
| time $\quad$ OFF response | 5 ms or less |
| Insulation system | Photo-coupler insulation |
| Input display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of input points / commons | 8 points / 1 common |
| Internal current consumption | Approx. 30 mA |


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 |  |
|  | [6] | 5 |  |
|  | [7] | 6 |  |
|  | [8] | 7 |  |
|  | [9] | C |  |
|  | [10] | N.C. |  |
|  | [11] | N.C. |  |
|  | [12] | N.C. |  |
|  | [13] | N.C. |  |
|  | [14] | N.C. |  |
|  | [15] | N.C. |  |
|  | [16] | N.C. |  |
|  | [17] | N.C. |  |
|  | [18] | C |  |

(2) EH-XD16

| Specification |  | EH-XD16 |
| :---: | :---: | :---: |
| Input type |  | DC input (common use to sink and source) |
| Number of input points |  | 16 points |
| Input voltage |  | 24 V DC (19.2 to 30 V DC) |
| Input current |  | Approx. 4.0 mA |
| Input impedance |  | Approx. $5.9 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 5 ms or less |
|  | OFF response | 5 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED display (green) |
| External connection |  | Removable type screw terminal block (M3) |
| Number of input points / commons |  | 16 points / 1 common (common terminal is 2 points.) |
| Internal current consumption |  | Approx. 50 mA |


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 |  |
|  | [6] | 5 |  |
|  | [7] | 6 |  |
|  | [8] | 7 |  |
|  | [9] | C |  |
|  | [10] | 8 |  |
|  | [11] | 9 |  |
|  | [12] | 10 |  |
|  | [13] | 11 |  |
|  | [14] | 12 |  |
|  | [15] | 13 |  |
|  | [16] | 14 |  |
|  | [17] | 15 |  |
|  | [18] | C |  |

(3) EH-XDL16

| Specification | EH-XDL16 |
| :---: | :---: |
| Input type | DC input (common use to sink and source) |
| Number of input points | 16 points |
| Input voltage | 24 V DC (19.2 to 30 V DC) |
| Input current | Approx. 4.0 mA |
| Input impedance | Approx. $5.9 \mathrm{k} \Omega$ |
| Operating ON voltage | 15 V or more |
| voltage OFF voltage | 5 V or less |
| Input response ON response | 16 ms or less |
| time $\quad$ OFF response | 16 ms or less |
| Insulation system | Photo-coupler insulation |
| Input display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of input points / commons | 16 points / 1 common (Common terminal is 2 points.) |
| Internal current consumption | Approx. 50 mA |


| Terminal configuration | No. | Signal name | Diagram of internal circuit |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |  |  |
|  | [2] | 1 |  |  |  |
|  | [3] | 2 |  |  |  |
|  | [4] | 3 |  |  |  |
|  | [5] | 4 |  |  |  |
|  | [6] | 5 |  |  |  |
|  | [7] | 6 |  |  |  |
|  | [8] | 7 |  |  |  |
|  | [9] | C |  |  |  |
|  | [10] | 8 |  |  |  |
|  | [11] | 9 |  |  |  |
|  | [12] | 10 |  |  |  |
|  | [13] | 11 |  |  |  |
|  | [14] | 12 |  |  |  |
|  | [15] | 13 |  |  |  |
|  | [16] | 14 |  |  |  |
|  | [17] | 15 |  |  |  |
|  | [18] | C |  |  |  |

(4) EH-XDS16

| Specification |  | EH-XDS16 |
| :---: | :---: | :---: |
| Input type |  | DC input (common use to sink and source) |
| Number of input points |  | 16 points |
| Input voltage |  | 24 V DC (19.2 to 30 V DC) |
| Input current |  | Approx. 4.0 mA |
| Input impedance |  | Approx. $5.9 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 1 ms or less |
|  | OFF response | 1 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED display (green) |
| External connection |  | Removable type screw terminal block (M3) |
| Number of input points / commons |  | 16 points / 1 common (Common terminal is 2 points.) |
| Internal current consumption |  | Approx. 50 mA |


| Terminal configuration | No. | Signal name | Diagram of internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
| [1] (5) | [4] | 3 |  |
| [2] (5) [10] | [5] | 4 |  |
| (3) [11] | [6] | 5 |  |
| (5] (5) [12] | [7] | 6 |  |
| ${ }^{\text {[4] (5) [1] }}$ | [8] | 7 |  |
| ${ }^{\text {[5] }}$ (5) 10 | [9] | C |  |
| [6] (5) cb | [10] | 8 |  |
| [7] (5) [5] [15] | [11] | 9 |  |
| [81 (5) [16] | [12] | 10 |  |
| (9] (5) [17] | [13] | 11 |  |
| $\begin{aligned} & \text { Screw for (5) [18] } \\ & \text { fixing } \end{aligned}$ | [14] | 12 |  |
|  | [15] | 13 |  |
|  | [16] | 14 |  |
|  | [17] | 15 |  |
|  | [18] | C |  |

(5) EH-XA16

| Specification | EH-XA16 |
| :---: | :---: |
| Input type | AC input |
| Number of input points | 16 points |
| Input voltage | 100 to 120 V AC ( 85 to 132 V AC ) |
| Input current | 4.8 to $7.6 \mathrm{~mA} \mathrm{(100} \mathrm{~V} \mathrm{AC} \mathrm{/} 50 \mathrm{~Hz}$ ) |
| Input impedance | Approx. $16 \mathrm{k} \Omega(50 \mathrm{~Hz})$ / Approx. $13 \mathrm{k} \Omega(60 \mathrm{~Hz})$ |
| Operating voltage | 79 V AC or more |
|  | 20 V AC or less |
| Input response time | 15 ms or less |
| time $\quad$ OFF response | 25 ms or less |
| Insulation system | Photo-coupler insulation |
| Input display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of input points / commons | 16 points / 1 common (Common terminal is 2 points.) |
| Internal current consumption | Approx. 50 mA |


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 |  |
|  | [6] | 5 |  |
|  | [7] | 6 |  |
|  | [8] | 7 |  |
|  | [9] | C |  |
|  | [10] | 8 |  |
|  | [11] | 9 |  |
|  | [12] | 10 |  |
|  | [13] | 11 |  |
|  | [14] | 12 |  |
|  | [15] | 13 |  |
|  | [16] | 14 |  |
|  | [17] | 15 |  |
|  | [18] | C |  |

(6) EH-XAH16


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
| [1] (5) | [4] | 3 |  |
| [2] (5) [10] | [5] | 4 |  |
| (3) [11] | [6] | 5 |  |
| (5] (5) [12] | [7] | 6 |  |
| ${ }^{\text {[4] (5) [1] }}$ | [8] | 7 |  |
| ${ }^{\text {[5] }}$ (5) ${ }^{\text {c }}$ [14] | [9] | C |  |
| [6] (5) [6) | [10] | 8 |  |
| $\begin{array}{ll} {[7]} & (5) \\ \hline 15) \\ \hline 150 \end{array}$ | [11] | 9 |  |
| [8] (5) [16] | [12] | 10 |  |
| (9] (5) [17] | [13] | 11 |  |
| Screw for (5) [18] | [14] | 12 |  |
| fixing | [15] | 13 |  |
|  | [16] | 14 |  |
|  | [17] | 15 |  |
|  | [18] | C |  |

(7) EH-XD32

| Specification |  | EH-XD32 |
| :---: | :---: | :---: |
| Input type |  | DC input (Common use to sink and source) |
| Number of input points |  | 32 points |
| Input voltage |  | $24 \mathrm{~V} \mathrm{DC} \mathrm{(19.2} \mathrm{to} \mathrm{30.0} \mathrm{~V} \mathrm{DC)}$ |
| Input current |  | Approx. 4.3 mA |
| Input impedance |  | Approx. $5.6 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 5 ms or less |
|  | OFF response | 5 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED connector (green) |
| External connection |  | Connector |
| Number of input points / commons |  | 32 points / 1 common (Common terminal is 4 points.) |
| Internal current consumption |  | Approx. 60 mA |


(8) EH-XDL32

| Specification |  | EH-XDL32 |
| :---: | :---: | :---: |
| Input type |  | DC input (Common use to sink and source) |
| Number of input points |  | 32 points |
| Input voltage |  | 24 V DC (19.2 to 30.0 V DC) |
| Input current |  | Approx. 4.3 mA |
| Input impedance |  | Approx. $5.6 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 16 ms or less |
|  | OFF response | 16 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED connector (green) |
| External connection |  | Connector |
| Number of input points / commons |  | 32 points / 1 common (Common terminal is 4 points.) |
| Internal current consumption |  | Approx. 60 mA |


(9) EH-XDS32


(10) EH-XD32E

| Specification |  | EH-XD32E |
| :---: | :---: | :---: |
| Input type |  | DC input (Common use to sink and source) |
| Number of input points |  | 32 points |
| Input voltage |  | 24 V DC (19.2 to 30.0 V DC) |
| Input current |  | Approx. 4.3 mA |
| Input impedance |  | Approx. $5.6 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 1 ms or less |
|  | OFF response | 1 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED display (green) |
| External connection |  | Spring type terminal block (removable type) |
| Number of input points / commons |  | 8 points / 1 common (Common terminal is 2 points each. 4 system common is independent.) |
| Internal current consumption |  | Approx. 60 mA |


(11) EH-XDL32E

| Specification |  | EH-XDL32E |
| :---: | :---: | :---: |
| Input type |  | DC input (Common use to sink and source) |
| Number of input points |  | 32 points |
| Input voltage |  | 24 V DC (19.2 to 30 V DC) |
| Input current |  | Approx. 4.3 mA |
| Input impedance |  | Approx. $5.6 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 16 ms or less |
|  | OFF response | 16 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED display (green) |
| External connection |  | Spring type terminal block (removable type) |
| Number of input points / commons |  | 8 points / 1 common (Common terminal is 2 points each. 4 system common is independent.) |
| Internal current consumption |  | Approx. 60 mA |


(12) EH-XD32H

| Item |  | EH-XD32H | PIM-DM, PIH-DM (for replacing) |
| :---: | :---: | :---: | :---: |
| Series |  | HX / EH-150 | EM / EM- II, H-200 / 250 / 252B / 252C |
| Input specification |  | DC input (Common use to source) |  |
| Number of input points |  | 32 points |  |
| Input voltage |  | 24 V DC (21.6 to 26.0 V DC) |  |
| Input current (24V DC) |  | Approx. 4.1 mA | Approx. 4.7 mA |
| Input impedance |  | Approx. $5.9 \mathrm{k} \Omega$ | Approx. $5.1 \mathrm{k} \Omega$ |
| Operating <br> voltage | ON voltage | 19 V or more |  |
|  | OFF voltage | 7 V or less |  |
| Input response time | ON response | 4 ms or less |  |
|  | OFF response | 4 ms or less |  |
| Insulation system |  | Photo-coupler insulation |  |
| Number of input points / commons |  | 32 points / 1 common (common terminal is $4 * 1$ ) |  |
| Input display |  | LED (green) *2 | LED (red) |
| polarity |  | Common terminal (+) |  |
| External connection |  | Connector (50 pins) |  |
| Internal current consumption |  | Approx. 60 mA | Approx. 20 mA |

*1 Common terminals are connected internally.
*2 There are 16 points for each LED display. The displayed group is toggled using a switch.

| Specification of external wiring connector |  |  |  | Wire |
| :---: | :---: | :---: | :---: | :---: |
| Product name | Manufacturer | Product No. | Connection method |  |
| Plug connector | Hirose Electric Co., Ltd. | DX30-50P | Untie crimping | AWG\#30 |
|  |  | DX30A-50P |  | AWG\#28 |
|  |  | DX31-50P | Crimping | AWG\#30 |
|  |  | DX31A-50P |  | AWG\#28 |
|  |  | DX40-50P | Soldering | - |
| Die cast cover |  | DX-50-CV1 | - | - |


*1 EH-XD32H has a turned connector to a 32-point I/O module for EM / H-200 series. Connect an external wiring cable rotating 180 degrees around when replacing the module. (You cannot connect the cable in wrong direction due to the structure for avoiding improper connection.)

(13) EH-XD64

| Specification |  | EH-XD64 |
| :---: | :---: | :---: |
| Input type |  | DC input (Common used to sink and source) |
| Number of input points |  | 64 points |
| Input voltage |  | $24 \mathrm{~V} \mathrm{DC} \mathrm{(19.2} \mathrm{to} \mathrm{30.0} \mathrm{~V} \mathrm{DC)}$ |
| Input current |  | Approx. 4.3 mA |
| Input impedance |  | Approx. $5.6 \mathrm{k} \Omega$ |
| Operating voltage | ON voltage | 15 V or more |
|  | OFF voltage | 5 V or less |
| Input response time | ON response | 1 ms or less |
|  | OFF response | 1 ms or less |
| Insulation system |  | Photo-coupler insulation |
| Input display |  | LED display (green)*1 |
| External connection |  | Connector |
| Number of input points / commons |  | 32 points / 1 common (Common terminal is 4 points each. 2 system common is independent. $* 2$ ) |
| Internal current consumption |  | Approx. 80 mA |

*1 There are 16 points of LED indication. The indication group is switched by toggle switch.
*2 2 groups $(\mathrm{C} 1, \mathrm{C} 2)$ are separated. 4 common terminals in one group are connected internally.

| Terminal configuration |  | No. | Signal name | No. | Signal name | No. | Signal name | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\underbrace{[41]}{ }^{[61]}$ | $\begin{array}{cc} \mathrm{C} & \mathrm{C} \\ \mathrm{~N} & \mathrm{~N} \\ 2 & 1 \\ & \\ & {[21]} \end{array}-$ | [41] | 32 | [61] | 48 | [1] | 0 | [21] | 16 | $0 \rightarrow \square$ |
|  |  | [42] | 33 | [62] | 49 | [2] | 1 | [22] | 17 |  |
|  |  | [43] | 34 | [63] | 50 | [3] | 2 | [23] | 18 |  |
|  |  | [44] | 35 | [64] | 51 | [4] | 3 | [24] | 19 |  |
|  | $\left\|\begin{array}{ll} 0 & 0 \\ 0 & 0 \\ 0 & 0 \end{array}\right\|[1]$ | [45] | 36 | [65] | 52 | [5] | 4 | [25] | 20 | Intemal ciruit |
|  | [46] |  | 37 | [66] | 53 | [6] | 5 | [26] | 21 |  |
|  |  | [47] | 38 | [67] | 54 | [7] | 6 | [27] | 22 |  |
|  |  | [48] | 39 | [68] | 55 | [8] | 7 | [28] | 23 |  |
|  | [10 | [49] | C2 | [69] | C2 | [9] | C1 | [29] | C1 | Deratigy digaram |
|  |  | [50] | 40 | [70] | 56 | [10] | 8 | [30] | 24 |  |
|  |  | [51] | 41 | [71] | 57 | [11] | 9 | [31] | 25 |  |
|  | (100 | [52] | 42 | [72] | 58 | [12] | 10 | [32] | 26 | - |
|  |  | [53] | 43 | [73] | 59 | [13] | 11 | [33] | 27 | - - |
|  | \|ll|l|l|l| | [54] | 44 | [74] | 60 | [14] | 12 | [34] | 28 | - |
|  | [10] | [55] | 45 | [75] | 61 | [15] | 13 | [35] | 29 | ${ }^{26.4 \mathrm{VDC}}$ |
|  | (1) [20] | [56] | 46 | [76] | 62 | [16] | 14 | [36] | 30 |  |
| $\bigcirc$ |  | [57] | 47 | [77] | 63 | [17] | 15 | [37] | 31 |  |
|  | $\bigcirc$ | [58] | C2 | [78] | C2 | [18] | C1 | [38] | C1 | Ambient temperature $\left({ }^{\circ} \mathrm{C}\right)$ |
|  |  | [59] | N.C. | [79] | N.C. | [19] | N.C. | [39] | N.C. |  |
|  |  | [60] | N.C. | [80] | N.C. | [20] | N.C. | [40] | N.C. |  |
| Applicable connectors <br> - A 120 mm (4.73 in.) space is required for the front of the module. Please choose the installing location (space) accordingly. <br> - Use a shield cable and always use a class D grounding. |  |  |  |  |  |  |  |  |  |  |
| Manufacturer | Fujitsu <br> Takamizawa | Solder type |  |  |  | Socket: FCN-361J040-AU, Cover: FCN-360C040-E |  |  |  |  |
|  |  | Crimp type |  |  |  | Housing: FCN-363J040, Contact: FCN-363J-AU |  |  |  |  |
|  |  | Pressure-displacement type |  |  |  | FCN-367J040-AU/F |  |  |  |  |
|  | AMP | Solder type |  |  |  | 1473381-1 |  |  |  |  |

(14) EH-YT8

| Specification | EH-YT8 |
| :---: | :---: |
| Output specification | Transistor output (sink type) |
| Number of output points | 8 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%,-15 \%)$ |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit <br>  1 | $0.5 \mathrm{~A}(0.3 \mathrm{~A} \mathrm{MFG} \mathrm{NO.02F**} \mathrm{or} \mathrm{before)*1}$ |
| current 1 common | 2.4 A |
| Output $\quad \mathrm{OFF} \rightarrow \mathrm{ON}$ | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 8 points / 1 common |
| Surge removal circuit | Diode |
| Fuse*2 | $4 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(30 \mathrm{~mA}$ at the maximum) |
| Internal current consumption | Approx. 30 mA |
| Short-circuit protection function | None |

*1 MFG NO. ( $02 \mathrm{~F}^{* *}$ ) indicates products of June 2002.
*2 The module needs to be repaired in case the short-circuited load causes the fuse to blown out.
But, users cannot replace the fuse.

| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 |  |
|  | [6] | 5 |  |
|  | [7] | 6 |  |
|  | [8] | 7 |  |
|  | [9] | C |  |
|  | [10] | N.C. |  |
|  | [11] | N.C. |  |
|  | [12] | N.C. |  |
|  | [13] | N.C. |  |
|  | [14] | N.C. |  |
|  | [15] | N.C. |  |
|  | [16] | N.C. |  |
|  | [17] | N.C. |  |
|  | [18] | S |  |

(15)

EH-YT16

| Specification | EH-YT16 |
| :---: | :---: |
| Output specification | Transistor output (sink type) |
| Number of output prints | 16 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC (+10 \%, -15 \%) |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | $0.5 \mathrm{~A}(0.3$ A MFG NO.02F** or before)*1 |
| current 1 common <br> 0  | 4 A |
| Output $\quad$ OFF $\rightarrow$ ON | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 16 points / 1 common |
| Surge removal circuit | Diode |
| Fuse*2 | $8 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(30 \mathrm{~mA}$ at the maximum) |
| Internal current consumption | Approx. 50 mA |
| Short-circuit protection function | None |

* 1 MFG NO. ( $02 \mathrm{~F}^{* *}$ ) indicates products of June 2002.
*2 The module needs to be repaired in case the short-circuited load causes the fuse to blown out.
But, users cannot replace the fuse.

(16) EH-YTP8

| Specification | EH-YTP8 |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 8 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%$, $15 \%$ ) |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | $0.5 \mathrm{~A}(0.3 \mathrm{~A} \mathrm{MFG} \mathrm{NO.02F**} \mathrm{or} \mathrm{before)*1}$ |
| current 1 common <br> 0  | 2.4 A |
| Output $\quad \mathrm{OFF} \rightarrow \mathrm{ON}$ | 0.3 ms or less |
| response time $\quad$ ON $\rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green) |
| External connection | Removal type screw terminal block (M3) |
| Number of output points / commons | 8 points / 1 common |
| Surge removal circuit | Diode |
| Fuse*2 | $4 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(30 \mathrm{~mA}$ at the maximum) |
| Internal current consumption | Approx. 30 mA |
| Short-circuit protection function | None |

* 1 MFG NO. ( $02 \mathrm{~F}^{* *}$ ) indicates products of June 2002.
*2 The module needs to be repaired in case the short-circuited load causes the fuse to blown-out.
But, users cannot replace the fuse.

| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 | $\square^{\text {LED }}$ |
|  | [6] | 5 | (4) |
|  | [7] | 6 | $\begin{array}{l\|l\|l\|l} 0 & & \\ \hline 1 \end{array}$ |
|  | [8] | 7 | Internal |
|  | [9] | C | circuit |
|  | [10] | N.C. |  |
|  | [11] | N.C. <br> N.C. |  |
|  | [13] | N.C. | $\square \mathrm{O}$ |
|  | [14] | N.C. |  |
|  | [15] | N.C. |  |
|  | [16] | N.C. |  |
|  | [17] | N.C. |  |
|  | [18] | S |  |

## (17) EH-YTP16

| Specification | EH-YTP16 |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 16 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC (+10 \%, -15 \%) |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit <br>  1 | 0.5 A (0.3 A MFG NO.02F** or before*1) |
| current 1 common | 4 A |
| Output $\quad$ OFF $\rightarrow$ ON | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 16 points / 1 common |
| Surge removal circuit | Diode |
| Fuse*2 | $8 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(30 \mathrm{~mA}$ at the maximum) |
| Internal current consumption | Approx. 50 mA |
| Short-circuit protection function | None |

* 1 MFG NO. ( $02 \mathrm{~F}^{* *}$ ) indicates products of June 2002.
*2 The module needs to be repaired in case the short-circuited load causes the fuse to blown out.
But, users cannot replace the fuse.

| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 | LED |
|  | [6] | 5 | 4 - + |
|  | [7] | 6 | $\square$ |
|  | [8] | 7 | Internal $\square$ - |
|  | [9] | C | circuit |
|  | [10] | 8 | + |
|  | [12] | 10 | O- |
|  | [13] | 11 |  |
|  | [14] | 12 |  |
|  | [15] | 13 |  |
|  | [16] | 14 |  |
|  | [17] | 15 |  |
|  | [18] | S |  |

(18) EH-YTP16S

| Specification | EH-YTP16S |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 16 points |
| Raged load voltage | $12 / 24 \mathrm{~V}$ DC (+10 \%, -15 \%) |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | 0.8 A |
| current 10 common | 5 A |
| Output | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow \mathrm{OFF}$ | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 16 points / 1 common |
| Surge removal circuit | Built-in |
| Fuse | None |
| External power supply <br> (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(30 \mathrm{~mA}$ at the maximum) |
| Internal current consumption | Approx. 50 mA |
| Short-circuit protection function | Available |


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 0 |  |
|  | [2] | 1 |  |
|  | [3] | 2 |  |
|  | [4] | 3 |  |
|  | [5] | 4 | LED |
|  | [6] | 5 | 4 - |
|  | [7] | 6 | * |
|  | [8] | 7 | Internal |
|  | [9] | C | circuit |
|  | [10] | 8 |  |
|  | [11] | 9 | $\square 15$ |
|  | [12] | 10 | $\square$ O-■- |
|  | [13] | 11 | $\rightarrow-\mathrm{S}$ |
|  | [14] | 12 |  |
|  | [15] | 13 |  |
|  | [16] | 14 |  |
|  | [17] | 15 |  |
|  | [18] | S |  |

(19) EH-YR8B

| Specification | EH-YR8B |
| :---: | :---: |
| Output specification | Relay output |
| Number of output points | 8 points |
| Rated load voltage | $100 / 240 \mathrm{~V} \mathrm{AC}, 24 \mathrm{~V}$ DC |
| Minimum switching current | $1 \mathrm{~mA}(5 \mathrm{~V} \mathrm{DC})$, except after a great current switching |
| Leak current | None |
| Maximum load 1 circuit | 2 A |
| current 1 common | 2 A |
| Output | 10 ms or less |
| response time $\quad$ ON $\rightarrow$ OFF | 10 ms or less |
| Insulation system | Relay insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 1 point / 1 common (Each channel is independent.) |
| Surge removal circuit | Varistor (Varistor voltage 423 to 517 V ) |
| Fuse | None |
| External power supply | Not used |
| Internal current consumption (5V DC) | Approx. 220 mA |


(20)

EH-YR12

| Specification | EH-YR12 |
| :---: | :---: |
| Output specification | Relay output |
| Number of output points | 12 points |
| Rated load voltage | 100 / 240 V AC, 24 V DC |
| Minimum switching current | 1 mA ( 5 V DC ), except a great current switching |
| Leak current | None |
| Maximum load 1 circuit | 2 A |
| current 1 common | 5 A |
| Output OFF $\rightarrow$ ON | 10 ms or less |
| response time $\quad \mathrm{ON} \rightarrow \mathrm{OFF}$ | 10 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 12 points / 1 common (Common terminal is 2 points.) |
| Surge removal circuit | None |
| Fuse | None |
| External power supply | $24 \mathrm{~V} \mathrm{DC} \mathrm{( }+10 \%,-15 \%)(70 \mathrm{~mA}$ at the maximum) |
| Internal current consumption (5V DC) | Approx. 40 mA |


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: |
|  | [1] | 24V DC+ |  |
|  | [2] | N.C. |  |
|  | [3] | 0 |  |
|  | [4] | 1 | 24 V DC+ |
|  | [5] | 2 | LED |
|  | [6] | 3 | 4 - |
|  | [7] | 4 | $\left.\square \triangle \bigcirc\right\|^{0}{ }_{0}{ }^{0}$ |
|  | [8] | 5 | $\square$ - |
|  | [9] | C | Internal |
|  | [10] | 24V DC- | $\underset{\text { internal }}{\text { circuit }}$ |
|  | [11] | N.C. | circuit |
|  | [12] | 6 |  |
|  | [13] | 7 | - |
|  | [14] | 8 |  |
|  | [15] | 9 | 24 V DC- |
|  | [16] | 10 |  |
|  | [17] | 11 |  |
|  | [18] | C |  |

(21) EH-YR16 / EH-YR16D

| Item |  | Specification |  |
| :---: | :---: | :---: | :---: |
| Type |  | EH-YR16 | EH-YR16D |
| Output specification |  | Relay output |  |
| Rated load voltage |  | 100 / 240 V AC, 24 V DC |  |
| Minimum switching current |  | 1 mA |  |
| Leak current |  | None |  |
| Maximum load current | 1 circuit | 2 A |  |
|  | 1 common | 8 A (Ambient temperature $40^{\circ} \mathrm{C}$ ) <br> See the below derating table | 4 A (Ambient temperature $40^{\circ} \mathrm{C}$ ) <br> See the below derating table |
| Output response time | $\mathrm{OFF} \rightarrow \mathrm{ON}$ | 10 ms or less |  |
|  | $\mathrm{ON} \rightarrow$ OFF | 10 ms or less |  |
| Number of output points |  | 16 points / module |  |
| Number of common points |  | 16 points / 1 common (Common terminal is 2)*1 | 8 points / 1 common (Common terminal is 2)*2 |
| Surge removal circuit |  | There is no Surge removal circuit and Fuse internal of this module. Please Install proper device in the each output and / or the common line. |  |
| Fuse |  |  |  |
| Insulation system |  | Relay insulation |  |
| Output display |  | LED (green) |  |
| External connection |  | Removable type screw terminal block (M3) |  |
| Internal current consumption (5 V DC) |  | Approximately 430 mA |  |

*1 The common terminals are connected internally.
*2 The common terminals are separated.

| Terminal configuration |  | No. | Signal name |  | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | YR16 | YR16D |  |
|  |  | [1] | 0 | 0 |  |
|  |  | [2] | 1 | 1 |  |
|  |  | [3] | 2 | 2 |  |
|  |  | [4] | 3 | 3 |  |
|  |  | [5] | 4 | 4 |  |
|  |  | [6] | 5 | 5 |  |
|  |  | [7] | 6 | 6 |  |
|  |  | [8] | 7 | 7 |  |
|  |  | [9] | C | C0 |  |
|  |  | [10] | 8 | 8 |  |
|  |  | [11] | 9 | 9 |  |
|  |  | [12] | 10 | 10 |  |
|  |  | [13] | 11 | 11 |  |
|  |  | [14] | 12 | 12 |  |
|  |  | [15] | 13 | 13 |  |
|  |  | [16] | 14 | 14 |  |
|  |  | [17] | 15 | 15 |  |
|  |  | [18] | C | C1 |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |
|  |  |  |  |  |  |

(22)

EH-YS16

| Specification | EH-YS16 |
| :---: | :---: |
| Output specification | Triac output |
| Number of output points | 16 points |
| Rated load voltage | $100 / 240 \mathrm{~V}$ AC (85 to 250 V AC) |
| Minimum switching current | 10 mA |
| Leak current | 2 mA or less |
| Maximum load 1 circuit | 0.3 A |
| current 1 common | 4 A (Ambient temperature $45^{\circ} \mathrm{C}$ ), see the following derating table |
| Output | 1 ms or less |
| $\text { response time } \quad \mathrm{ON} \rightarrow \mathrm{OFF}$ | $1 \mathrm{~ms}+1 / 2$ cycle or less |
| Insulation system | Photo-coupler triac insulation |
| Output display | LED display (green) |
| External connection | Removable type screw terminal block (M3) |
| Number of output points / commons | 16 pints / 1 common |
| Surge removal circuit | Varistor |
| Fuse | 6.3 A (Mounting a fuse to external is necessary.) |
| Internal current consumption | Approx. 250 mA |



## (23) EH-YT32

| Specification | EH-YT32 |
| :---: | :---: |
| Output specification | Transistor output (sink type) |
| Number of output points | 32 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%,-15 \%)$ |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | 0.2 A |
| current 1 1 common | $6.4 \mathrm{~A}^{*} 1$ |
| Output | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green)*2 |
| External connection | Connector |
| Number of output points / commons | 32 points / 1 common (Common terminal is 4 points.) |
| Surge removal circuit | Diode |
| Fuse*3 | $10 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC} \mathrm{(+10} \mathrm{\%}, \mathrm{-15} \mathrm{\%)} \mathrm{( } 30 \mathrm{~mA}$ at the maximum) |
| Internal current consumption (5V DC) | Approx. 90 mA |
| Short-circuit protection function | Available*4 |

*1 Total current of 4 common pins.
For each common pin of a connector, please make common current which is sent into one common pin into 3A or less.
*2 There are 16 points for each LED display. The display group is switched using a switch.
*3 The module needs to be repaired in case a fuse is blown out. But, users cannot replace the fuse.
*4 MFG No.01E** or later are applied.(MFG No.01E** indicates products of May 2001.)

| Termin configura |  | No. | Signal name | No. | Signa name |  | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | [1] | 0 | [21] | 16 | module. Please choose the installing location (space) accordingly. <br> Socket: FCN-361J040-AU, Cover: FCN-360C040-E <br> Housing: FCN-363J040, Contact: FCN-363J-AU <br> FN-367J040-AU/F <br> 473381-1 |  |
|  |  | [2] | 1 | [22] | 17 |  |  |
|  |  | [3] | 2 | [23] | 18 |  |  |
|  |  | [4] | 3 | [24] | 19 |  |  |
|  |  | [5] | 4 | [25] | 20 |  |  |
|  |  | [6] | 5 | [26] | 21 |  |  |
|  |  | [7] | 6 | [27] | 22 |  |  |
|  |  | [8] | 7 | [28] | 23 |  |  |
|  |  | [9] | C | [29] | C |  |  |
|  |  | [10] | S | [30] | S |  |  |
|  |  | [11] | - 8 | [31] | 24 |  |  |
|  |  | [12] | - 9 | [32] | 25 |  |  |
|  |  | [13] | 10 | [33] | 26 |  |  |
|  |  | [14] | 11 | [34] | 27 |  |  |
|  |  | [15] | 12 | [35] | 28 |  |  |
|  |  | [16] | 13 | [36] | 39 |  |  |
|  |  | [17] | 14 | [37] | 30 |  |  |
|  |  | [18] | 15 | [38] | 31 |  |  |
|  |  | [19] | C | [39] | C |  |  |
|  |  | [20] | S | [40] | S |  |  |
| Applicable connector <br> - A 120 mm (4.73in.) space is required for the front of the module. Please choose the installing location (space) accordingly. <br> - Use a shield cable and always use a class D grounding. |  |  |  |  |  |  |  |
| Manufacturer | Fujitsu Takamizawa |  | Solder type |  |  |  |  |
|  |  |  | Crimp type |  |  |  |  |
|  |  |  | Pressure-displacement type |  |  |  |  |
|  | AMP |  | Solder type |  |  |  |  |

## (24) EH-YTP32

| Specification | EH-YTP32 |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 32 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%,-15 \%)$ |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | 0.2 A |
| current 1 common <br> 年  | $6.4 \mathrm{~A}^{*} 1$ |
| Output | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow \mathrm{OFF}$ | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green)*2 |
| External connection | Connector |
| Number of output points / commons | 32 points / 1 common (Common terminal is 4 points.) |
| Surge removal circuit | Diode |
| Fuse*3 | $10 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC} \mathrm{( }+10 \%$, $-15 \%$ ) ( 30 mA at the maximum) |
| Internal current consumption (5V DC) | Approx. 90 mA |
| Short-circuit protection function | Available*4 |

*1 Total current of 4 common pins.
For each common pin of a connector, please make common current which is sent into one common pin into 3 A or less.
*2 There are 16 points for each LED display. The display group is switched using a switch.
*3 The module needs to be repaired in case a fuse is blown out. But, users cannot replace.
*4 MFG No.01E** or later are applied.(MFG No.01E** indicates products of May 2001.)


## (25) EH-YT32E

| Specification |  | EH-YT32E |
| :---: | :---: | :---: |
| Output specification |  | Transistor output (si |
| Number of output points |  | 32 points |
| Rated load voltage |  | $12 / 24 \mathrm{~V}$ DC $++10 \%$ |
| Minimum switching current |  | 1 mA |
| Leak current |  | 0.1 mA |
| Maximum load current | 1 circuit | 0.2 A |
|  | 1 common | 1 A |
| Output response time | OFF $\rightarrow$ ON | 0.3 ms or les |
|  | $\mathrm{ON} \rightarrow \mathrm{OFF}$ | 1 ms or less |
| Insulation system |  | Photo-coupler insu |
| Output display |  | LED display (gree |
| External connection |  | Spring type termina |
| Number of output points / commons |  | 8 points / 1 common (Common t |
| Surge removal circuit |  | Diode |
| Fuse*2 |  | $10 \mathrm{~A} / 1$ comm |
| External power supply <br> (for supplying power to S-terminal) |  | $12 / 24 \mathrm{~V}$ DC (+10 \%, -15 \%) (30 |
| Internal current consumption (5V DC) |  | Approx. 90 m |
| Short-circuit protection function |  | Available |

*1 There are 16 points for each LED display. The display group is switched using a switch.
*2 The module needs to be repaired in case a fuse is blown out. But, users cannot replace the fuse.

| Terminal configuration | No. | Signal name | No. | Signal name | Diagram of Internal circuit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| [1] | [1] | 0 | [21] | 16 |  |
|  | [2] | 1 | [22] | 17 |  |
|  | [3] | 2 | [23] | 18 |  |
|  | [4] | 3 | [24] | 19 |  |
|  | [5] | 4 | [25] | 20 |  |
|  | [6] | 5 | [26] | 21 |  |
|  | [7] | 6 | [27] | 22 |  |
|  | [8] | 7 | [28] | 23 |  |
|  | [9] | C1 | [29] | C3 |  |
|  | [10] | S1 | [30] | S3 | Internal |
|  | [11] | 8 | [31] | 24 | circuit |
|  | [12] | 9 | [32] | 25 |  |
|  | [13] | 10 | [33] | 26 | $\mathrm{C} 1$ |
|  | [14] | 11 | [34] | 27 | -1-ـ |
|  | [15] | 12 | [35] | 28 |  |
|  | [16] | 13 | [36] | 29 |  |
|  | [17] | 14 | [37] | 30 |  |
|  | [18] | 15 | [38] | 31 |  |
|  | [19] | C2 | [39] | C4 |  |
|  | [20] | S2 | [40] | S4 |  |
| Applicable connector |  |  |  | Applicable cable |  |
| Manufacturer: Weidmuller Type: B2L3.5/20AUOR Product No.: 175736 |  |  |  | $0.5 \mathrm{~mm}^{2}-1.0 \mathrm{~mm}^{2}$ (shared at a twisted pair cable and a single core cable.) AWG 28-18 <br> A crimp terminal cannot be used. |  |

## (26) EH-YTP32E

| Specification | EH-YTP32E |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 32 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%$, $-15 \%$ ) |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load current | 0.2 A |
|  | 1 A |
| Output response time | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow \mathrm{OFF}$ | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green)*1 |
| External connection | Spring type terminal block |
| Number of output points / commons | 8 points / 1 common (Common terminal is 4 points.) |
| Surge removal circuit | Diode |
| Fuse*2 | $10 \mathrm{~A} / 1$ common |
| External power supply <br> (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(30 \mathrm{~mA}$ at the maximum) |
| $\begin{aligned} & \text { Internal current consumption } \\ & (5 \mathrm{~V} \mathrm{DC}) \end{aligned}$ | Approx. 90 mA |
| Short-circuit protection function | Available |

*1 There are 16 points for each LED display. The display group is switched using a switch.
*2 The module needs to be repaired in case a fuse is blown out. But, users cannot replace the fuse.

(27) EH-YT32H

| Item |  | EH-YT32H | POM-TM, POH-TM (for replacing) |
| :---: | :---: | :---: | :---: |
| Series |  | HX / EH-150 | EM / EM-II, H-200 / 250 / 252 |
| Output specification |  | Transistor output (sink type) |  |
| Number of output points |  | 32 points |  |
| Rated load voltage |  | $5 / 12$ / 24 V DC ( 5 to 27 V DC) |  |
| Minimum switching current |  | 1 mA |  |
| Leak current |  | 0.05 mA or less |  |
| Maximum output saturation voltage |  | 1 V or less |  |
| Maximum <br> load current | 1 point | 0.1 A |  |
|  | 1 common | 0.8 A |  |
| Output response time | $\mathrm{OFF} \rightarrow \mathrm{ON}$ | 1 ms or less |  |
|  | $\mathrm{ON} \rightarrow \mathrm{OFF}$ | 1 ms or less |  |
| Insulation method |  | Photo-coupler insulation |  |
| Output display |  | LED (green)*2 | LED (red) |
| External connection |  | Connector (50 pins) |  |
| Number of common points |  | 8 points / 1 common |  |
| Surge removal circuit |  | Diode (Connecting case of the S terminal) |  |
| Fuse*1 |  | $2 \mathrm{~A} / 1$ common | $1.5 \mathrm{~A} / 1$ common |
| External power supply*3 <br> (For supplying power to the S terminal) |  | $\begin{gathered} 5 \text { to } 27 \mathrm{~V} \mathrm{DC} \\ \text { (maximum } 100 \mathrm{~mA} \text { ) } \end{gathered}$ |  |
| Internal current consumption (5 V DC) |  | Approx. 90 mA | Approx. 70 mA |
| Short-circuit protection |  | None |  |

*1 The module needs to be repaired in case a load short causes a blown fuse. Further more, it is not allowed for user to replace a fuse as safety reason.
*2 There are 16 points for each LED display. The display group is toggled using a switch. And, LED display is renewed by refresh processing.
*3 It is necessary to supply $12 / 24 \mathrm{~V}$ DC to the S terminals.

| Specification of external wiring connector |  |  |  | Wire |
| :---: | :---: | :---: | :---: | :---: |
| Product name | Manufacturer | Product No. | Connection method |  |
| Plug connector | Hirose Electric Co., Ltd. | DX30-50P | Untie crimping | AWG\#30 |
|  |  | DX30A-50P |  | AWG\#28 |
|  |  | DX31-50P | Crimping | AWG\#30 |
|  |  | DX31A-50P |  | AWG\#28 |
|  |  | DX40-50P | Soldering | - |
| Die cast cover |  | DX-50-CV1 | - | - |


*1 EH-XD32H has a turned connector to a 32 -point I/O module for EM / H-200 series. Connect an external wiring cable rotating 180 degrees around when replacing the module. (You cannot connect the cable in wrong direction due to the structure for avoiding improper connection.)


## (28) EH-YT64

| Specification | EH-YTP64 |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 64 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%,-15 \%)$ |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | 0.1 A |
| current 1 common <br> 0  | 3.2 A |
| Output | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green)*1 |
| External connection | Connector |
| Number of output points / commons | 32 points / 1 common (Common terminal is 4 points each.) |
| Surge removal circuit | Diode |
| Fuse*2 | $5 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(100 \mathrm{~mA}$ at the maximum) |
| Internal current consumption (5V DC) | Approx. 120 mA |
| Short-circuit protection function | Available |

*1 There are 16 points for each LED display. The display group is switched using a switch.
*2 The module needs to be repaired in case a fuse is blown out. But, users cannot replace the fuse.


## (29) EH-YTP64

| Specification | EH-YTP64 |
| :---: | :---: |
| Output specification | Transistor output (source type) |
| Number of output points | 64 points |
| Rated load voltage | $12 / 24 \mathrm{~V}$ DC ( $+10 \%,-15 \%)$ |
| Minimum switching current | 1 mA |
| Leak current | 0.1 mA |
| Maximum load 1 circuit | 0.1 A |
| current 1 common | 3.2 A |
| Output | 0.3 ms or less |
| response time $\quad \mathrm{ON} \rightarrow$ OFF | 1 ms or less |
| Insulation system | Photo-coupler insulation |
| Output display | LED display (green)*1 |
| External connection | Connector |
| Number of output points / commons | 32 points / 1 common (Common terminal is 4 points each.) |
| Surge removal circuit | Diode |
| Fuse*2 | $5 \mathrm{~A} / 1$ common |
| External power supply (for supplying power to S-terminal) | $12 / 24 \mathrm{~V} \mathrm{DC}(+10 \%,-15 \%)(100 \mathrm{~mA}$ at the maximum) |
| Internal current consumption (5V DC) | Approx. 120 mA |
| Short-circuit protection function | Available |

*1 There are 16 points for each LED display. The display group is switched using a switch.
*2 The module needs to be repaired in case a fuse is blown out. But, users cannot replace the fuse.


## Chapter 7 Analog I/O Module, Resistance Temperature Detector Input Module, Thermocouple Input Module

7.1 12-bit Analog I/O Module

| Name and function of each part |  | Type (Weight) | $\begin{aligned} & \text { EH-AX44 } \\ & \text { (Approx. } 0.18 \mathrm{~kg}(0.41 \mathrm{lb} .)) \end{aligned}$ |
| :---: | :---: | :---: | :---: |
|  |  |  | EH-AX8V, AX8H <br> (Approx. $0.18 \mathrm{~kg}(0.41 \mathrm{lb})$. |
|  |  |  | EH-AX8I, AX8IO <br> (Approx. 0.18 kg ( 0.41 lb.$)$ ) |
|  |  |  | EH-AY22 <br> (Approx. 0.18 kg ( 0.41 lb.$)$ ) |
|  |  |  | EH-AY2H <br> (Approx. $0.18 \mathrm{~kg}(0.41 \mathrm{lb})$. |
|  |  |  | EH-AY4V, AY4H <br> (Approx. 0.18 kg ( 0.41 lb.$)$ ) |
|  |  |  | EH-AY4I <br> (Approx. 0.18 kg ( 0.41 lb.$)$ ) |
|  |  | Dimensions (mm (in.)) |  |
| Terminal |  |  |  |
| Item | Description |  |  |
| Terminal block | This is a terminal block for connecting the I/O signals. The terminal block is removable. Screws for the terminal block are M3 screw. Use a crimp terminal fitting to the screw diameter. The maximum thickness of the cable should be $0.75 \mathrm{~mm}^{2}$. (Use a $0.5 \mathrm{~mm}^{2}$ cable when attaching two crimp terminals to the same terminal.) <br> Recommended crimp terminal is shown below. |  |  |
| Terminal block cover | This is a covert for installing on the terminal block. |  |  |

(1) EH-AX44

| Specification |  | EH-AX44 |
| :---: | :---: | :---: |
| Current range |  | 4 to 20 mA |
| Voltage range |  | 0 to 10 V DC |
| Number of channels | Current | 4 (0 to 3 channels) |
|  | Voltage | 4 (4 to 7 channels) |
| Resolution |  | 12 bits |
| Conversion time |  | 5 ms or less |
| Overall accuracy |  | $\pm 1 \%$ or less (of full-scale value) |
| Input impedance | Current | Approx. $100 \Omega$ |
|  | Voltage | Approx. $100 \mathrm{k} \Omega$ |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 400 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m ( 65.62 ft .) or less) |
| Internal current consumption |  | Approx. 100 mA |


(2) EH-AX8V

| Specification |  | EH-AX8V |
| :---: | :---: | :---: |
| Current range |  | - |
| Voltage range |  | 0 to 10 V DC |
| Number of channels | Current | - |
|  | Voltage | 8 (0 to 7 channels) |
| Resolution |  | 12 bits |
| Conversion time |  | 5 ms or less |
| Overall accuracy |  | $\pm 1 \%$ or less (of full-scale value) |
| Input impedance | Current | - |
|  | Voltage | Approx. $100 \mathrm{k} \Omega$ |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | $24 \mathrm{~V} \mathrm{DC} \mathrm{(+20} \mathrm{\%}, \mathrm{-15} \mathrm{\%)} \mathrm{Approx}$.150 mA (Approx. 400 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption |  | Approx. 100 mA |


(3) EH-AX8H

| Specification |  | EH-AX8H |
| :---: | :---: | :---: |
| Current range |  | - |
| Voltage range |  | +/-10 V DC |
| Number of channels | Current | - |
|  | Voltage | 8 (0 to 7 channels) |
| Resolution |  | 12 bits |
| Conversion time |  | 5 ms or less |
| Overall accuracy |  | $\pm 1 \%$ or less (of full-scale value) |
| Input impedance | Current | - |
|  | Voltage | Approx. $100 \mathrm{k} \Omega$ |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 400 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption |  | Approx. 100 mA |


(4) EH-AX8I

| Specification | EH-AX8I |  |
| :--- | :--- | :---: |
| Current range | 4 to 20 mA |  |
| Voltage range | - |  |
| Number of channels | Current | 8 (0 to 7 channels) |
|  | Voltage | - |
| Resolution | 12 bits |  |
| Conversion time | Current | $\pm 1 \%$ or less (of full-scale value) |
| Overall accuracy | Approx. $100 \Omega$ |  |
| Input impedance |  |  |
| Insulation system | Channel and Internal circuit | - |
|  | Between channels | Photo-coupler insulation |
| External connection | No insulation |  |
| External power supply | Removable type screw terminal block (M3) |  |
| External wiring | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 400 mA at power ON) |  |
| Internal current consumption | 2-core shield cable (20 m or less) |  |


(5) EH-AX8IO

| Specification | EH-AX8IO |  |
| :--- | :--- | :---: |
| Current range | 0 to 22 mA |  |
| Voltage range | - |  |
| Number of channels | Current | 8 (0 to 7 channels $)$ |
|  | Voltage | - |
| Resolution | 12 bits |  |
| Conversion time | Current | 5 ms or less |
| Overall accuracy | Voltage | Approx. $100 \Omega$ |
| Input impedance $\Omega$ |  |  |
|  | Channel and Internal circuit | - |
| Insulation system | Photo-coupler insulation |  |
| External connection | No insulation |  |
| External power supply | Removable type screw terminal block (M3) |  |
| External wiring | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 400 mA at power ON) |  |
| Internal current consumption | 2-core shield cable (20 m or less) |  |


(6) EH-AY22

| Specification | EH-AY22 |  |
| :--- | :--- | :---: |
| Current range | 4 to 20 mA |  |
| Voltage range | 0 to 10 V DC |  |
| Number of channels | Current | $2(2$ to 3 channels $)$ |
|  | Voltage | 2 (0 to 1 channels $)$ |
| Resolution | 12 bits |  |
| Conversion time | 5 ms or less |  |
| Overall accuracy | Current | $\pm 1 \%$ or less (of full-scale value $)$ |
| External <br> load resistance | Voltage | 0 to $500 \Omega$ |
| Insulation system | Channel and Internal circuit | $10 \mathrm{k} \Omega$ or more |
|  | Between channels | Photo-coupler insulation |
| External connection | No insulation |  |
| External power supply | Removable type screw terminal block (M3) |  |
| External wiring | 24 V DC (+20 \%, -15 \%) Approx. $150 \mathrm{~mA} \mathrm{(Approx} .\mathrm{500} \mathrm{mA} \mathrm{at} \mathrm{power} \mathrm{ON)}$ |  |
| Internal current consumption | 2-core shield cable (20 m or less) |  |


(7) EH-AY2H

| Specification |  | EH-AY2H |
| :---: | :---: | :---: |
| Current range |  | - |
| Voltage range |  | + / - 10 V DC |
| Number of channels | Current | - |
|  | Voltage | 2 (0 to 1 channels) |
| Resolution |  | 12 bits |
| Conversion time |  | 5 ms or less |
| Overall accuracy |  | $\pm 1 \%$ or less (of full-scale value) |
| External load resistance | Current | - |
|  | Voltage | $10 \mathrm{k} \Omega$ or more |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 500 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption |  | Approx. 100 mA |


(8) EH-AY4I

| Specification | EH-AY4I |  |
| :--- | :--- | :---: |
| Current range | 4 to 20 mA |  |
| Voltage range | - |  |
| Number of channels | Current | 4 (0 to 3 channels) |
|  | Voltage | - |
| Resolution | 12 bits |  |
| Conversion time | Current | 5 ms or less |
| Overall accuracy | Voltage | $\pm 1 \%$ or less (of full-scale value) |
| External <br> load resistance | Channel and Internal circuit | - |
| Insulation system | Petween channels | Photo-coupler insulation |
| External connection | No insulation |  |
| External power supply | Removable type screw terminal block (M3) |  |
| External wiring | 24 V DC (+20 \%,-15 \%) Approx. $150 \mathrm{~mA} \mathrm{(Approx} .\mathrm{500} \mathrm{mA} \mathrm{at} \mathrm{power} \mathrm{ON)}$ |  |
| Internal current consumption | 2-core shield cable (20 m or less) |  |


(9) EH-AY4V

| Specification |  | EH-AY4V |
| :--- | :--- | :---: |
| Current range | - |  |
| Voltage range | 0 to 10 V DC |  |
| Number of channels | Current | - |
|  | Voltage | 4 (0 to 3 channels) |
| Resolution | 12 bits |  |
| Conversion time | 5 ms or less |  |
| Overall accuracy | $\pm 1 \%$ or less (of full-scale value) |  |
| External load resistance | Current | - |
|  | Voltage | $10 \mathrm{k} \Omega$ or more |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 500 A at power ON) |  |
| External wiring | 2-core shield cable (20 m or less) |  |
| Internal current consumption | Approx. 100 mA |  |


(10)

EH-AY4H

| Specification |  | EH-AY4H |
| :---: | :---: | :---: |
| Current range |  | - |
| Voltage range |  | +/-10 V DC |
| Number of channels | Current | - |
|  | Voltage | 4 (0 to 3 channels) |
| Resolution |  | 12 bits |
| Conversion time |  | 5 ms or less |
| Overall accuracy |  | $\pm 1 \%$ or less (of full-scale value) |
| External loadresistance | Current | - |
|  | Voltage | $10 \mathrm{k} \Omega$ or more |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC (+20 \%, -15 \%) Approx. 150 mA (Approx. 500 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption |  | Approx. 100 mA |



### 7.2 14-bit Analog I/O Module



| Front view of LED | Indicating contents |
| :---: | :---: |
| $\begin{array}{\|llll\|} \hline \text { OK } & & & \\ 0 & 1 & 2 & 3 \\ 4 & 5 & 6 & 7 \\ \hline \text { ANAROG IN } & \\ \hline \end{array}$ | OK: Light is on when the module is normal. <br> 0 to 7: Light is off when normal. <br> [EH-AXH8M] <br> LED corresponding to the channel flashes if the input becomes 2 mA or less when the range is 4 to 22 mA . (when selecting 0.002 mA resolution.) <br> [EH-AYH8M] <br> LED corresponding to the channel flashes if the data outside the output range is set. |

## (1) EH-AXH8M

| Specification |  | EH-AXH8M |
| :---: | :---: | :---: |
| Current range |  | 0 to $22 \mathrm{~mA} / 4$ to 22 mA |
| Voltage range |  | 0 to 10 V DC / -10 to 10 V DC |
| Number of channels | Current | 8 channels (can switch current / voltage in 4-ch unit) |
|  | Voltage |  |
| Resolution | Current | 0.002 mA or $1 / 16,384$ (14 bits) |
|  | Voltage | 1 mV or $1 / 16,384$ (14 bits) |
| Conversion time |  | $8.9 \mathrm{~ms} / 8$ channels |
| Overall accuracy | Current | $\pm 0.8 \%$ or less (of full-scale value) |
|  | Voltage | $\pm 0.5 \%$ or less (of full-scale value) |
| Linear error |  | $\pm 0.1 \%$ or less (of full-scale value) |
| Input filter | Valid | Approx. 90 ms ( $90 \%$ arriving time after the step input) |
|  | Invalid | 18 ms or less ( $90 \%$ arriving time after the step input) |
| Input impedance | Current | $249 \Omega$ |
|  | Voltage | Differential $200 \mathrm{k} \Omega$ |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC (+20 \%, -15 \%) Approx. 40 mA (Approx. 300 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption |  | Approx. 70 mA |


| Terminal configuration | No. | Signal name | Diagram of Internal circuit |  |
| :---: | :---: | :---: | :---: | :---: |
|  | [1] | $0+$ |  |  |
|  | [2] | $1+$ |  |  |
|  | [3] | $2+$ |  |  |
|  | [4] | $3+$ |  |  |
|  | [5] | $4+$ |  |  |
|  | [6] | $5+$ |  |  |
|  | [7] | $6+$ |  |  |
|  | [8] | $7+$ |  |  |
|  | [9] | 24 V DC+ |  |  |
|  | [10] | 0 - |  |  |
|  | [11] | 1 - |  |  |
|  | [12] | 2 - |  |  |
|  | [13] | 3 - |  |  |
|  | [14] | 4 - |  |  |
|  | [15] | 5 - |  |  |
|  | [16] | 6 - |  |  |
|  | [17] | 7 - |  |  |
|  | [18] | 24 V DC- |  |  |


[Setups shown in the white font on black background are initial factory setting:]

* In this module, be sure to perform the above setup before use. Further, be sure to turn off the power in setting up. Otherwise, the setups are invalid. And when the input range is switched with the function selectable switch, be sure to set the current / voltage switch to the corresponding range accordingly.
(2) EH-AYH8M

| Specification |  | EH-AYH8M |
| :---: | :---: | :---: |
| Current range |  | 0 to $22 \mathrm{~mA} / 4$ to 22 mA |
| Voltage range |  | 0 to 10 V DC |
| Number <br> channels | Current | 8 channels (can switch current and voltage in 4-ch unit) |
|  | Voltage |  |
| Resolution | Current | 0.002 mA or $1 / 16,384$ (14 bits) |
|  | Voltage | 1 mV or $1 / 16,384$ (14 bits) |
| Conversion time |  | $8.9 \mathrm{~ms} / 8$ channels |
| Overall accuracy | Current | $\pm 0.8 \%$ or less (of full-scale value) |
|  | Voltage | $\pm 0.8 \%$ or less (of full-scale value) |
| Linear error |  | $\pm 0.2 \%$ or less (of full-scale value) (range from 0 to 10 V and from 0.05 to 22 mA ) |
| Output filter | Valid | Approx. 200 ms or less ( $90 \%$ arriving time after setting) |
|  | Invalid | Approx. 18 ms or less ( $90 \%$ arriving time after setting) |
| Output impedance | Current | $400 \Omega$ or less |
|  | Voltage | $10 \mathrm{k} \Omega$ or less |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC (+20 \%, -15\%) Approx. 150 mA (Approx. 400 mA at power ON) |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption |  | Approx. 70 mA |



[Setups shown in the white font on black background are initial factory setting:]

* In this module, be sure to perform the above setups before use. Further, be sure to turn of the power in setting up. Otherwise, the setups are invalid. And when the input range is switched with the function selectable switch, be sure to set the current/voltage switch to the corresponding range accordingly.


### 7.3 Isolated Analog I/O Module

Name and function of each part

| Front view of LED | Indicating contents |
| :---: | :---: |
| EH-AXG5M <br> OK HS 16 b 12 b  <br> 0 1 2 3 <br> 4    <br> ANALOG IN    | OK: Light is on when the module is normal. <br> HS : Light up when this module is high speed conversion mode. <br> Light is turned off when this module is high accuracy mode. <br> 16 b : Light up when this module is high resolution mode. <br> 12 b : Light up when this module is 12 bit resolution mode. <br> 0 to 7: Light is off when normal. LED corresponding to the channel flashes if the input becomes 2 mA or less when the range is 4 to 22 mA .(when selecting high resolution mode.) |
| EH-AYG4M | OK: Light is on when the module is normal. <br> 16b: Light up when this module is high resolution mode. <br> 12 b : Light up when this module is 12 bit resolution mode. <br> 0 to 3 : In case of current range, LED of each channel is blinking when wire breaking (when current mode) or out of data range was detected. |

## (1) EH-AXG5M

| Specification |  | EH-AXG5M |
| :---: | :---: | :---: |
| Current range |  | 0 to $22 \mathrm{~mA} / 4$ to 22 mA |
| Voltage range |  | 0 to 10 V DC / -10 to 10 V DC |
| Number of channels | Current | 5 channels (can switch current / voltage) |
|  | Voltage |  |
| Resolution | Current | 0 to $64,000,-7,111$ to 32,000 or 0 to $4,095(20 \mathrm{~mA})$ |
|  | Voltage | 0 to 64,000 or 0 to 4,095 |
| Conversion time |  | 8 ms or $0.25 \mathrm{~ms} / 5$ channels |
| Overall accuracy ${ }^{7,,^{2}}$ | At $25^{\circ} \mathrm{C}$ | -0.05 to $+0.05 \%$ or less (of full-scale value) |
|  | Temperature coefficient | -80 to $+80 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ or less (of full-scale value) |
| Absolute maximum ratings |  | Voltage: -15 to 15 V Current : $30 \mathrm{~mA}^{* 3}$ |
| Input filter |  | 1 kHz |
| Input impedance | Current | $249 \Omega$ |
|  | Voltage | Differential $200 \mathrm{k} \Omega$ |
| Insulation system | Channel and Internal circuit | Transformer ( $1,000 \mathrm{~V}$ AC, 1 minutes) |
|  | Between channels | Transformer (1,000 V DC, 1 minutes) |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | None |
| External wiring |  | 2-core shield cable ( 20 m or less) |
| Internal current consumption (5 V DC) |  | Approx. 300 mA |

*1 Example) Accuracy at $40^{\circ} \mathrm{C}$ is calculated as follows,
$0.05 \%$ (accuracy at $25^{\circ} \mathrm{C}$ ) $+0.008 \% /{ }^{\circ} \mathrm{C}\left(\right.$ Temperature coefficient) $* 15{ }^{\circ} \mathrm{C}$ (difference form $25^{\circ} \mathrm{C}$ ) $=0.17 \%$
*2 The accuracy indicates the value after 15 minutes from the power-up. The value may become a lightly higher immediately after the power-up.
*3 It is the momentary current value that does not destroy the resistance in the module.


(2) EH-AYG4M

| Specification |  | EH-AYG4M |
| :---: | :---: | :---: |
| Current range |  | 0 to $22 \mathrm{~mA} / 4$ to 22 mA |
| Voltage range |  | 0 to 10 V DC / -10 to 10 V DC |
| Number of channels | Current | 4 channels (can switch current / voltage) |
|  | Voltage |  |
| Resolution | Current | 0 to $64,000,-7,111$ to 32,000 or 0 to 4,095 ( 20 mA ) |
|  | Voltage | 0 to 64,000 or 0 to 4,095 |
| Conversion time |  | $0.25 \mathrm{~ms} / 4$ channels |
| Overall accuracy*1,*2 | At $25^{\circ} \mathrm{C}$ | -0.1 to $+0.1 \%$ or less (of full-scale value) |
|  | Temperature coefficient | -80 to $+80 \mathrm{ppm} /{ }^{\circ} \mathrm{C}$ or less (of full-scale value) |
| Absolute maximum ratings |  | Voltage: -15 to 15 V Current 24 mA |
| Output impedance | Current | More than $1 \mathrm{k} \Omega$ |
|  | Voltage | Less than $600 \Omega$ |
| Insulation system | Channel and Internal circuit | Transformer ( $1,000 \mathrm{~V} \mathrm{AC}$,1 minutes) |
|  | Between channels | Transformer (1,000 V DC, 1 minutes) |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | None |
| External wiring |  | 2 -core shield cable ( 20 m or less) |
| Internal current consumption (5 V DC) *3 |  | Max. 730 mA |

*1 Example) Accuracy at $40^{\circ} \mathrm{C}$ is calculated as follows,
$0.1 \%$ (accuracy at $25^{\circ} \mathrm{C}$ ) $+0.008 \% /{ }^{\circ} \mathrm{C}$ (Temperature coefficient) $* 15^{\circ} \mathrm{C}$ (difference form $\left.25^{\circ} \mathrm{C}\right)=0.22 \%$
*2 The accuracy indicates the value after 15 minutes from the power-up. The value may become a lightly higher immediately after the power-up.
*3 480 mA ( All channel output 10 V voltage output with $10 \mathrm{k} \Omega$ impedance )
600 mA ( All channel output 10 V voltage output with $1 \mathrm{k} \Omega$ impedance ) or (All channel output 11 mA current output )
730 mA ( All channel output 22 mA current output )


[Setups shown in the white font on black background are initial factory setting:]

[^6]
### 7.4 Resistance Temperature Detector Input Module

(1) Resistance temperature detector input
Same and function of each part

| Specification |  | EH-PT4 |
| :---: | :---: | :---: |
| Applicable resistance thermometer |  | Platinum resistance thermometer Pt100 (JIS C 1604-1989) / Pt1000 |
| Temperature conversion data |  | Signed 15 bits |
| Accuracy*1 | $\begin{array}{\|l} \hline-20 \text { to } 40^{\circ} \mathrm{C} \\ (\mathrm{Pt} 100) \\ \hline \end{array}$ | $\pm 0.1{ }^{\circ} \mathrm{C} @ 25^{\circ} \mathrm{C}\left( \pm 0.5{ }^{\circ} \mathrm{C} @ 0\right.$ to $\left.55{ }^{\circ} \mathrm{C}\right)$ |
|  | $\begin{aligned} & -50 \text { to } 400^{\circ} \mathrm{C} \\ & (\mathrm{Pt} 100) \end{aligned}$ | $\pm 0.6{ }^{\circ} \mathrm{C} @ 25^{\circ} \mathrm{C}\left( \pm 3^{\circ} \mathrm{C} @ 0\right.$ to $\left.55^{\circ} \mathrm{C}\right)$ |
|  | $\begin{array}{\|l} -50 \text { to } 400^{\circ} \mathrm{C} \\ \text { (Pt1000) } \end{array}$ | $\pm 0.8{ }^{\circ} \mathrm{C} @ 25^{\circ} \mathrm{C}\left( \pm 6^{\circ} \mathrm{C} @ 0\right.$ to $\left.55^{\circ} \mathrm{C}\right)$ |
| Measuring temperature range |  | -20 to $40{ }^{\circ} \mathrm{C} /-50$ to $400{ }^{\circ} \mathrm{C}(2 \mathrm{~mA}$ constant current system) |
| Input channel |  | 4 channels |
| Conversion time |  | Approx. 1s / 4 channels |
| Insulation system | Channel and Internal circuit | Photo-coupler insulation |
|  | Between channels | No insulation |
| External connection |  | Removable type screw terminal block (M3) |
| External power supply |  | 24 V DC |
| External wiring |  | Shield cable |
| Unused terminal processing |  | Temperature conversion data is H7FFF |
| External wiring resistance |  | Total resistance of 4 channels $400 \Omega$ at the maximum |
| Additional function |  | Linearization |
| Error detection*2 |  | Temperature conversion data is H7FFF at -51 ${ }^{\circ} \mathrm{C}$ or less, or $410^{\circ} \mathrm{C}$ or more |
| Wire breakage processing*2 |  | Temperature conversion data is H7FFF |
| Internal current consumption |  | Approx. 160 mA |

*1 The accuracy indicates the value after 10 minutes from the power-up. The value may become a lightly higher immediately after the power-up. Also, check the resistance thermometer in advance because there is error in the resistance thermometer.
*2 Indicates the current terminal wiring in open state. When an open error occurs in the voltage terminal wiring, the data is indefinite.

(2) 6 ch.(3-wire) / 8 ch.(2-wire) resistance temperature detector input


| Name |  |  | Function |
| :---: | :---: | :---: | :---: |
| Mode setting DIP switch | These switches are to set wiring type, temperature range, input filter, conversion time, temperature unit, EH-PT4 compatible mode and sensor type. |  |  |
|  | No. | Setting | Function |
|  | SW1-1 | 1 | Wiring type |
|  |  | OFF | 3-wire |
|  |  | ON | 2-wire |
|  | SW1-2 | 2 | Temperature range |
|  |  | OFF | -200 to $850{ }^{\circ} \mathrm{C},{ }^{\circ} \mathrm{F}$ conversion: -328 to $1,562{ }^{\circ} \mathrm{F}$, EH-PT4 compatible:- 60 to $410^{\circ} \mathrm{C}$ |
|  |  | ON | -40 to $60^{\circ} \mathrm{C},{ }^{\circ} \mathrm{F}$ conversion: -328 to $1,562{ }^{\circ} \mathrm{F}$, EH-PT4 compatible: -25 to $45^{\circ} \mathrm{C}$ |
|  | SW1-3 | 3 | Input filter |
|  |  | OFF | None |
|  |  | ON | 16 times moving average |
|  | SW1-4 | 4 | Conversion time |
|  |  | OFF | 1.6 s |
|  |  | ON | 0.5 s |
|  | SW1-5 | 5 | Temperature unit |
|  |  | OFF | ${ }^{\circ} \mathrm{C}$ |
|  |  | ON | ${ }^{\circ} \mathrm{F}$ |
|  | SW1-6 | 6 | EH-PT4 compatible mode |
|  |  | OFF | Disable |
|  |  | ON | Enable |
|  | SW1-7 | 7 | For system use |
|  |  | OFF | Set always OFF |
|  | SW1-8 | 8 | For system use |
|  |  | OFF | Set always OFF |
|  | SW2 | 9 | Sensor type |
|  |  | OFF | Pt1000 |
|  |  | ON | Pt100 |


| Item |  | Specification |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Type |  | EH-RTD8 |  |  |
| Supported RTD type |  | PT100 / PT1000 (3-wire or 2-wire) |  |  |
| Number of channel <br> Selectable by the DIP switch |  | 6 (3-wire) or 8 (2-wire) |  |  |
| Temperature range <br> Selectable by the DIP switch |  | -200 to $850{ }^{\circ} \mathrm{C}$ or -40 to $60^{\circ} \mathrm{C}$ |  |  |
| Resolution <br> Selectable by the DIP switch |  | ${ }^{\circ} \mathrm{C}$ conversion | ${ }^{\circ} \mathrm{F}$ conversion | PT4 compatible |
|  |  | -200 to $850{ }^{\circ} \mathrm{C}: 0.1{ }^{\circ} \mathrm{C}$ | -328 to $1562{ }^{\circ} \mathrm{F}: 0.1{ }^{\circ} \mathrm{F}$ | -60 to $410^{\circ} \mathrm{C}: 15$ bits |
|  |  | -40 to $60^{\circ} \mathrm{C}: 0.02^{\circ} \mathrm{C}$ | - | -25 to $45{ }^{\circ} \mathrm{C}$ : 15 bits |
| Conversion time <br> Selectable by the DIP switch |  | 1.6 s (all channels) or 0.5 s (all channels) |  |  |
| Accuracy *1 | Standard accuracy ( $25{ }^{\circ} \mathrm{C}$ ) | Max. $\pm 0.5^{\circ} \mathrm{C}$ (measured temperature under $380^{\circ} \mathrm{C}$ ) <br> Max. $\pm 0.8^{\circ} \mathrm{C}$ (measured temperature over $380^{\circ} \mathrm{C}$ ) |  |  |
|  | Temperature coefficient | $\pm 0.01 \% /{ }^{\circ} \mathrm{C}(\mathrm{FS}) * 2 \quad\left( \pm 0.1{ }^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{C}\right)$ |  |  |
| Measurement current |  | 0.18 mA |  |  |
| Diagnostic error (Wire breaking detection) | LED | LED blinking at error channel |  |  |
|  | Conversion value |  | H7FFF |  |
| Input filter Selectable by the DIP switch |  | None or moving average 16 times |  |  |
| Warm-up time *3 |  | 1 minute |  |  |
| Isolation | Channel to internal circuit | Photo coupler |  |  |
|  | ween channels | Not isolated |  |  |
| External connector |  | Removable terminal (M3) |  |  |
| Internal current consumption (5 V DC) |  | Max. 300 mA |  |  |
| External power supply |  | None |  |  |
| Wiring |  | Twisted shield cable, wiring resistance Max. $5 \Omega$ (Max. 100m of 22 AWG) |  |  |

*1 Example : Measuring under $380^{\circ} \mathrm{C}$ in ambient temperature $35^{\circ} \mathrm{C}$.(under noise-free environment)
$0.5^{\circ} \mathrm{C}$ (standard accuracy) $+0.1^{\circ} \mathrm{C} /{ }^{\circ} \mathrm{C}$ (temperature coefficient) $\times 10$ (difference to $\left.25^{\circ} \mathrm{C}\right)= \pm 1.5^{\circ} \mathrm{C}$
*2 Full scale is -200 to $850^{\circ} \mathrm{C}$.
*3 It is the time for data to be stable after power on.

| Terminal layout | No. | Signal name |  | Internal circuit |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | 2-wire | 3-wire |  |  |  |
|  | [1] | A0 | A0 |  |  |  |
|  | [2] | A1 | b0 |  |  |  |
|  | [3] | B2 - B3 | B1 |  |  |  |
|  | [4] | A4 | A2 |  |  |  |
|  | [5] | A5 | b2 |  |  |  |
|  | [6] | B6.B7 | B3 |  |  |  |
|  | [7] | NC | A4 |  |  |  |
|  | [8] | NC | b4 |  |  |  |
|  | [9] | NC | B5 |  |  |  |
|  | [10] | B0•B1 | B0 |  |  |  |
|  | [11] | A2 | A1 |  |  |  |
|  | [12] | A3 | b1 |  |  |  |
|  | [13] | B4•B5 | B2 |  |  |  |
|  | [14] | A6 | A3 |  |  |  |
|  | [15] | A7 | b3 |  |  |  |
|  | [16] | NC | B4 |  |  |  |
|  | [17] | NC | A5 |  |  |  |
|  | [18] | NC | b5 |  |  |  |

### 7.5 Thermocouple Input Module

Name and function of each part

| Front view of LED |  |
| :--- | :--- |
| OK    <br> 0 1 2 3 <br> 4 5 6 7 <br> ANAROG IN EH-AXHBM    | OK: Light is on when the module is normal. <br> 0 |


| Specification |  |  | EH-TC8 |  |
| :---: | :---: | :---: | :---: | :---: |
| Applicable thermocouple (switchable by a switch) |  |  | Conforms to JIS C 1602-1995 Type K, E, J, T, B, R, S, N |  |
| Temperature conversion data |  |  | Signed 15 bits |  |
| Measuring temperature range and accuracy*1 |  | Type | Accuracy guaranteed range | Input range |
|  |  | K | -200 to 1,200 ${ }^{\circ} \mathrm{C} \quad 0.4 \%$ (FS) | -270 to $1,370{ }^{\circ} \mathrm{C}$ |
|  |  | E | -200 to $900{ }^{\circ} \mathrm{C} \quad 0.3 \%$ (FS) | -270 to $1,000{ }^{\circ} \mathrm{C}$ |
|  |  | J | -40 to $750{ }^{\circ} \mathrm{C} \quad 0.3 \%$ (FS) | -270 to $1,200{ }^{\circ} \mathrm{C}$ |
|  |  | T | -200 to $350{ }^{\circ} \mathrm{C} \quad 0.8 \%$ (FS) | -270 to $400{ }^{\circ} \mathrm{C}$ |
|  |  | B | 600 to $1,700{ }^{\circ} \mathrm{C} \quad 1.0 \%$ (FS) | 0 to $1,820{ }^{\circ} \mathrm{C}$ |
|  |  | R | 0 to $1,600{ }^{\circ} \mathrm{C} \quad 1.0 \%$ (FS) | -50 to $1,760^{\circ} \mathrm{C}$ |
|  |  | S | 0 to $1,600{ }^{\circ} \mathrm{C} \quad 1.0 \%$ (FS) | -50 to $1,760{ }^{\circ} \mathrm{C}$ |
|  |  | N | -200 to $1,200{ }^{\circ} \mathrm{C} \quad 0.4 \%$ (FS) | -270 to $1,300{ }^{\circ} \mathrm{C}$ |
| Cold junction temperature error*2 |  |  | $\begin{aligned} & \left. \pm 2{ }^{\circ} \mathrm{C} \text { or less (Ambient temperature } 15 \text { to } 35^{\circ} \mathrm{C}\right) \\ & \left. \pm 3{ }^{\circ} \mathrm{C} \text { or less (Ambient temperature } 0 \text { to } 55^{\circ} \mathrm{C}\right) \end{aligned}$ |  |
| Resolution |  |  | $0.1{ }^{\circ} \mathrm{C} / 0.1{ }^{\circ} \mathrm{F}(\mathrm{K}, \mathrm{E}, \mathrm{J}, \mathrm{T}, \mathrm{N}) \quad 1.0{ }^{\circ} \mathrm{C} / 1.0{ }^{\circ} \mathrm{F}(\mathrm{B}, \mathrm{R}, \mathrm{S})$ |  |
| Input channel |  |  | 8 channels |  |
| Conversion time |  |  | $108 / 860 \mathrm{~ms}$ |  |
| Insulation system | Channel and Internal circuit |  | Photo-coupler insulation |  |
|  | Betwee | n channels | No insulation |  |
| External connection |  |  | Removable type screw terminal block (M3) |  |
| External power supply |  |  | 24 V DC $\pm 10 \% 100 \mathrm{~mA}$ at the maximum |  |
| External wiring*3 |  |  | Shield cable |  |
| Internal current consumption |  |  | Approx. 70 mA |  |
| Error detection | Input upper limit value over / <br> Breaking wiring detection |  | Input data: H7FFF (LED corresponding to a channel which detected error flashes.) |  |
|  | Input lower limit value over |  | Input data: H8000 |  |

*1 The sum of accuracy of each sensor and the cold junction temperature error is the overall accuracy. Also, there is error in the thermocouple.
*2 Error is the value after 10 minutes from the power-up. Error may increase slightly because of a quick change in using ambient temperature.
*3 The external wiring length is possible to $100 \mathrm{~m}(328 \mathrm{ft}$.) at the maximum. However, understand in advance that it may change according to the environment used.

| Terminal configuration |  |  | No. | Signal name | Diagram of Internal circuit |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | [1] | CH0(+) |  |  |  |  |  |
|  |  |  | [2] | CH1(+) |  |  |  |  |  |
|  |  |  | [3] | CH2(+) |  |  |  |  |  |
|  |  | [10] | [4] | CH3(+) |  |  |  |  |  |
|  |  |  | [5] | CH4(+) |  |  |  |  |  |
|  |  | [11] | [6] | CH5(+) |  |  |  |  |  |
|  |  | [12] | [7] | CH6(+) |  |  |  |  |  |
|  |  | [13] | [8] | CH7(+) |  |  |  |  |  |
|  |  | [14] | [9] | 24 V DC+ |  |  |  |  |  |
|  |  |  | [10] | CH0(-) |  |  |  |  |  |
|  |  | [15] | [11] | CH1(-) |  |  |  |  |  |
|  |  | [16] | [12] | CH2(-) |  |  |  |  |  |
|  |  | [17] | [13] | CH3(-) |  |  |  |  |  |
|  |  |  | [14] | CH4(-) |  |  |  |  |  |
|  |  | [18] | [15] | CH5(-) |  |  |  |  |  |
|  |  |  | [16] | CH6(-) |  |  |  |  |  |
|  |  |  | [17] | CH7(-) |  |  |  |  |  |
|  |  |  | [18] | 24 V DC- |  |  |  |  |  |


| Item | Switch setup |  |  | Setting contents |
| :---: | :---: | :---: | :---: | :---: |
| Thermocouple sensor switching (Common to all channels) | 1 | 2 | 3 |  |
|  | OFF | OFF | OFF | Type K |
|  | ON | OFF | OFF | Type E |
|  | OFF | ON | OFF | Type J |
|  | ON | ON | OFF | Type T |
|  | OFF | OFF | ON | Type B |
|  | ON | OFF | ON | Type R |
|  | OFF | ON | ON | Type S |
|  | ON | ON | ON | Type N |
| Celsius $\left({ }^{\circ} \mathrm{C}\right) /$ Fahrenheit $\left({ }^{\circ} \mathrm{F}\right)$ switching (Common to all channels) | 4 |  |  |  |
|  | OFF |  |  | Celsius ( ${ }^{\circ} \mathrm{C}$ ) |
|  | ON |  |  | Fahrenheit ( ${ }^{\circ} \mathrm{F}$ ) |
| Data updating interval switching | 5 |  |  |  |
|  | OFF |  |  | 860 ms |
|  | ON |  |  | 108 ms |
| Internal cold junction compensation switching | 6 |  |  |  |
|  | OFF |  |  | Cold junction compensation; Valid |
|  | ON |  |  | Cold junction compensation; Invalid |
| (System mode) | 7 |  |  |  |
|  | OFF |  |  | Always OFF (Do not turn ON.) |
|  | 8 |  |  |  |
|  | OFF |  |  | Always OFF (Do not turn ON.) |

[Setups shown in the white font on black background are initial factory setting:]

* In this module, be sure to perform the above setups. And, be sure to turn off the power in setting up. Otherwise, the setups are invalid.


## Reference

If the internal cold junction compensation is invalidated and a highly accurate ice-bus is installed outside, the temperature can be measured accurately on higher level.

MEMO

## Chapter 8 Positioning and Counter Module

### 8.1 Single-axis Positioning Module



| Purpose | Applied switch | Bit 1 | Bit 2 | Explanation |
| :---: | :---: | :---: | :---: | :---: |
| Choice of pulse output method | Bit 1-2 | OFF | OFF | Clock pulse / Direction signal output (Positive logic) |
|  |  | OFF | ON | Clock pulse / Direction signal output (Negative logic) |
|  |  | ON | OFF | CW / CCW pulse output (Positive logic) |
|  |  | ON | ON | CW / CCW pulse output (Negative logic) |


| Purpose | Applied switch |  | Explanation |
| :---: | :---: | :---: | :---: |
| Positioning complete external input signal | $\begin{array}{\|l\|l\|} \hline O N \quad 1 \end{array}$ | OFF | COIN signal |
| Choice of (COIN) is in or not | Bit 4 | ON | No COIN signal |
| + Direction overrun external input signal Choice of (+0.RUN) is in or not | Bit 5 | OFF | +0.RUN signal |
|  |  | ON | No +0.RUN |
| - Direction overrun external input signal Choice of ( -0. RUN ) is in or not | Bit 6 | OFF | -0.RUN signal |
|  |  | ON | No -0.RUN signal |

[^7]Specifications

| Item |  | Specification |
| :---: | :---: | :---: |
| Number of control axes |  | 1 axis |
| Highest frequency |  | $400 \mathrm{kpuls} / \mathrm{s}$ |
| Positioning data | Capacity | 256 points |
|  | Setting procedure | 1. Sequence program <br> 2. Positioner (Note, a positioner is optional.) |
| Positioning | Method | 1. Absolute system <br> 2. Absolute system + Increment system <br> 3. Increment system |
|  | Positioning instruction | 1. Pulse specifying <br> 2. $\mu \mathrm{m}$ specifying <br> 3. inch specifying <br> 4. degree specifying |
|  | Speed instruction | Automatic, manual, and homing 6.25 pulse/s to $400 \mathrm{kpulse} / \mathrm{s}$ <br> $\mu \mathrm{m} / \mathrm{s}, ~ \mathrm{inch} / \mathrm{s}$, degree $/ \mathrm{s}$ input function |
|  | Speed stage | 10 stages |
|  | Acceleration and deceleration system | Trapezoid acceleration and deceleration <br> S-curve acceleration and deceleration (3-stage acceleration and deceleration) |
|  | Acceleration and deceleration time | 1 to $65,535 \mathrm{~ms}$ |
|  | Backlash | 0 to 255 pulse |
|  | High and low limit setting | +2,147,483,647 to -2,147,483,648 pulse |
|  | Pulse output method | 1. Pulse chain (CW / CCW) <br> 2. Clock + direction signal (CK / Direction) (DIP switch No. 1 and No. 2 set the choice of pulse output system and the switching of each positive and negative logic.) |
|  | Pulse output procedure | 1. Open collector output (Photo-coupler insulation) <br> 2. Line driver output (Photo-coupler insulation) |
| Homing function |  | 1. Free home position <br> 2. Low speed homing <br> 3. High speed homing 1 <br> 4. High speed homing 2 <br> 5. Absolute value encoder homing |
| Teaching |  | Possible |
| Manual (JOG) operation |  | Pulse output by manual input signal |
| Operation when CPU has stopped |  | Operation is possible via I/O set or using the positioner |
| Absolute value encoder input |  | Supports to $\Sigma$ series / $\Sigma$ II series by Yasukawa Electric Co. and P series by SANYO electric Co. |
| Mounting position |  | Basic base and Expansion base |
| Number of units to be mounted simultaneously |  | Unlimited within power supply capacity of the power module |

(continued on the following page)
*1 When the CPU is stopped during operation, the motor decelerates and stops.
*2 The maximum travel per one movement is $2,147,483,647$ pulses. If the operation is performed exceeding the maximum travel, the motor decelerates and stops at the maximum travel position.

Specifications (continued from the preceding page)

| Item |  |  | Specification |
| :---: | :---: | :---: | :---: |
| Output | Pulse chain (CW / CCW) output <br> Clock + Direction signal <br> (CK / Direction) pulse output |  | 1. Open collector output photo-coupler insulation ( 30 V DC at the maximum, 30 mA resistive load) <br> 2. Line driver output photo-coupler insulation ( 5 V DC ) |
|  | Maximum leak current |  | $100 \mu \mathrm{~A}$ or less |
|  | Maximum voltage drop at ON |  | 0.8 V at the maximum (at output current 30 mA ) |
| Input | Input voltage |  | 10.8 to 30 V DC |
|  | Input impedance |  | Approx. $2.2 \mathrm{k} \Omega$ |
|  | Input current |  | Approx. 10 mA (24 V DC) |
|  | Operating voltage | Minimum ON voltage | 9 V |
|  |  | Maximum OFF voltage | 3.6 V |
|  | Input lag | $\mathrm{ON} \rightarrow$ OFF | 1 ms or less |
|  |  | $\mathrm{OFF} \rightarrow \mathrm{ON}$ | 1 ms or less |
|  | Polarity |  | Only encoder signal input uses the plus common inside the unit, and other inputs do not specify polarity. |
|  | Insulation system |  | Photo-coupler |

A) Specifications of Positioner connector (CN1): conforms to RS-422

| Terminal configuration | No. | Signal | Signal name | Diagram of Internal circuit |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | Do - | Driver output - |  |  |  |
|  | 2 | Do + | Driver output + |  |  |  |
|  | 3 | Ri - | Receiver input - |  |  |  |
|  | 4 | $\mathrm{Ri}+$ | Receiver input + |  |  |  |
|  | 5 | 5 V DC + | $+5 \mathrm{~V}$ |  |  |  |
|  | 6 | 0 V | GND |  |  |  |
|  | 7 | 0 V | GND |  |  |  |
|  | 8 | 12 V DC - | -12 V |  |  |  |
|  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |

B) Specifications of I/O connector (CN2)


### 8.2 High Speed Counter Module

Name and function of each part

LED name

| External view of LED part | LED name | Details | Color |
| :---: | :---: | :---: | :---: |
|  | PW | Lighted when the power is ON and the module operates regularly. | Green |
| 1A 1B 1M PW | ER | Lighted when the hardware error of the module occurs. | Red |
| $2 \mathrm{~A} \quad 2 \mathrm{~B} \quad 2 \mathrm{M} \quad \mathrm{ER}$ | 1A | Lighted depending on ON / OFF of the A-phase input signal of Channel 1. | Green |
| $\begin{array}{llll} 0 & 1 & 2 & 3 \end{array}$ | 1B | Lighted depending on ON / OFF of the B-phase input signal of Chnnale1. | Green |
| COUNTER EH-CU | 1M | Lighted depending on ON / OFF of the marker input signal of Channel 1. | Green |
| EH-CU (2-ch type) | 2A | Lighted depending on ON / OFF of the A-phase input signal of Channel 2. | Green |
|  | 2B | Lighted depending on ON / OFF of the B-phase input signal of Channel 2. | Green |
|  | 2M | Lighted depending on ON / OFF of the marker input signal of Channel 2. | Green |
| ER | 0 | Lighted depending on ON / OFF of Y0 output terminal. | Green |
| $0 \quad 1$ | 1 | Lighted depending on ON / OFF of Y1 output terminal. | Green |
| COUNTER EH-CUE | 2 | Lighted depending on ON / OFF of Y2 output terminal. | Green |
| EH-CUE (1-ch type) | 3 | Lighted depending on ON / OFF of Y3 output terminal. | Green |

* "ER" LED lights up for an instance if the reset switch is pressed down. That is no error.

| Purpose | Applied switch | Bit1 | Bit 2 | Explanation |
| :--- | :---: | :---: | :---: | :--- |
| Select the counter mode <br> (Common between <br> channels) | Bit 1,2 | OFF | OFF | 2-phase counter (100 kHz at the maximum) |


| Purpose | Applied switch |  | Explanation |
| :---: | :---: | :---: | :---: |
| Select the marker polarity | Bit 3 | OFF | Channel 1 Detects the marker at the input OFF edge. |
|  |  | ON | Channel 1 Detects the marker at the input ON edge. |
|  | N-1000 | OFF | Channel 2 Detects the marker at the input OFF edge. |
|  | Bit 4 | ON | Channel 2 Detects the marker at the input ON edge. |
| Select counting operation during STOP |  | OFF | Channel 1 Stops counting while the CPU module stops. |
|  |  | ON | Channel 1 Keeps counting while the CPU module stops. |
|  |  | OFF | Channel 2 Stops counting while the CPU module stops. |
|  | Bit 6 | ON | Channel 2 Keeps counting while the CPU module stops. |
| Select normal counter / ring counter |  | OFF | Channel 1 Normal counter |
|  |  | ON | Channel 1 Ring counter |
|  |  | OFF | Channel 2 Normal counter |
|  | Bit 8 | ON | Channel 2 Ring counter |
| Select the test mode |  | OFF | Normal operation |
|  |  | ON | Test mode (Program for checking is started up.) |

* Always use Bit 10 with OFF.


## Specifications

| Item |  | Specification |  |
| :---: | :---: | :---: | :---: |
| Type |  | EH-CU | EH-CUE |
| Number of channels |  | 2 channels | 1 channel |
| Number of counts at the maximum |  | 32 bits (0 to 4,294,967,295) |  |
| Maximum frequency |  | 100 k Hz ( 25 k Hz at multiplied by 4) |  |
| Count mode |  | Select by setting of DIP switch. (EH-CU is common to both channels.) 2-phase, 1-phase (CW / CCW, CK, U / D), 2-phase multiplied by 4 |  |
| Differential input current |  | 4 mA or more |  |
| Differential input voltage |  | 12 to 24 V DC |  |
|  | Minimum ON voltage | 10 V DC |  |
|  | Maximun OFF voltage | 4 V DC |  |
| Insulation system |  | Photo-coupler |  |
| Number of input points 3 points / CH | A:A, CW, CK | Phase difference of each channel (A - B) during 2-phase counting $+45^{\circ}$ to $+125^{\circ}$ when up, $-45^{\circ}$ to $-125^{\circ}$ when down |  |
|  | B:B, CCW, U / D |  |  |
|  | M: Marker (z) |  |  |
| Minimum counter pulse width |  | ON: $4 \mu \mathrm{~s}$ or more, OFF: $4 \mu$ s or more |  |
| Minimum marker pulse width |  | $10 \mu \mathrm{~s}$ or more (detected at ON edge) |  |
| External wiring method |  | 30-pin batch connector for both channels | 30-pin connector |
| External wiring |  | Wired with twisted pair cables and batch shielded cables |  |
| Output voltage |  | $12 / 24 \mathrm{~V}$ DC ( 30 V DC at the maximum) |  |
| Load current |  | $20 \mathrm{~mA} /$ point at the maximum |  |
| Output method |  | Open collector output |  |
| Minimum load current |  | 1 mA |  |
| Output delay time | $\mathrm{ON} \rightarrow$ OFF | 1 ms or less |  |
|  | $\mathrm{OFF} \rightarrow \mathrm{ON}$ | 1 ms or less |  |
| Voltage down at ON |  | 1.5 V at the maximum |  |
| Number of external output points |  | 4 points / module <br> External terminal of output destination can be specified for each channel | 2 points / module |
|  | Normal counter | Current value = Set value 1, or Current value > Set value 1 |  |
|  | Ring counter | Current value $=$ Set value 2 |  |
| Leak current |  | 0.5 mA at the maximum |  |
| Polarity |  | $(-)$ common within the module |  |
| External power supply |  | $12 / 24 \mathrm{~V}$ DC ( 30 V DC at the maximum) |  |
| Insulation system |  | Photo-coupler |  |
| Mounting position |  | Basic base, Expansion base (cannot mount on the remote base) |  |
| Number of units to be mounted simultaneously |  | Unlimited within power supply capacity of the power module. |  |

Specifications of I/O terminal

| EH-CU |  | Terminal configuration | No. | CH2 | No. | CH1 |  | Meaning of signal |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | 16 | Vin A | 1 | Vin A | Phase A | Connects to a 12 to 24 V DC power supply at using voltage input. |
|  |  |  | 17 | A (+) | 2 | A (+) |  | Connects (+) polarity at using differential input. |
|  |  |  | 18 | A (-) | 3 | A (-) |  | Connects an open collector signal at using voltage input. <br> Connects (-) polarity at using differential input. |
|  |  |  | 19 | Vin B | 4 | Vin B | Phase B | Connects to a 12 to 24 V DC power supply at using voltage input. |
|  |  |  | 20 | B (+) | 5 | B (+) |  | Connects (+) polarity at using differential input. |
|  |  |  | 21 | B (-) | 6 | B (-) |  | Connects an open collector signal at using voltage input. <br> Connects (-) polarity at using differential input. |
|  |  |  | 22 | Vin M | 7 | Vin M | Marker | Connects to a 12 to 24 V DC power supply at using voltage input. |
|  |  |  | 23 | M (+) | 8 | M (+) |  | Connects (+) polarity at using differential input. |
|  |  |  | 24 | M (-) | 9 | M (-) |  | Connects an open collector signal at using voltage input. <br> Connects (-) polarity at using differential input. |
|  |  |  | 25 to 27 N.C. |  | 10 to 12 N.C. |  |  | Connect nothing. |
|  |  |  | 28 | Y2 | 13 | Y0 | Output | Coincidence output. Connects to the other input. |
|  |  |  | 29 | Y3 | 14 | Y1 |  | Coincidence output. Connects to the other input. |
|  |  |  | 30 | Com2 | 15 | Com1 |  | (-) common for coincidence common. Commons 1 and 2 are independent. |

* Pin No. defined in EH-CU does not accord with pin No. defined by connector maker.


[^8]MEMO

## Chapter 9 Communication and Network Module

### 9.1 CPU Link Module

Coaxial cable type


* The CPU module will detect a "Link Module Error (error code: 74H)" if the reset switch is pressed. Please resolve the error of the CPU module after making sure that the link module is operating normally.


## LED name

| Front view of LED part | LED | Details |  | Color |
| :---: | :---: | :---: | :---: | :---: |
| CPU LINK EH-LNK | TxD | Flashes when data is received. |  | Yellow green |
|  | RxD | Flashes when data is transmitted. |  | Yellow green |
| ERR RxD | RUN | Lights up when the link module is operating properly. |  | Yellow green |
|  | ERR | Normal state <br> Error (data link is possible) <br> Error (data link is impossible) | OFF <br> Flashing (in 1 s interval) <br> : Flashing (in 0.5 s interval), turn on | Red |

Optical cable type


* If the reset switch is pressed, the CPU module will detect a "Link Module Error (error code: 74H)". Please resolve the error of the CPU module after making sure that the link module is operating normally.

LED name

| Front view of LED part | LED |  | Details | Color |
| :---: | :---: | :---: | :---: | :---: |
|  | TxD | Flashes when data is received. |  | Yellow green |
| CPU LINK EH-OLNK | RxD | Flashes when data is transmitted. |  | Yellow green |
| ERR RxD | RUN | Lights up when the link module is operating properly. |  | Yellow green |
|  | ERR | Normal state <br> Error (data link is possible) <br> Error (data link is impossible) | OFF <br> : Flashing (in 1s interval) <br> Flashing (in 0.5 s interval), turn on | Red |

Specifications (CPU link module (coaxial, optical))

| Item |  |  | Specification |
| :---: | :---: | :---: | :---: |
|  | Number of connected link modules |  | 64 units at the maximum per link system |
|  | Number of link points |  | 1,024 words per loop ( 2,048 words per 2 loops)*1 |
|  | Data delivery system |  | Common data area system |
|  | Transmit / Receive distinction on data area allocation |  | Parameter setup from peripheral devices |
|  | Station No. specifying |  | Specifies 0 to 63 by a rotary switch. |
|  | Transmission speed |  | 1.0 Mbps |
|  | Transmission method |  | Half-duplex serial transmission, frame synchronization |
|  | Communication method |  | Token passing |
|  | Modulation method |  | Base band |
|  | Refresh time |  | At 64 stations connection and 1024 words transfer; Approx. 390 ms |
|  | Error check |  | CRC, overrun check, timeout, open circuit parameter error (Dual specifying of station No., overlap of link area, etc.) |
|  | Self-diagnosis |  | System ROM / RAM check, watchdog timer check, transmission loop back check |
| Transmission channel Specification | Transmission channel form |  | Loop type |
|  | Cable length | ween stations | Maximum 500 m (EH-LNK), Maximum 1,000 m (EH-OLNK), Maximum 2,000 m (EH-OLNKG,E) |
|  |  | extension | Maximum 1,000 m (EH-LNK), Maximum 15,000 m (EH-OLNK,EH-OLNKG,E) |
|  | Error station processing |  | Bypass system (coaxial), Bypass system (optical; only when supplying 5 V DC from another power source) |
|  | Recommended cable (EH-LNK) |  | Coaxial cable with shield (equivalent to the 5D-2V with shield) |
|  | Recommended connector (EH-LNK) |  | Link module side: equivalent to 413631-1 (by AMP) |
|  | Recommended cable and connector (Refer to the instruction of each module for more details.) | EH-OLNK | CA7103-1 M-2 L 31 Hitachi Hybrid Network Co., Ltd. 1 : cable length, 2 : cable type, 3 : core number |
|  |  | EH-OLNKG, EH-OLNKE | CA9103S- 1 M-AL11 Hitachi Hybrid Network Co., Ltd. CA9003S- 1 M-AL12 CA9103S-1 M- 2 B 1: cable length, 2 : core number For the recommended cable of EH-OLNKE, add "- 625 " at the end of above types. |
| Mounting position |  |  | Slot 0 to 7 on the basic base |

*1 Power failure memory protection is not possible.

### 9.2 PROFIBUS-DP Master Module 2



| Outline of communication connector | Symbol | Indication |  | Details |
| :---: | :---: | :---: | :---: | :---: |
| PROFIBUS | PROFIBUS | Communication connector | D-sub 9 pin Terminal la | onnector. |
|  |  |  | Pin No. | Details |
|  |  |  | 1 | NC |
|  |  |  |  | NC |
|  |  |  | 4 | NC |
|  |  |  | 5 | GND |
|  |  |  | 6 | +5 V DC |
|  |  |  | 7 | NC ${ }^{\text {A-Line }}$ |
|  |  |  | 9 | NC |

Description of LED display

| LED | LED name | Indication | Details |  |
| :---: | :---: | :---: | :---: | :---: |
|  | RDY | Hardware status <br> (Green / Red) | Display EH-RMP2 hardware status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Hardware error <br> Power supply error |
|  |  |  |  |  |
|  |  |  | Flash in green or red | Initialization |
|  |  |  | Lit in red | Hardware error |
|  |  |  | Lit in green | No error |
|  | STATUS | System status (Green / Red) | Display EH-RMP2 system status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Power supply error |
|  |  |  | Flash in red | Internal error |
|  |  |  | Lit in red | WDT error |
|  |  |  | Fifth-flash in green | Side DIP switch setting error |
|  |  |  | Forth-flash in green | Link parameter error |
| PROFIBUS EH-RIMP2  <br> $\square \square$ $\square$ $\square$ <br> RDY RUN ERR <br> $\square \square$ $\square$  <br> STATUS  REM |  |  | Triple-flash in green | Configuration data error |
|  |  |  | Double-flash in green | CPU module error |
|  |  |  | Single-flash in green | Initialization |
|  |  |  | Lit in green | No error |
|  | RUN | Display PROFIBUS network status. |  |  |
|  |  | Network status (Green) | State | Details |
|  |  |  | Off | No communication established |
|  |  |  | Blinking | Under communication establishment |
|  |  |  | On | Communication established |
|  | ERR | Error status <br> (Red) | Display PROFIBUS error status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Communication established |
|  |  |  | Blinking | Slave units at least one are not established |
|  |  |  | On | All slave units are not established |
|  | REM | Operating mode <br> (Green) | No use. It is always off. |  |

The state of LED is indicated below.


Description of Rotary switch

| Rotary switch | $\begin{gathered} \text { Symbol } \\ \hline \hline \text { MODE } \end{gathered}$ | Meaning | Details of setting |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| [Default setting: 0] |  | Input / Output Sizes | The input / output sizes of PROFIBUS network are set by rotary switch. |  |  |  |
|  |  |  | Value | Network size | Input size | Output size |
|  |  |  | 0 | Variable size | 512 words max | 512 words max |
|  |  |  | 1 | 64W / 64W fixed | 64 words | 64 words |
|  |  |  | 2 | 128W / 128W fixed | 128 words | 128 words |
|  |  |  | 3 | 256W / 256W fixed | 256 words | 256 words |
|  |  |  | 4 | 512W / 512W fixed | 512 words | 512 words |
|  |  |  | 5 |  |  |  |
|  |  |  | 6 |  |  |  |
|  |  |  | 7 | Variable size | 512 words max | 512 words max |
|  |  |  | 8 |  |  |  |
|  |  |  | 9 |  |  |  |
|  |  |  | In case of fixed at 25 | e compatible mode, ords / 256words in sp | input / output <br> of setting of thi | es of PROFIBU witch. |

Please set rotary switch to 0 if you use auto addressing function with use of the SYCON.net. If you map each slave I/O address including offset address, please set rotary switch value $1,2,3$ or 4 . When actual input / output sizes exceed setting sizes, EH-RMP2 detects error.

## Description of Side DIP switch



## Performance specification

| Item |  | Specifications |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | EH-RMP2 |  | EH-RMP <br> (Existing model) |
|  |  | Standard mode | Compatible mode |  |
|  | Communication protocol | PROFIBUS-DP V0 |  |  |
|  | Range of node address | 0 to 125 : Setting by configuration tool |  |  |
|  | Maximum I/O size | Input: 512 words, output: 512 words (Setting by rotary switch) | Input: 256 words, output: 256 words |  |
|  | Connector | D-sub 9 pin |  |  |
|  | Topology | BUS |  |  |
|  | Communication cable |  | ROFIBUS cable |  |
|  | Segment length, <br> Transmit speed |  | kbps $: 1,200 \mathrm{~m}$ <br> kbps $: 1,200 \mathrm{~m}$ <br> kbps $: 1,200 \mathrm{~m}$ <br> kbps $: 1,000 \mathrm{~m}$ <br> kbps $: 400 \mathrm{~m}$ <br> kbps $: 200 \mathrm{~m}$ <br> Mbps $: 100 \mathrm{~m}$ <br> Mbps $: 100 \mathrm{~m}$ <br> Mbps $: 100 \mathrm{~m}$ |  |
|  | Maximum connectable number of slaves | 125 slaves |  |  |
|  | Output hold | Supported (Clear mode, Freeze mode, Copy mode) |  |  |
|  | Termination | Not built-in |  | Built-in |
|  | Configuration tool | SYCON.net |  | SyCon |
|  | Number of modules | 8 modules / CPU |  |  |
|  | Self-check | WDT check |  | WDT check <br> System memory check |
|  | Error indication | LED |  |  |

### 9.3 PROFIBUS-DP Slave Controller 2



| Outline of communication connector | Symbol | Indication |  | Details |
| :---: | :---: | :---: | :---: | :---: |
| PROFIBUS | PROFIBUS | Communication connector | D-sub 9 pin connector. <br> Terminal layouts are shown below. |  |
|  |  |  | Pin No. | Details |
|  |  |  | 1 | NC |
|  |  |  | 2 | NC |
|  |  |  | 3 | B-Line |
|  |  |  | 4 | NC |
|  |  |  | 5 | GND |
|  |  |  | 6 | +5 V DC |
|  |  |  | 7 | NC |
|  |  |  | 8 | A-Line |
|  |  |  | 9 | NC |

## Description of LED display



The state of LED is indicated below.


Description of Rotary switch

| Rotary switch | Symbol | Meaning | Details of setting |
| :---: | :---: | :---: | :--- |

## Description of Bottom DIP switch

|  |  |  | Downward position is ON side in case of bottom view like left figure. |  |
| :---: | :---: | :---: | :---: | :---: |
| No. | Setting description | Details |  |  |
|  | Output hold function selecting <br> [Default setting: OFF] | When the PROFIBUS master's communication stopped, it is selected whether the output data from the master is held or not. (Hold means the last data received properly is fixed.) Output hold function may be changed action depending on master unit. Please read master's manual and check the combination master unit and EH-IOCP2, before using output hold function of EH-IOCP2. |  |  |
|  |  | Bit1 | Position | Output hold function selection |
|  |  | OFF |  | Disable the output hold function (Turn off all output data from the master at the communication stopped.) |
|  |  | ON |  | Enable the output hold function (At the communication stopped, output data from master is held with last data received properly.) |
| 2 | EH-IOCP compatible mode selecting <br> [Default setting: OFF] | It can select whether the EH-IOCP2 operates as standard mode or compatible mode. |  |  |
|  |  | Bit2 | Position | EH-IOCP compatible mode selection |
|  |  | OFF |  | Standard mode (EH-IOCP2) |
|  |  | ON |  | Compatible mode (EH-IOCP) |
| 3 | Data swap function selecting | It can select whether it performs byte swap by a word unit. |  |  |
|  |  | Bit3 | Position | Data swap function selection |
|  | [Default setting: OFF] | OFF |  | Disable the data swap function |
|  |  | ON |  | Enable the data swap function |
| 4 | No use <br> [Default setting: OFF] | Please keep off. |  |  |
|  |  |  |  |  |

Performance specification

| Item |  | Specifications |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  |  | EH-IOCP2 |  | EH-IOCP(Existing model) |
|  |  | Standard mode | EH-IOCP compatible mode |  |
|  | Communication protocol | PROFIBUS-DP V0 |  |  |
|  | Range of node address | 0 to 99 : Setting by rotary switch |  |  |
|  | Maximum I/O size | Input : 244 bytes, Output : 244 bytes*1 |  |  |
|  | Connector | D-sub 9 pin |  |  |
|  | Topology | BUS |  |  |
|  | Communication cable | PROFIBUS cable |  |  |
|  | Segment length, Transmit speed | 9.6 kbps <br> 19.2 kbps <br> 93.75 kbps <br> 187.5 kbps <br> 500 kbps <br> 1,500 kbps <br> 3 Mbps <br> 6 Mbps <br> 12 Mbps | $\begin{aligned} & : 1,200 \mathrm{~m} \\ & : 1,200 \mathrm{~m} \\ & : 1,200 \mathrm{~m} \\ & : 1,000 \mathrm{~m} \\ & : 400 \mathrm{~m} \\ & : 200 \mathrm{~m} \\ & : 100 \mathrm{~m} \\ & : 100 \mathrm{~m} \\ & : 100 \mathrm{~m} \end{aligned}$ |  |
|  | Output hold | Supported*2 |  |  |
|  | Data swap | Supported |  | Not supported |
|  | Termination | Not built-in |  | Built-in |
|  | GSD file | HITA0E64.GSD | HITA049D.GSD |  |
| $\begin{gathered} 0.0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{gathered}$ | Support base unit | EH-BS3/5/8/3A/5A/ 6A / 8A/ 11A / 8R | EH-BS3/5/8/3A/5A/6A / 8A |  |
|  | Number of modules | 22 modules / EH-IOCP2 | 16 modules / EH-IOCP(2) |  |
|  | Number of I/O points | 1,408 points: Digital I/O <br> 176 ch : Analog I/O*2 | 1,024 points: Digital I/O, 128 ch : Analog I/O |  |
|  | Expansion unit | 1 (use by EH-IOC, EH-IOCH and EH-IOCH2) |  |  |
|  | Refresh time | $500 \mu \mathrm{~s}$ |  | 5 ms |
|  | Self-check | WDT check |  | WDT check <br> System memory check |
|  | Error indication | LED |  |  |

[^9]
### 9.4 EtherCAT Slave Controller



Description of LED display

| Outline | LED name | Indication | Details |  |
| :---: | :---: | :---: | :---: | :---: |
|  | POW | Power supply <br> (Green) | On : indicates that the 5 V DC power is supplied. <br> Off : indicates that the 5 V DC power is not supplied or reset switch is on. |  |
|  | RUN | Status <br> (Green) | Display an EtherCAT communication status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Init |
|  |  |  | Blinking | PRE-OPERATIONAL |
|  |  |  | Single-flash | SAFE-OPERATIONAL |
|  |  |  | On | OPERATIONAL |
|  | ERR | Error <br> (Red) | Display EtherCAT error status or EH-IOCA hardware status. |  |
|  |  |  | State | Details |
|  |  |  | Off | No error |
|  |  |  | Blinking | Configuration error |
|  |  |  | Single-flash | EtherCAT synchronism failure <br> Communication data failure |
|  |  |  | Double-flash | Application watchdog timeout |
|  |  |  | Flickering | Boot error |
|  |  |  | On | PDI watchdog timeout |

The state of LED is indicated below.


Description of Rotary switch

| Rotary switch | Symbol | Meaning | Details of setting |
| :---: | :---: | :---: | :--- |

Node address of EH-IOCA is set by node address method of EtherCAT master unit. If EtherCAT master use fixed node address method, rotary switch of EH-IOCA is valid. If EtherCAT master use logic node address method or auto increment address method, rotary switch of EH-IOCA is invalid. If EtherCAT master use logic nodes address method or auto increment address method, please set the rotary switch to " 00 ".

Description of Connector

\begin{tabular}{|c|c|c|c|c|}
\hline \multicolumn{2}{|l|}{Connector} \& Symbol \& Indication \& Details \\
\hline \begin{tabular}{l}
LINK \\
IN \\
ACT
\end{tabular} \& \multirow[t]{3}{*}{\begin{tabular}{l}
8 \\
1 \\
8
\end{tabular}} \& IN

OUT \& Communication connector \& | RJ45 8-pin connector. |
| :--- |
| Terminal layouts are shown below. | <br>

\hline \& \& LINK \& | LINK LED |
| :--- |
| (Green) | \& LINK LED light up if the communication device are connected with a cable. <br>


\hline \& \& ACT \& | ACT LED |
| :--- |
| (Orange) | \& ACT LED is flashing during operation. <br>

\hline
\end{tabular}

## Recommended cable

Recommended cable of EH-IOCA is shown below. But if EH-IOCA is used in noisy environment, we recommend cables with double, aluminum tape and braided shielding.

| Item | Details |
| :--- | :--- |
| Twisted pair cable | 100BASE-TX (CAT 5 or higher) <br> STP cable |
| RJ45 connector | CAT 5 or higher, Shielded |

The maximum cable length between connected nodes is 100 m . Note that some cables do not guarantee 100 m . In general, if the conductors are strand wire, the transmission performance will be lower than solid wire and the operation at 100 m distance cannot be guaranteed. Confirm details with the cable manufacturer.

Performance specification

| Item |  | Specifications |
| :---: | :---: | :---: |
|  | Communication protocol | EtherCAT protocol |
|  | Transmit modulation method | Base band |
|  | Transmit speed | 100 Mbps |
|  | Physical layer | 100BASE-TX (IEEE802.3) |
|  | Connector | RJ45 (IN, OUT) |
|  | Topology | Daisy-chain |
|  | Recommended cable | CAT5 or higher, STP cable |
|  | Maximum segment length | 100 m |
|  | Communication cycle | $200 \mu$ or over *1 |
|  | Node address range | 1 to 99 :Setting by rotary switch <br> 1 to 65,535 :Setting by EtherCAT master |
|  | Process data | Fixed PDO mapping |
|  | Mailbox | Support |
|  | Cycle mode | Free Run mode (asynchronous) |
|  | Output hold | Support |
|  | Support base unit | EH-BS3A / 5A / 6A / 8A / 11A / 8R |
|  | Number of modules | 22 modules / EH-IOCA |
|  | Number of I/O points | 1,408 points: Digital I/O <br> 176 ch : Analog I/O |
|  | Expansion unit | 1 |
|  | Refresh time | $500 \mu \mathrm{~s}$ |
|  | Self-check | WDT check |
|  | Error indication | LED |
|  | Current consumption | 350 mA |

*1 The communication cycle is dependent on the specification of the EtherCAT Master.

### 9.5 FL-net Module 3

Name and function of each part

## Description of LED display

| LED | LED name | Indication | Details |  |
| :---: | :---: | :---: | :---: | :---: |
|  | POW | Power supply <br> (Green) | Display the power(5 V DC) status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Power off |
|  |  |  | Lit in green | Power on |
|  | LNK | Network status (Green) | Display the entry state of FL-net network. |  |
|  |  |  | State | Details |
|  |  |  | Off | Not participation in network |
|  |  |  | Lit in green | Participation in network |
|  | TxD | Transmit (Green) | Display transmission status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Not sending data |
| FL-net <br> EH-FLN3 <br> POW <br> LNK <br> TXD <br> PER <br> RXD |  |  | Lit in green | Sending data |
|  | RxD | Receive (Green) | Display receiving status. |  |
|  |  |  | State | Details |
|  |  |  | Off | Not receiving data |
|  |  |  | Lit in green | Receiving data |
|  | PER | Parameter error (Red) | Display parameter status. |  |
|  |  |  | State | Details |
|  |  |  | Off | No error |
|  |  |  | Lit in red | Parameter error |
|  | HER | Hardware error (Red) | Display hardware status. |  |
|  |  |  | State | Details |
|  |  |  | Off | No error |
|  |  |  | Lit in red | Hardware error |

## Description of Side DIP switch



## Performance specification

| Item |  | Specifications |
| :---: | :---: | :---: |
|  | Communication protocol | FL-net Ver.3.01 class 1 |
|  | Baud rate | 10M / 100Mbps <br> Auto Negotiation |
|  | Modulation | Baseband transmission |
|  | Electrical interface | Conforms to IEEE802.3 (Conforms to CSMA / CD) |
|  | Communication protocol | UDP/IP FA link protocol |
|  | Communication cable | 10/100BASE-T <br> CAT5(UTP) |
|  | Maximum transmission distance | 100 m |
|  | Maximum number of nodes | 254 nodes |
| 碳 | Number of modules | 2 modules / CPU, Mounting position is the slot 0 to 7 |
|  | Cyclic transmission | Area1: 8 kbits <br> Area2: 8 kwords |
|  | Message transmission | Not supported |
|  | Self-check | System memory check WDT check |

## Chapter 10 Accessories

10.1 Dummy Module


### 10.2 Expansion Cable



### 10.3 Terminal Block for 32/64 Points I/O Module



Terminal configuration


| I/O and Terminal block |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EH-XD32 |  |  |  |  |  |  |  |  | EH-YT32 / YTP32 |  |  |
| I/O No. <br> (Signal) | Terminal <br> block No. | I/O No. <br> (Signal) | Terminal <br> block No. | I/O No. <br> (Signal) | Terminal <br> block No. | I/O No. <br> (Signal) | Terminal <br> block No. |  |  |  |  |
| Bit00 | 1 | Bit16 | 21 | Bit00 | 1 | Bit16 | 21 |  |  |  |  |
| Bit01 | 2 | Bit17 | 22 | Bit01 | 2 | Bit17 | 22 |  |  |  |  |
| Bit02 | 3 | Bit18 | 23 | Bit02 | 3 | Bit18 | 23 |  |  |  |  |
| Bit03 | 4 | Bit19 | 24 | Bit03 | 4 | Bit19 | 24 |  |  |  |  |
| Bit04 | 5 | Bit20 | 25 | Bit04 | 5 | Bit20 | 25 |  |  |  |  |
| Bit05 | 6 | Bit21 | 26 | Bit05 | 6 | Bit21 | 26 |  |  |  |  |
| Bit06 | 7 | Bit22 | 27 | Bit06 | 7 | Bit22 | 27 |  |  |  |  |
| Bit07 | 8 | Bit23 | 28 | Bit07 | 8 | Bit23 | 28 |  |  |  |  |
| C | 9 | C | 29 | C | 9 | C | 29 |  |  |  |  |
| Bit08 | 10 | Bit24 | 30 | S | 10 | S | 30 |  |  |  |  |
| Bit09 | 11 | Bit25 | 31 | Bit08 | 11 | Bit24 | 31 |  |  |  |  |
| Bit10 | 12 | Bit26 | 32 | Bit09 | 12 | Bit25 | 32 |  |  |  |  |
| Bit11 | 13 | Bit27 | 33 | Bit10 | 13 | Bit26 | 33 |  |  |  |  |
| Bit12 | 14 | Bit28 | 34 | Bit11 | 14 | Bit27 | 34 |  |  |  |  |
| Bit13 | 15 | Bit29 | 35 | Bit12 | 15 | Bit28 | 35 |  |  |  |  |
| Bit14 | 16 | Bit30 | 36 | Bit13 | 16 | Bit29 | 36 |  |  |  |  |
| Bit15 | 17 | Bit31 | 37 | Bit14 | 17 | Bit30 | 37 |  |  |  |  |
| C | 18 | C | 38 | Bit15 | 18 | Bit31 | 38 |  |  |  |  |
| N.C. | 19 | N.C. | 39 | C | 19 | C | 39 |  |  |  |  |
| N.C. | 20 | N.C. | 40 | S | 20 | S | 40 |  |  |  |  |

* In case the 64-point module, the signal No. 00 to 31 depends on the table mentioned above. For signal No. 32 to 63 (including COM), read signal No. 00 to 31 as signal No. 32 to 63 in above table.
When using the 64 -point module, 2 sets of the terminal block (HPX7DS-40V6) and the connection cable (EH-CBM ${ }^{* *}$ W) per a module are needed.


### 10.4 Cable for 32 / 64-Point Module



| Cable code for wiring |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Connector Pin No. | Color | Dot (Color) | Connector Pin No. | Color | Dot (Color) |
| 1 | Orange | (Black) | 21 | Orange | ■■ (Black) |
| 2 | Orange | $\square$ (Red) | 22 | Orange | $\square \square \square$ (Red) |
| 3 | Gray | - (Black) | 23 | Gray | ■■ (Black) |
| 4 | Gray | $\square$ (Red) | 24 | Gray | $\square \square \square$ (Red) |
| 5 | White | - (Black) | 25 | White | ■■ (Black) |
| 6 | White | $\square$ (Red) | 26 | White | $\square \square \square$ (Red) |
| 7 | Yellow | -(Black) | 27 | Yellow |  |
| 8 | Yellow | $\square$ (Red) | 28 | Yellow | $\square \square \square$ (Red) |
| 9 | Pink | (Black) | 29 | Pink | ■ - (Black) |
| 10 | Pink | $\square$ (Red) | 30 | Pink | $\square \square \square$ (Red) |
| 11 | Orange | ■ (Black) | 31 | Orange | ■■■■(Black) |
| 12 | Orange | $\square \square$ (Red) | 32 | Orange | $\square \square \square \square($ Red $)$ |
| 13 | Gray | ■(Black) | 33 | Gray | ■■■(Black) |
| 14 | Gray | $\square \square(\mathrm{Red})$ | 34 | Gray | $\square \square \square \square($ Red $)$ |
| 15 | White | - $\square_{\text {(Black) }}$ | 35 | White | ■■■(Black) |
| 16 | White | $\square \square$ (Red) | 36 | White | $\square \square \square \square($ Red $)$ |
| 17 | Yellow | ■ (Black) | 37 | Yellow | ■■■■(Black) |
| 18 | Yellow | $\square \square(\mathrm{Red})$ | 38 | Yellow | $\square \square \square \square($ Red ) |
| 19 | Pink | ■ (Black) | 39 | Pink | ■■■■(Black) |
| 20 | Pink | $\square \square$ (Red) | 40 | Pink | $\square \square \square \square(\mathrm{Red})$ |

10.5 Cable for Counter Input Module


## MEMO

## Chapter 11 PAC Installation, Mounting, Wiring

For safety use, avoid installing the PAC in the following locations.

- Excessive dusts, salty air, and / or conductive materials (iron powder, etc.)
- Direct sunlight
- Temperature less than $0^{\circ} \mathrm{C}$ or more than $55^{\circ} \mathrm{C}$
- Dew condensation
- Humidity less than $5 \%$ or more than $95 \%$
- Direct vibration and / or impact to the unit
- Corrosive, explosive and / or combustible gasses
- Water, chemicals and / or oil splashing on the PAC
- Close to noise emission devices


### 11.1 Installation

(1) Installing location and environment
(a) Use the module in the "3.1 General Specification" environment when installing the HX-CPU.
(b) Mount the PAC onto the metal plate.
(c) Install the PAC in a suitable enclosure such as a cabinet which opens with a key, tool, etc.
(2) Installation of a base unit
(a) Precaution when installing the base unit

1] Fix the base unit securely with screws in 4 places (M4, length 20 mm ( 0.79 in .) or longer) or DIN rail when installing it.

2] To keep using the unit within the ambient temperature range.
a) Allow ample space for air circulation. ( 50 mm ( 1.97 in .) or more at top and bottom, 10 mm ( 0.39 in .) or more at right and left)
b) Avoid installing the unit directly above equipment that generates a lot of heat (heater, transformer, large-capacity resistance, etc.).
c) Install a fan or a cooler to lower the ambient temperature to below $55^{\circ} \mathrm{C}$ when the temperature reaches more than $55^{\circ} \mathrm{C}$.

3] Avoid mounting inside a panel where high-voltage equipment is installed.
4] Install 200 mm ( 7.87 in .) or more away from high-voltage wires or power wires.
5] Avoid mounting the unit upside down, in vertical, or in horizontal.


Figure 11.1 Amount of installation


Figure 11.2 External dimensions
Table 11.1 Dimensional table

| Base | L1 <br> (External <br> dimensions) | L2 <br> (Mounted <br> dimensions) |
| :---: | :---: | :---: |
| EH-BS3A | $222.5(8.76)$ | $207(8.15)$ |
| EH-BS5A | $282.5(11.2)$ | $267(10.51)$ |
| EH-BS6A | $312.5(12.31)$ | $297(11.70)$ |
| EH-BS8A | $372.5(14.67)$ | $357(14.06)$ |
| EH-BS11A | $462.5(18.21)$ | $447(17.6)$ |
| EH-BS8R | $432.5(17.01)$ | $417(16.42)$ |
| Unit: mm (in.) |  |  |

## (b) Mounting to a DIN rail

Attaching to a DIN rail


Fixing the unit


Removing the unit from the DIN rail


1] While lowering the DIN rail fixing mounting lever toward the bottom, raise the base upward to remove.

### 11.2 Mounting Module

(1) Installing


1] Hook the claw at the lower section of the module to the hole in the base.
2] Press in the upper side of the module until it clicks.
*1 Make sure the module does not come out after loading the module.
*2 Load the power module at the far left side of base unit.
*3 Load the CPU module and the I/O controller to the left of the power module.

It can reinforce with the screw after installation. Use M $4 \times 10 \mathrm{~mm}$ screws in this case.
(2) Removing


1] Push in the lock button.
2] With the lock button pushed in, pull the top of the module toward the front.
3] Raise it toward the top and pull it out.

* Pull the power module out while pushing down the two lock buttons.


### 11.3 Wiring

(1) Separation of the power system

There is power for the HX-CPU unit / power for I/O signal / power for general equipment as the power supply.
These power supplies should be wired from separate systems as much as possible.
When these power supplied are supplied from one main power source, separate the wiring with a transformer or similar devices, so that each power supply is a separate system.


Figure 11.3 Example of power system diagram
(2) Regarding fail safe

1] Construct an interlock circuit outside the PAC.
When the PAC power supply is turned ON / OFF, the lag time and the difference in the startup time between the PAC unit power and the external power (particular DC power supply) for the PAC I/O module signals may temporarily cause the I/O not to operate normally.

Do not control the power for the EH-YR12 relays to have it perform an interlock with the external load, etc. The relay may turn on even when the power has not been supplied by an aluminum electrolytic condenser inside the module to drive the relay.

Also, it is conceivable that a fault in the external power and a failure in the PAC unit lead to abnormal actions. To prevent such actions from causing abnormal operation in the entire system, and from a point of view of creating a fail safe mechanism, construct ladder such as an emergency stop circuit, the protect circuit, and the interlock circuit, for the sections that lead to a mechanical breakdown and accident from abnormal actions outside the PAC.

## 2] Install a lightning arrester

To prevent damage to equipment as a result of being struck by lightning, we recommend setting up a lightning arrester for each PAC power supply ladder.

The HX-CPU detects power failures from a voltage drop of the internal 5 V DC power supply. For this reason, the load in the 5 V DC power of the unit is light, the 5 V DC is retained for a long time and operations may continue for more than 100 ms . Therefore, when using the AC input module, an OFF delay timer for coordinating with the internal 5 V DC is needed because the AC input signal turns off more quickly than the internal.
(3) Wiring to the power module


Figure 11.4 Wiring power diagram
(a) For power supply wiring, use a cable of 2 $\mathrm{mm}^{2}\left(0.0031 \mathrm{in}^{2}\right.$.) or more to prevent a voltage drop from occurring.
(b) The function ground terminal (FE terminal) should use a cable of $2 \mathrm{~mm}^{2}\left(0.0031 \mathrm{in}^{2}\right)$ or more and Class D grounding ( $100 \Omega$ or less). The appropriate distance for ground cable is within 20 m ( 65.62 ft ).
1] Shared with instrumentation panel, relay panel grounding.
2] Avoid joint grounding with equipment that can generate noise such as high-frequency heating furnace, large power panel (several kW or more), thyristor exchanger, electric welders, etc.
3] Be sure to connect a noise filter (NF) to the power cable.
(c) A terminal screw is an M3. Tighten screws within a torque range of 0.49 to $0.78 \mathrm{~N} \cdot \mathrm{~m}$ when wiring.
(d) Use the same power supply system for the basic and expansion units.

Screw for each terminal is M3.
Tighten within a torque range of 0.49 to $0.78 \mathrm{~N} \cdot \mathrm{~m}$. Use a crimp terminal with an outer diameter ot 6 mm ( 0.24 in .) or less when using it.
Use only up to 2 crimp terminals in the same terminal. Avoid claming down more than 3 at the same time.
Use a cable thickness of $0.75 \mathrm{~mm}^{2}\left(0.0011 \mathrm{in}^{2}\right.$.) at the maximum. (Use a $0.5 \mathrm{~mm}^{2}\left(0.00075 \mathrm{in}^{2}\right.$.) cable when adding 2 crimp terminals in the same terminal.)

* Use shielded cable for the relay output module when corresponding to CE marking EMC command is necessary.

1] Align the tip of a terminal block mounting screw to the screw section of the I/O cover insertion fittings.
2] Push in the top of the terminal block until the I/O cover claw section locks with a click.
3] Tighten terminal block mounting screws while holding down the upper part of the terminal block.
4] Pull on the top of the terminal block to make cure that it is locked and cannot come out.

* Always reinstall it following the instructions above if the terminal block is removed.
(5) Input wiring for the input module

| $\begin{gathered} \text { DC input } \\ \text { (EH-XD16, EH-XD8) } \end{gathered}$ | AC input (EH-XA16, EH-XAH16) |
| :---: | :---: |
| Current-output-type 24 V DC proximity switch <br> (Example of EH-XD16) |  |

Figure 11.5 Input wiring
(a) DC input module

1] When all input terminal and the common terminal (C) are loaded with 24 V DC, the input changes to ON, and approximately 6.9 mA current in case of EH-XD8, or approximately 4 mA current in case of EH-XD16, flow to the external input contacts.
2] For sensors such as a proximity switch and photoelectric switch, current-output-type (transistor open collector) can be directly connected. For voltage-output-type sensors, connect them to the input terminal after first going through the transistor.
3] Measures to prevent contact failure in high load current contact.


The current that flows to a contact when external contacts are closed is approximately 6.9 mA for the EH-XD8, and approximately 4 mA for $\mathrm{EH}-\mathrm{XD} 16$. If it is necessary high load current to the contact, add resistance as shown in the diagram at left and supply sufficient current to the contact to prevent a contact failure .

4] Limit the wiring length within 30 m ( 98.43 ft .).
(b) Wiring for 32 / 64-point input module (EH-XD32, EH-XD64) (Based on CE marking)

*1 Wire only the signal line through the shield cable, and provide class D grounding on the shield cable side.
*2 Do not wire the common line or S terminal line through the shield cable. Be sure to wire them independently and separately from the power line, I/O lines or power supply line.
*3 The supply line to the external power supply should be wired as close as possible to the common terminal of the output module.
(c) AC input module

When using the AC input module, if the wiring route gets longer, voltage may be generated on the input terminal though there are no actual signal, because the leak current may flow by the stray capacity between wirings..


There are the following two methods 1] and 2] as its countermeasures. Please limit the voltage caused by the electrostatic combination on the input terminal, to half the maximum OFF voltage level of the input module.

1] Lower impedance of the input module by connecting the dummy resistance with the input terminal in parallel.

2] Connect the external power supply to the external device side.

(6) Output wiring for the output module


Figure 11.6 Output wiring
(a) Wiring for the relay output module

1] Life of relay contact

Life curve of relay contact


Life of the contact is also in squared reverse proportion to the current, so be aware that interrupting rush current or directly driving the condenser load will drastically reduce the life of the relay. When switching is done with high frequency, use a transistor output module.

## 2] Surge killer

For inductive load, connect a surge killer (condenser $0.1 \mu \mathrm{~F},+$ resistance of around $100 \Omega$ ) in parallel to the load. Also, for DC load, connect a flywheel diode.

3] Fuse
A fuse is not built in this module. Install a 6A fuse in the common to prevent the external wiring from burning out.
4] Power supply for driving the relay
If a 24 V DC power supply is connected to drive the relay, take care with respect to the polarity when connecting. There is a risk that the internal circuit will be damaged if the wiring is done incorrectly. Also, do not perform an interlock, etc. to the external load with the power supply for driving the relay.
(b) Wiring for the transistor output module

1] Flywheel diode
For inductive load, connect a flywheel diode in parallel.
2] $S$ and $C$ terminals
Always connect an $S$ terminal and $C$ (common) terminal. If the module is used without connecting these terminals, the internal flywheel diode does not function and there is a risk that the module will malfunction or breakdown.

3] Fuse
A fuse is inserted in the common to prevent the external wiring from burning out, but this does not protect transistor elements. Therefore, note that these elements are destroyed when the external load is short-circuited. Please contact us for repair if the external load short-circuits.

Also, if the fuse blows, there will be no output even if the LED lights up. (The fuse out lamp for the module at this time as well as a CPU module error will not be displayed.)

* If the fuse is melted or blown, do not supply power to the module after changing the fuse without eliminating the source of the problem. Damage escalation, smoke, etc., may otherwise result.
(c) Wiring for the 32 / 64-point output module (EH-YT32 / YTP32, EH-YT64 / YTP64)(Based on CE marking)

*1 Wire only the signal line through the shield cable and provide class D grounding on the shield cable side.
*2 Do not wire the common line or $S$ terminal line through the shield cable. Be sure to wire them independently and separately from the power line, I/O lines or power supply line.
*3 The supply line to the external power supply should be wired as close as possible to the common terminal of the output module.
(7) I/O wiring for the analog module
- Do not apply excess voltage to the analog input module beyond the rated input voltage. Similarly, do not subject the module to current that exceeds the rated input current. Connecting the analog input module to a power supply other than the specified types may cause damage to the product or burning or its internal components.
- For unused channels of the analog input module, short the input terminals before use.
- For unused channels of the analog output module (unused current output channel, 2 to 3 channels), short the outputs before use.
- When wiring the external lines of the analog module, route then through the shield cables while separating them from other power lines or signal lines subject to differential voltage. Shield cables must be grounded on one side. However, whether it is more effective to ground on both side and leave both sides open, depends on the noise environment condition in the actual use. Provide appropriate grounding based on the noise environment.
- Use separate piping for the AC power supply line and the signal / data lines.
- Wire the signal lines and data lines as close as possible to the grounded surface of the cabinet or a metal bar.
(8) Wiring to the module terminal


Figure 11.7 Example of wiring

## Chapter 12 Maintenance and Inspection

In order to use the HX-CPU functions in the most desirable condition and maintain the system to operate normally, it is necessary to conduct daily and periodic inspections.

### 12.1 Daily and Periodic Inspection

(1) Daily inspection

Verify the following items while the system is running.
Table 12.1 Items for daily inspection

| Item | LED display | Inspection <br> method | Normal status | Main cause of error |
| :--- | :---: | :---: | :---: | :--- |
| Power module display | POW | Visual check | ON | Power supply error, etc. |
| CPU module display | RUN | Visual check | ON <br> (Running) | OFF: <br> Microprocessor error, memory error, etc. <br> Refer to chapter 3 for further information. |
|  | ERR | Visual check | OFF | ON: <br> Serious errors such as microprocessor error or <br> memory error, etc. Refer to chapter 3. <br> Blink: <br> $7 x$ error |

*1 If power off time is more than 1 week, realtime clock data could be lost due to super capacitor.

## (2) Periodic inspection

Turn off the power for the external I/O circuit, and check the following items once every six months.
Table 12.2 Items for periodic inspection

| Part | Item | Check criteria | Remarks |
| :---: | :---: | :---: | :---: |
| Programming device to CPU | Check the operation of the programming device | All switch and display lamps work properly. |  |
| Power supply | Check for the voltage fluctuations | EH-PSA, EH-PSR : <br> 85 to 264 V AC <br> EH-PSD : <br> 21.6 to 26.4 V DC | Tester |
| I/O module | Output relay life | Electrical life 200,000 times <br> Mechanical life 10 million times | Refer to the relay contact file curve (chapter 11). |
|  | LED | Turns ON / OFF correctly |  |
|  | External power voltage | Within the specification for each I/O module. | Refer to the specifications of I/O module |
| Battery (Lithium battery) | Check voltage and life | ERR lamp flashes. Within 5 years after replacement. |  |
| Installation and connecting areas | (1) All module are securely fixed. <br> (2) All command fits snugly. <br> (3) All screw is tight. <br> (4) All cables are normal. | No defects | Tighten Check insertion Tighten Visual check |
| Ambient environment | (1) Temperature <br> (2) Humidity <br> (3) Others | 0 to $55^{\circ} \mathrm{C}$ <br> 5 to $95 \% \mathrm{RH}$ (no condensation) <br> No dust, foreign matter, vibration | Visual check |
| Spare part | Check the number of parts, the storage condition | No defects | Visual check |
| Program | Check program contents | Compare the contents of the latest program saved and CPU contents, and make sure they are the same. | Check both master and backup. |

### 12.2 Life of Product

The lifetime of electrolytic capacitors used in the power module is limited. Electrolytic capacitors are used in some of I/O modules to improve noise resistance. If the lifetime is exceeded, performance of product is not guaranteed. Be sure to conduct inspection and maintenance as follows.

## (1) Power module

Many electrolytic capacitors are used in the power module. It is said that lifetime of electrolytic capacitor would be half when ambient temperature increases $10^{\circ} \mathrm{C}$.

If lifetime of electrolytic capacitor is exceeded, output power becomes unstable especially when output current is high due to many point of outputs are activated for example.

Prepare spare units with considering 5 years lifetime in case ambient temperature is $30^{\circ} \mathrm{C}$. For longer lifetime, take account of installation location in terms of temperature and air circulation around power unit and.
(2) CPU module

Some electrolytic capacitors are used in CPU module also. If lifetime of electrolytic capacitor is exceeded, more errors could happen since noise resistance is not enough. Be sure to overhaul CPU module periodically. CPU module has a capacitor to maintain realtime clock data. Backup time with the capacitor is 7 days. The life of the capacitor is approximately 31,000 hours, the ambient temperature influences the life of the capacitor. When the capacitor is life, the backup time becomes short. When the time is not synchronous with a NTP server. In the case of the following, use the battery.

- During the 8 days or more of a power cut, if the retention of realtime clock data is required
- When HX-CPU is used by more than $50{ }^{\circ} \mathrm{C}$ of environment.

Be noted following points about lifetime of battery.

- Refer to the following tables in the lifetime of the battery.
- When using the battery, enable the battery error detection. Refer to the manual section 2.6 Configuration of HX series application manual (Software).
- The life time of the battery means the total time of interruption of power supply for PAC.
- When ERR LED is displayed flashing or the 7 -segment LED is displayed 71, replace the battery within 7 days.
- The durable life of the battery is 5 years. Even if the battery is not a life, replace it every 5 years.

| Battery life (Total power failure time)[Hr] |  |
| :---: | :---: |
| Guaranteed value (MIN) @ $55^{\circ} \mathrm{C}$ | Actual value (MAX) @ $25^{\circ} \mathrm{C}$ |
| 25,000 | 67,000 |

## Chapter 13 Troubleshooting

### 13.1 Error Code

HX-CPU has 7-segment display and error LED to indicate an error code as listed below. If two or more errors are detected at the same time, smaller error code has higher priority to be displayed. If error is detected, read the description following countermeasures depending on error level.


| Error code | Error level | Countermeasure |
| :--- | :--- | :--- |
| 88,11 to 1 F | Serious error | Cycle power. If it does not solve, contact your local supplier. |
| 20 to 34 | Exception | Exception status is cleared only by Reset operation. <br> Execute Reset cold / warm / origin by HX-CODESYS |
| 70 to 79 | Warning | User program execution does not stop by warning. If you need to activate alarm or <br> any action by warning, use CmpHIESErrors_HX library. <br> Press E.CLR button to clear error code. |


| $\begin{aligned} & \text { Err. } \\ & \text { code } \end{aligned}$ | Error name [Detected when] | Description | PAC <br> System* | Application | ERR <br> LED |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 88 | Hardware watchdog error [Always] | The watchdog timer detected a microcomputer overload error because the microcomputer did not operate according to the system program. | Stop | Stop | $-$ |
| 11 | System ROM error (OS) <br> [Power on] | Checksum value of system program (OS) in FLASH does not match the checksum calculated. | Stop | Stop | ${ }^{-1}$ |
| 12 | Read / Write check failed in RAM <br> [Power on] | Read / write check for system RAM has failed. | Stop | Stop | ${ }^{-}$ |
| 17 | System ROM error (File system) <br> [Power on] | Checksum value of system program (File system) in FLASH does not match the checksum calculated. | Stop | Stop | $-\therefore$ |
| 18 | MAC address error <br> [Power on] | MAC address is missing or wrong value. | Stop | Stop | - |
| 1A | Initialize failed in power management device [Power on] | Initialization of power supply has failed. | Stop | Stop | $-C_{1}^{1}$ |
| 1F | Flash access failed [Power on] | Access to a FLASH memory has failed. | Stop | Stop | $-\bigcirc$ |

-'- : ON, -': Blink,

* When a PAC system stops, because a system program of PAC stops, you can't communicate with HX-CODESYS.

| Err. <br> code | Error name [Detected when] | Description | PAC <br> System | Application | $\begin{aligned} & \text { ERR } \\ & \text { LED } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 20 | Illegal instruction [Always] | Illegal instruction was detected in a processor. | Run | Stop | $-\bigcirc^{\prime}$ |
| 21 | Retain identify mismatch [Power on] | Error of checksum value for retain memory data was detected. | Run | Stop |  |
| 23 | Unresolved external references [Always] | A library doesn't exist in CPU. | Run | Stop | $-$ |
| 24 | Software watchdog error [Always] | Actual cycle time has exceeded watchdog time. Set longer watchdog time. | Run | Stop | $-$ |
| 25 | Processorload watchdog [Always] | The processor load exceeded $80 \%$. | Run | Stop | $-\bigcirc^{\prime}$ |
| 27 | Division by zero [Always] | The divisor of division command is 0 in IEC program. | Run | Stop | $-\ominus^{\prime}$ |
| 28 | FPU* Division by zero [Always] | The divisor of division command is 0 in IEC program (FPU). | Run | Stop | $-$ |
| 29 | Access violation <br> [Always] | Access violation was detected in a processor. | Run | Stop | $-\bigcirc_{1}^{\prime}$ |
| 2A | Overflow <br> [Always] | Overflow was detected in a processor. | Run | Stop | $-$ |
| 2B | FPU* Overflow [Always] | FPU overflow was detected in a processor. | Run | Stop | $-\bigcirc_{1}^{\prime}$ |
| 2C | FPU* Underflow [Always] | FPU underflow was detected in a processor. | Run | Stop | $-$ |
| 2E | FPU* Invalid operation [Always] | FPU Invalid operation was detected in a processor. | Run | Stop | $-\bigcirc^{\prime}$ |
| 31 | Load bootproject failed [Power on] | Checksum value of user program in FLASH does not match the checksum calculated. | Run | Stop | $-$ |
| 32 | IoConfig Error [Always] | The setting of modbus specification outside value was detected. | Run | Stop |  |
| 34 | Config file Error <br> [Power on] | Config file Error was detected in a processor. | Run | Stop | $-\bigcirc^{\prime}-$ |

[^10]

ON,


- OFF

| Err. <br> code | Error name <br> [Detected when] | Description | PAC System | Application | $\begin{aligned} & \text { ERR } \\ & \text { LED } \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 70 | I/O Configuration Error [Always] | I/O configuration does not match with actual I/O modules. | Run | Stop | - |
| 71 | Battery error [Always] | Battery voltage is low or battery is disconnected. | Run | Stop | - |
| 72 | Special module failure [Always] | Hardware error is detected in special module or communication module. | Run | Stop | - |
| 74 | Comm. module configuration error [Always] | Configuration error is detected in communication module. | Run | Stop | $-0$ |
| 77 | FLASH writing failure [FLASH writing] | Failure has been detected in writing FLASH memory or the number of writing times (100,000 times) has been exceeded. | Run | Stop | -' |
| 78 | Checksum mismatch in Flash (IP address) [Power on] | Checksum value of IP address in FLASH does not match the checksum calculated. | Run | Stop | $-$ |
| 79 | Realtime clock initialized <br> [Power on] | Realtime clock was initialized, because power cut time exceeds the 7 days of the guarantee time. | Run | Stop | -' |


 O: OFF

* If error cause is removed, error code remains except for error code 71 (battery error).

71 Error and ERR LED blinking automatically disappear if battery is replaced to new one.
It's possible to invalidate I/O configuration Error detection and battery error detection in PAC Parameters setting. For details, please refer to an application manual [Software].

### 13.2 Corrective Actions when Error Occurs

The process flow when error occurs is shown below.


| Error code | Error name | Corrective action |
| :---: | :---: | :---: |
| 88 | Hardware watchdog error | Recheck the fixation of the HX-CPU to the basic base unit, and restart the power supply. <br> If the same error occurs, it is a hardware error in the HX-CPU. Replace the CPU module with a spare. <br> Make sure that there are no machines which generates excessive noise, etc. near HX-CPU system. |
| 11 | System ROM error (OS) |  |
| 12 | Read / Write check failed in RAM |  |
| 17 | System ROM error (File system) |  |
| 18 | MAC address error |  |
| 1A | Initialize failed in power management device |  |
| 1F | Flash access failed |  |
| 20 | Illegal instruction | Check the user program. |
| 21 | Retain identify mismatch | Login to HX-CPU and reset cold. |
| 23 | Unresolved external references | Check the library. <br> When a making library is being used, check that "External implementation" in property of Application becomes disable. |
| 24 | Software watchdog error | Change the software watchdog time of the user program. |
| 25 | Processorload watchdog | Change to the program that Processorload may be done small. For example make the task cycle long. |
| 27 | Division by zero | Change to the program that does not excute the division by zero. |
| 28 | FPU Division by zero | Check the user program. |
| 29 | Access violation |  |
| 2A | Overflow |  |
| 2B | FPU Overflow |  |
| 2C | FPU Underflow |  |
| 2 E | FPU Invalid operation |  |
| 31 | Load bootproject failed | The contents of the user program are destroyed. Transfer the program again after initialization. |
| 32 | IoConfig Error | Set the correct settings. |
| 34 | Config file Error | Transfer the program again and reset an error. When using supporting function for security protection, reconfiguration supporting function for security protection settings. |


| Error <br> code | Error name | Corrective action |
| :---: | :--- | :--- |
| 70 | I/O Configuration Error | Check the I/O assignment once more. <br> Recheck the fixation of each I/O module and I/O controller, and the connection of the expansion cable. |
| 71 | Battery error | Replace the battery with a new one. <br> Check the connection of the battery connector. <br> When operating in the battery-less, set to disable the "Battery error detection". |
| 72 | Special module failure | Refer to the error code of the special module, perform the error recovery processing. | | 74 | Comm. module configuration <br> error | Refer to the error code of the comm module, perform the error recovery processing. |
| :---: | :--- | :--- |
| 77 | FLASH writing failure | After the initialization, download the user program again. <br> If the same error occurs, it is a hardware error in the CPU module. Replace the CPU module with a <br> spare. |
| 78 | Checksum mismatch in Flash <br> (IP address) | Set the IP address (ETH1, 2, 3) again. |
| 79 | Realtime clock initialized | Set the time in the Realtime clock. Refer to "SetDateAndTime" an application manual <br> [Command references ]. |

## Reseting the factory default settings

When that does not solve the problem even after you restart and when the online connection to the HX-CODESYS has become impossible, it's possible to reset HX-CPU to factory default settings.

## < How to reset the factory default settings >

(1) Remove power from the PAC.
(2) Toggle the RUN / STOP switch to STOP position.
(3) Turn on all 2 bits switches (SW1).
(4) Supply power to the PAC with E.CLR button pressed until "SP" is displayed in the 7-segment LED.

(5) Toggle the RUN / STOP switch to RUN position.
(6) It takes a few seconds to delete boot project. Then "Fn" is displayed in the 7-segment LED.

(7) Turn off all 2 bits switches (SW1).

When turning on the power next time, it starts with the factory default settings.


### 13.3 Error Libraries

As for warnings (error code 70 to 78), special libraries called "CmpHIESErrors_HX" are available as below. Use them in your application program if necessary. If it is not registered in your library repository, install CmpHIESErrors_HX.compiled-library by choosing [Tools]-[Install library...].

| Error code | Libraries (CmpHIESErrors_HX) | Input | Output |
| :---: | :---: | :---: | :---: |
| all | HIESGetLastEEror <br> WORD HIESGetLastError | - | Last detected error code (WORD) |
| All |  | Execution bit to clear error code (BOOL) | Result (BOOL) |
| 70 |  IOConfigError <br> BOOL xIoConfigError  <br> WORD wUnit  <br> WORD wSlot $-$ <br> (FB) | - | 70 Error bit (BOOL) <br> Unit number (WORD) <br> Slot number (WORD) |
| 71 | BatteryError <br> BOO BatteryError | - | 71 Error bit (BOOL) |
| 72 | SpecialModuleError <br> BOOL <br> xSpecial ModuleError <br> WOD wUnit <br> WORD wSlot <br> (FB) | - | 72 Error bit (BOOL) <br> Unit number (WORD) <br> Slot number (WORD) |
| 74 | ComModule Error <br> BOOL xComModuleError <br> WORD wUniter <br> WORD wSlot$-$ <br> (FB) | - | 74 Error bit (BOOL) <br> Unit number (WORD) <br> Slot number (WORD) |
| 77 | FlashwritingError <br> BOO    | - | 77 Error bit (BOOL) |
| 78 | ComParamSumError <br> BOOL ComParamSumError | - | 78 Error bit (BOOL) |


[^0]:    * The last alphabet of the manual No. stands for version starting from blank, A, B, C...

[^1]:    * The basic base 4] and the expansion base 5] are the same product.

[^2]:    *1 CPUs, power modules and I/O controllers (EH-IOCH2, EH-IOCP2, EH-IOCA) are mounted on reserved positions only.
    *2 Short circuit protection version is from May 2001 production. (MFG. No. 01Exx)
    *3 The suggested torque for the terminal connections is 9 in-lbs as below.
    *4 Supporting module version is from April 2005 production. (MFG. No. 05Dxx)
    *5 Please use the maximum output current of EH-PSR on the following conditions.
    Less than 45 degree ambient temperature : 5.6 A
    From 45 to 55 degree
    : 5.0 A

[^3]:    * Please refer to "Software manual of HX series" for the PC operating environment necessary to use it.

[^4]:    * User program download function will be supported in near future.

[^5]:    *1 Full function model support only.

[^6]:    * In this module, be sure to perform the above setup before use. Further, be sure to turn off the power in setting up. Otherwise, the setups are invalid.

[^7]:    * Always use Bit 3 with OFF

[^8]:    * Pin No. defined in EH-CUE does not accord with pin No. defined by the connector maker.

[^9]:    *1 Each I/O size of EH-IOCP2 is expanded from 128 bytes to 244 bytes by software version 0014 or newer.
    *2 The output hold function of EH-IOCP2 is supported by software version 0014 or newer.

[^10]:    * FPU means a Floating Point Unit of main processor in the HX-CPU.

